

Categorical combinatorics for non deterministic strategies on simple games

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Abstract. The purpose of this paper is to define in a clean and conceptual way a non-deterministic and sheaf-theoretic variant of the category of simple games and deterministic strategies. One thus starts by associating to every simple game a presheaf category of non-deterministic strategies. The 2-category of simple games and non-deterministic strategies is then obtained by a construction inspired by the recent work by Melliès and Zeilberger on type refinement systems. We show that the resulting 2-category is symmetric monoidal closed and cartesian. We also define a 2-comonad which adapts the Curién-Lamarche exponential modality of linear logic to the 2-dimensional and non deterministic framework. We conclude by discussing in what sense the 2-category of simple games defines a model of non deterministic intuitionistic linear logic.

1 Introduction

A new generation of 2-categorical and sheaf-theoretic game semantics is currently emerging in the field of programming language semantics. The games and strategies which determine them are more sophisticated mathematically, and also more difficult to define rigorously, than they were in the deterministic case. For that reason, it is timely to examine more closely the 2-categorical and sheaf-theoretic frameworks available to us in order to formulate these games and strategies in a suitably clean and conceptual way. In this investigation, one benefits from the efforts made in the past twenty-five years to give a clearer mathematical status to the previous generation of game semantics, which was (to a large extent) based on the notion of arena game. We recognize three main lines of work here:

1. the logical approach advocated by Girard, and formulated in ludics [3], polarized linear logic [7] or tensorial logic [12] with its connection to continuations and string diagrams,
2. the combinatorial approach advocated by Hyland, inspired by algebraic topology, and based on the combinatorial description of the structure of pointers in arena games [4],
3. the concurrent and asynchronous approach advocated by Melliès, based on the description of arena games as asynchronous games, and of strategies as causal concurrent structures playing on them, either in an alternated [11, 9, 10] or in a non-alternated way [18].

Interestingly, all the sheaf-theoretic frameworks designed for game semantics today are offsprings of the third approach based on asynchronous games: on the one hand, the notion of concurrent strategy in [19] is a sheaf-theoretic transcription of the notion of receptive ingenuous strategy formulated in [18] ; on the other hand, the sheaf-theoretic notion of non-deterministic innocent strategy in [13, 17] relies on the diagrammatic and local definition of innocence in alternated asynchronous games [11]. For that reason, our purpose in this paper is to investigate the connection with the second approach, different in spirit and design, and to define a 2-category of simple games and non-deterministic strategies in the sheaf-theoretic style of Harmer, Hyland and Melliès [4]. As we will see, our work also integrates a number of elements coming from the first approach, and more specifically, the discovery by Melliès that strategies are presented by generators and relations, and for that reason, are prone to factorisation theorems [14, 15]. Since we are interested in sheaf-theoretic models of computations, we should not forget to mention the pioneering work by Hirschowitz and Pous on models of process calculi [5], and its recent connection to game semantics [2].

In the present paper, we start from the category \mathcal{G} of simple games and deterministic strategies between them, and we explain how to turn \mathcal{G} into a bicategory \mathcal{S} of simple games and *non-deterministic* strategies. As we will see, the construction of \mathcal{S} relies on the discovery of a number of elementary but fundamental fibrational properties of the original category \mathcal{G} . Since our work is built on [4], let us recall that a simple game A is defined there as a contravariant presheaf $A : \omega^{op} \rightarrow \mathbf{Set}$ over the order category $\omega = 0 \rightarrow 1 \rightarrow 2 \rightarrow \dots$ associated to the infinite countable ordinal ω . A simple game A is thus a family of sets A_n together with a function $\pi_n : A_{n+1} \rightarrow A_n$ for all $n \in \mathbb{N}$, depicted as:

$$A_0 \xleftarrow{\pi_0} A_1 \xleftarrow{\pi_1} A_2 \xleftarrow{\quad} \dots \xleftarrow{\quad} A_n \xleftarrow{\pi_n} A_{n+1} \xleftarrow{\quad} \dots$$

One requires moreover that A_0 is the singleton set. The intuition is that A is a rooted tree ; that A_n contains its plays (or branches) of length n ; and that π_n is the prefix function which transports every play of length $n + 1$ to its prefix of length n . In particular, every simple game A contains only one play of length 0, which should be thought as the empty play. Every simple game A should be moreover understood as alternated: here, the intuition is that every play of odd length $2n + 1$ ends with an Opponent move, and that every play of even length $2n$ ends with a Player move.

Terminology: an element $a \in A_n$ is called a position of degree n in the game A . The position $a \in A_n$ is called a *P*-position when its degree n is even, and a *O*-position when its degree n is odd. Given a position $a \in A_{n+1}$, we write $\pi(a)$ for the position $\pi_n(a)$; similarly, given a position $a \in A_{n+2}$, we write $\pi^2(a)$ for the position $\pi_n \circ \pi_{n+1}(a)$. A simple game A is called *O*-branching when the function $\pi : A_{2n+2} \rightarrow A_{2n+1}$ is injective, for all $n \in \mathbb{N}$. This means that every Opponent position $a \in A_{2n+1}$ can be extended in at most one way into a Player position $b \in A_{2n+2}$, for all $n \in \mathbb{N}$.

We start the paper by formulating a sheaf-theoretic notion of non-deterministic P -strategy on a simple game A . Recall that a deterministic P -strategy σ of a simple game A is defined in [4] as a family of subsets $\sigma_{2n} \subseteq A_{2n}$ of P -positions, satisfying the following properties, for all $n \in \mathbb{N}$:

- (i) **Unique empty play** — σ_0 is equal to the singleton set A_0 ,
- (ii) **Closure under even prefixes** — if $a \in \sigma_{2n+2}$ then $\pi^2(a) \in \sigma_{2n}$,
- (iii) **Determinacy** — if $a, b \in \sigma_{2n}$ with $\pi(a) = \pi(b)$, then $a = b$.

In order to generalize this definition to non-deterministic P -strategies, we find convenient to consider the full subcategory ω_P of ω consisting of the strictly positive even numbers, of the form $2n$ for $n > 0$; and the inclusion functor $\iota_P : \omega_P \rightarrow \omega$. Define the presheaf $A_P = A \circ \iota_P$ as the simple game A obtained by restricting the presheaf $A : \omega^{op} \rightarrow \mathbf{Set}$ to the subcategory ω_P :

$$A_P = \omega_P^{op} \xrightarrow{\iota_P} \omega^{op} \xrightarrow{A} \mathbf{Set}$$

The collection A_P thus consists of all the Player positions in A , except for the initial one $* \in A(0)$. This leads us to the following definition of (non-deterministic) P -strategy on a simple game A :

Definition 1. *A P -strategy σ on a simple game A is a presheaf $S : \omega_P^{op} \rightarrow \mathbf{Set}$ over the category ω_P together with a morphism of presheaves $\sigma : S \rightarrow A_P$. We write $\sigma : A$ in that case. The presheaf S is called the support of the strategy σ and the elements of S_{2n} are called the runs of degree $2n$ of the strategy, for $n \geq 0$.*

In other words, a P -strategy σ on A is a family of sets S_{2n} indexed by strictly positive numbers $n > 0$, related between them by functions $(\pi_P)_{2n} : S_{2n+2} \rightarrow S_{2n}$ pictured as:

$$S_2 \xleftarrow{\pi_P} S_4 \longleftarrow \cdots \longleftarrow S_{2n} \xleftarrow{\pi_P} S_{2n+2} \longleftarrow \cdots$$

together with a family of functions $\sigma_{2n} : S_{2n} \rightarrow A_{2n}$ making the diagram below commute, for all $n > 0$:

$$\begin{array}{ccccc} S_{2n} & \xleftarrow{\pi_P} & & & S_{2n+2} \\ \sigma_{2n} \downarrow & & & & \downarrow \sigma_{2n+2} \\ A_{2n} & \xleftarrow{\pi} & A_{2n+1} & \xleftarrow{\pi} & A_{2n+2} \end{array}$$

To every simple game A , we associate the category $\mathcal{P}(A)$ of P -strategies over A , defined as the slice category

$$\mathcal{P}(A) = [\omega_P^{op}, \mathbf{Set}] / A_P \tag{1}$$

whose objects are thus the strategies over A , and whose morphisms $\theta : \sigma \rightarrow \tau$ between two strategies $\sigma : S \rightarrow A$ and $\tau : T \rightarrow A$ are the morphisms $\theta : S \rightarrow T$ of presheaves satisfying the expected equation : $\sigma = \tau \circ \theta$. We will call those

simulations. One main contribution of the paper is the observation that the family of categories $\mathcal{P}(A)$ can be organised into a pseudofunctor

$$\mathcal{P} : \mathcal{G} \longrightarrow \mathbf{Cat}$$

from the category \mathcal{G} of simple games and deterministic strategies. The pseudofunctor \mathcal{P} is moreover monoidal, in the sense that there exists a family of functors

$$m_{A,B} : \mathcal{P}(A) \times \mathcal{P}(B) \longrightarrow \mathcal{P}(A \otimes B)$$

indexed by simple games A, B . As a symmetric monoidal closed category, the category \mathcal{G} is enriched over itself, with the simple game $\mathcal{G}(A, B) = A \multimap B$ constructed from the simple games A and B . Here comes the nice point of the construction: the bicategory \mathcal{S} is simply defined as the bicategory with simple games A, B as objects, and with

$$\mathcal{S}(A, B) = \mathcal{P}(A \multimap B)$$

as category of morphisms between two simple games A and B . In other words, a morphism $\sigma : A \rightarrow B$ in \mathcal{S} is a P -strategy $\sigma : A \multimap B$, and a 2-cell $\theta : \sigma \Rightarrow \tau : A \rightarrow B$ is a morphism $\theta : \sigma \rightarrow \tau$ in the category $\mathcal{P}(A \multimap B)$. At this point, the fact that \mathcal{S} defines a bicategory is easily derived from the lax monoidal structure of the pseudofunctor \mathcal{P} . Recall that, as a symmetric monoidal closed category, the category \mathcal{G} is enriched over itself. From a conceptual point of view, the construction of the bicategory \mathcal{S} thus amounts to a change of enrichment category along the lax monoidal pseudofunctor $\mathcal{P} : \mathcal{G} \rightarrow \mathbf{Cat}$, transforming the \mathcal{G} -enriched category \mathcal{G} into the (weak) \mathbf{Cat} -enriched category \mathcal{S} .

Besides the construction of \mathcal{S} , a great care will be devoted to the analysis of the Curien-Lamarche exponential comonad $!$ on the category \mathcal{G} and to the recipe to turn it into an exponential 2-comonad on the bicategory \mathcal{S} . The construction relies on the existence of a family of functors

$$p_A : \mathcal{P}(A) \longrightarrow \mathcal{P}(!A)$$

called “promotion” functors, and natural in the simple game A in the category \mathcal{G} . In particular, the functorial part of the exponential 2-comonad $! : \mathcal{S} \rightarrow \mathcal{S}$ is defined as the composite:

$$\mathcal{P}(A \multimap B) \xrightarrow{p_A} \mathcal{P}(!A \multimap B) \xrightarrow{\mathcal{P}(n_{A,B})} \mathcal{P}(!A \multimap !B)$$

where $n_{A,B} : !A \multimap B \rightarrow !A \multimap !B$ is the canonical morphism in \mathcal{G} which provides the structure of a lax monoidal functor to the original comonad $! : \mathcal{G} \rightarrow \mathcal{G}$.

2 Non-deterministic P -strategies as P -cartesian transductions

As explained in the introduction, a P -strategy $\sigma \in \mathcal{P}(A)$ over a simple game A is defined as an object of the slice category (1) in the category $[\omega_P^{op}, \mathbf{Set}]$ of

contravariant presheaves over ω_P . We will use the fact that the slice category is equivalent to the category of contravariant presheaves

$$\mathcal{P}(A) = [\omega_P^{op}, \mathbf{Set}] / A_P \cong [\mathbf{tree}(A_P)^{op}, \mathbf{Set}]$$

over the Grothendieck category $\mathbf{tree}(A_P)$ generated by the presheaf $A_P \in [\omega_P^{op}, \mathbf{Set}]$. The category $\mathbf{tree}(A_P)$ has the P -positions of the simple game A as objects, and a morphism $a \rightarrow a'$ between $a \in A_{2p}$ and $a' \in A_{2q}$ precisely when $p \leq q$ and $\pi^{2q-2p}(a') = a$. In other words, it is the order category associated to the tree of P -positions of the simple game A .

We find convenient for later purposes to reformulate non-deterministic P -strategies in the following way. This paves the way to a comprehension theorem for the pseudofunctor \mathcal{P} , which will be established in the next section. A transduction $\theta : A \rightarrow B$ between two simple games $A, B : \omega^{op} \rightarrow \mathbf{Set}$ is defined as a natural transformation between the presheaves A and B , given by a family of functions $\theta_n : A_n \rightarrow B_n$ making the square \square_n diagram below commute, for all $n \in \mathbb{N}$:

$$\begin{array}{ccc} A_n & \xleftarrow{\pi_n} & A_{n+1} \\ \theta_n \downarrow & \square_n & \downarrow \theta_{n+1} \\ B_n & \xleftarrow{\pi_n} & B_{n+1} \end{array}$$

A transduction $\theta : A \rightarrow B$ is called P -cartesian when \square_{2n} is a pullback square for all $n \in \mathbb{N}$; and O -cartesian when \square_{2n+1} is a pullback square for all $n \in \mathbb{N}$. We write \mathcal{T} for the category of simple games and transductions between them, and \mathcal{T}_P (resp. \mathcal{T}_O) for the subcategory of P -cartesian (resp. O -cartesian) transductions. Note that the restriction functor

$$(-)_P : [\omega^{op}, \mathbf{Set}] \longrightarrow [\omega_P^{op}, \mathbf{Set}]$$

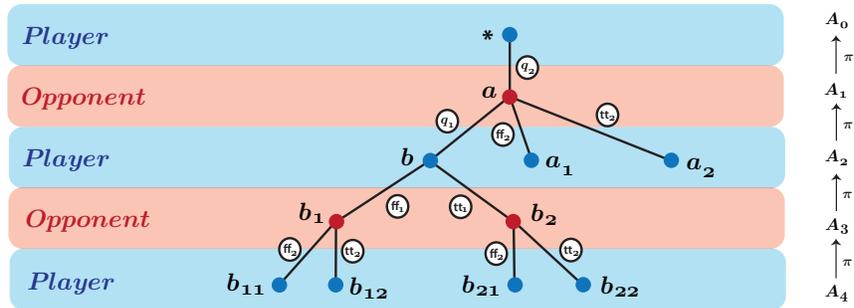
is a fibration, and that a transduction $\theta : A \rightarrow B$ between simple games is P -cartesian precisely when it defines a cartesian morphism with respect to the fibration $(-)_P$. For that reason, a P -cartesian transduction $\theta : A \rightarrow B$ is entirely characterized by the family of functions $\theta_{2n} : A_{2n} \rightarrow B_{2n}$ on the P -positions of the simple games A and B , for $n \in \mathbb{N}$. From this follows easily that

Proposition 1. *A P -strategy σ on a simple game A is the same thing as a simple game S together with a P -cartesian transduction $S \rightarrow A$. The simple game S is uniquely determined by σ up to isomorphism. It is called the support (or run-tree) of σ , and noted $\{A | \sigma\}$, while the P -cartesian transduction is noted $\text{supp}_\sigma : \{A | \sigma\} \rightarrow A$.*

Note that the definition applies the general principle formulated in [18] that a strategy σ of a game A is a specific kind of map (here a P -cartesian transduction) $S \rightarrow A$ from a given game $S = \{A | \sigma\}$ to the game A of interest. One benefit of this principle is that it unifies the two concepts of game and of strategy, by regarding a strategy σ of a game A as a game S “embedded” in a appropriate

way by $S \rightarrow A$ inside the simple game A . This insight coming from [18] underlies for instance the construction in [19] of a category of non-deterministic strategies between asynchronous games.

Typically, consider the simple game $A = \mathbb{B}_1 \multimap \mathbb{B}_2$ where \mathbb{B} is the simple boolean game with a unique initial Opponent move q and two Player moves tt for true and ff for false ; and where the indices 1, 2 are here to indicate the component of the boolean game \mathbb{B} . The simple game A may be represented as the decision tree below:



where the sets of positions are defined as:

$$A_1 = \{a\} \quad A_2 = \{b, a_1, a_2\} \quad A_3 = \{b_1, b_2\} \quad A_4 = \{b_{11}, b_{12}, b_{21}, b_{22}\}$$

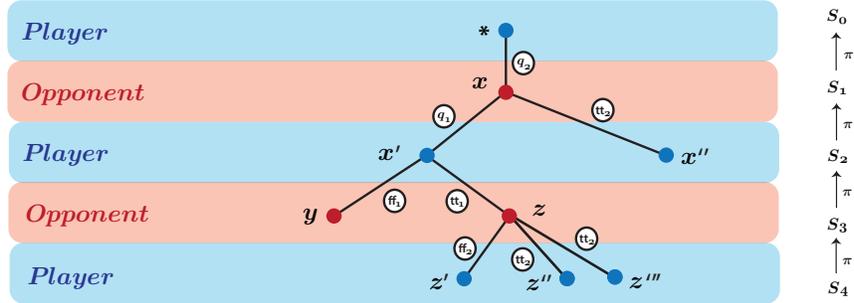
and where the branches are induced by the prefix functions $\pi_n : A_{n+1} \rightarrow A_n$ depicted on the picture above. For the reader's convenience, we label every edge of A by the name of the move which would be used in the more familiar definition of simple games, where plays are defined as sequences of moves [1, 6]. Note that every position $a \in A_n$ of degree n is determined by its occurrence, defined as the sequence of n moves from the root $*$ to the position a in the tree A . Typically, the P -position $b \in A_2$ has occurrence $q_2 \cdot q_1$ and the P -position $b_{21} \in A_4$ has occurrence $q_2 \cdot q_1 \cdot \text{tt}_1 \cdot \text{ff}_2$.

By way of illustration, we define the P -strategy $\sigma \in \mathcal{P}(A)$ as the presheaf below

$$\begin{array}{ccccccc} * \mapsto \{*\} & a_1 \mapsto \emptyset & a_2 \mapsto \{x''\} & & & & \\ b \mapsto \{x'\} & b_{11} \mapsto \emptyset & b_{12} \mapsto \emptyset & b_{21} \mapsto \{z'\} & b_{22} \mapsto \{z'', z'''\} & & \end{array}$$

on the Grothendieck category $\mathbf{tree}(A_P)$ associated to the presheaf A_P of P -positions in A . As explained in Prop. 1, the P -strategy σ may be equivalently

defined as the simple game $S = \{A \mid \sigma\}$ below



together with the P -cartesian transduction $\text{supp}_\sigma : \{A \mid \sigma\} \rightarrow A$ described as:

$$x \mapsto a \quad x' \mapsto b \quad x'' \mapsto a_2 \quad y \mapsto b_1 \quad z' \mapsto b_{21} \quad z'' \mapsto b_{22} \quad z''' \mapsto b_{22}$$

It is worth mentioning that the transduction supp_σ may be recovered from the moves labelled on the run-tree $S = \{A \mid \sigma\}$. This pictorial description provides a convenient way to describe how the non-deterministic P -strategy σ plays on A . Typically, when questioned by the initial move q_2 of the game, the non-deterministic P -strategy σ answers tt_2 with the run $x'' \in S_2$ or asks the value of the input boolean by playing the move q_1 ; when the Opponent answers with the move tt_1 , the P -strategy reacts by playing the value ff_2 with the run $z' \in S_4$ or by playing the value ff_2 with the runs $z'', z''' \in S_4$. Note in particular that the P -strategy σ is allowed to play two different runs $z'', z''' \in S_4$ of the same play $b_{22} \in A_4$.

3 P -cartesian transductions as deterministic strategies

In the previous section, we have seen how to regard every non-deterministic P -strategy $\sigma \in \mathcal{P}(B)$ as a P -cartesian transduction $\text{supp}_\sigma : \{B \mid \sigma\} \rightarrow B$ into the simple game B . Our purpose here is to show that every P -cartesian transduction $\theta : A \rightarrow B$ can be seen as a particular kind of deterministic strategy of the simple game $A \multimap B$.

Definition 2 (Total strategies). *A deterministic strategy σ of a simple game A is total when for every O -position s such that the P -position $\pi(s)$ is an element of σ , there exists a P -position t in the strategy σ such that $\pi(t) = s$.*

Definition 3 (Back-and-forth strategies). *Given two simple games A and B , a back-and-forth strategy f of the simple game $A \multimap B$ is a deterministic and total strategy whose positions are all of the form (c, a, b) where $c : n \rightarrow n$ is a copycat schedule.*

Back-and-forth strategies compose, and thus define a subcategory of \mathcal{G} :

Definition 4 (The category \mathcal{BF}). *The category \mathcal{BF} of back-and-forth strategies is the subcategory of \mathcal{G} whose objects are the simple games and whose morphisms $f : A \rightarrow B$ are the back-and-forth strategies of $A \multimap B$.*

As a matter of fact, we will be particularly interested here in the subcategory \mathcal{BF}^+ of *functional* back-and-forth strategies in the category \mathcal{BF} .

Definition 5 (Functional strategies). *A functional strategy f of the simple game $A \multimap B$ is a back-and-forth strategy such that for every position $a \in A_n$ of degree n in the simple game A , there exists a unique position $b \in B_n$ of same degree in B such that $(c, a, b) \in f$, where $c : n \rightarrow n$ is the copycat schedule.*

The following basic observation justifies our interest in the notion of functional strategy:

Proposition 2. *For all simple games A, B , there is a one-to-one correspondence between the P -cartesian transductions $A \rightarrow B$ and the functional strategies in $A \multimap B$.*

Proof. See Appendix E.

For that reason, we will identify P -cartesian transductions and functional strategies from now on. Put together with Prop. 1, this leads us to the following correspondence, which holds for every simple game A :

Proposition 3. *The category $\mathcal{P}(A)$ is equivalent to the slice category \mathcal{BF}^+ / A .*

The result may be understood as a preliminary form of comprehension: it states that every non-deterministic P -strategy $\sigma \in \mathcal{P}(A)$ may be equivalently seen as a functional P -strategy

$$\text{supp}_\sigma : \{A | \sigma\} \longrightarrow A \quad (2)$$

in the category \mathcal{G} of simple games and deterministic strategies, obtained by composing the equivalences stated in Prop. 1 and Prop. 3. Note that the simple game $\{A | \sigma\}$ coincides with the run-tree S of the non-deterministic strategy σ formulated in Prop. 1 and that the functional strategy supp_σ coincides with the P -cartesian transduction which “projects” the support S on the simple game A . The property (Prop. 3) is important from a methodological point of view, because it enables us to use the rich toolbox developed for simple games and deterministic strategies, in order to handle non-deterministic strategies *inside* the category \mathcal{G} .

4 The pseudofunctor \mathcal{P}

Suppose given a P -strategy $\sigma \in \mathcal{P}(A)$ over the simple game A and a morphism $f : A \rightarrow B$ in the category \mathcal{G} .

Definition 6. The P -strategy $\mathcal{P}(f)(\sigma) \in \mathcal{P}(B)$ over the simple game B is defined as the contravariant presheaf over $\mathbf{tree}(B_P)$ which transports every P -position b of the simple game B to the disjoint union defined below:

$$\mathcal{P}(f)(\sigma) : b \mapsto \coprod_{(e,a,b) \in f} \sigma(a). \quad (3)$$

The fact that (3) defines a presheaf over $\mathcal{P}(B)$ and that \mathcal{P} is a pseudofunctor (see Def 24) is established in the appendix F.

This construction equips the family of presheaf categories $\mathcal{P}(A)$ with the structure of a pseudofunctor $\mathcal{P} : \mathcal{G} \rightarrow \mathbf{Cat}$. Moreover, the pseudo-functor \mathcal{P} has comprehension in the sense of Lawvere [8]. For every simple game B , the *comprehension functor* is defined as the composite

$$\{B | -\} : \mathcal{P}(B) \longrightarrow \mathcal{BF}^+/B \longrightarrow \mathcal{G}/B$$

which transports every non-deterministic P -strategy to the morphism (2) seen as an object of \mathcal{G}/B . One establishes that

Theorem 1 (Comprehension). *For every simple game B , the comprehension functor*

$$\{B | -\} : \mathcal{P}(B) \longrightarrow \mathcal{G}/B$$

has a left adjoint functor

$$\mathbf{image} : \mathcal{G}/B \longrightarrow \mathcal{P}(B).$$

Given a deterministic strategy $f : A \rightarrow B$, the contravariant presheaf $\mathbf{image}(f)$ over the category $\mathbf{tree}(B_P)$ transports every P -position b of the game B to the set below:

$$\mathbf{image}(f) : b \mapsto \left\{ (e, a, b) \mid (e, a, b) \in f \right\}$$

Note that the presheaf $\mathbf{image}(f)$ may be also described by the formula

$$\mathbf{image}(f) = \mathcal{P}(f)(*_A) \in \mathcal{P}(B)$$

where $*_A$ is the terminal object in the category $\mathcal{P}(A)$ of P -strategies over A . Note that the run-tree $\{A | *_A\}$ of the P -strategy $*_A \in \mathcal{P}(A)$ is the simple game A itself, with \mathbf{supp}_{*_A} the identity $i_A : A \rightarrow A$. In other words, the P -strategy $*_A$ has exactly one run over each position of the simple game A .

Also note that we will occasionally note positions of $\mathbf{image}(f)$ $b_{(e,a)}$ when there is need to emphasize the fact that $\mathbf{image}(f)$ is a contravariant presheaf over $\mathbf{tree}(B_P)$.

5 The slender-functional factorisation theorem

In order to establish the comprehension theorem, we prove a factorization theorem in the original category \mathcal{G} , which involves slender and functional strategies.

Definition 7. *A deterministic strategy f in a simple game $A \multimap B$ is slender when for every P -position b in the simple game B , there exists exactly one P -position a of the simple game A and exactly one schedule e such that $(e, a, b) \in f$.*

By extension, we say that a morphism $f : A \rightarrow B$ in the category \mathcal{G} is slender when the deterministic strategy f is slender in $A \multimap B$. Note that every isomorphism $f : A \rightarrow B$ in the category \mathcal{G} is both slender and functional.

Proposition 4. *Suppose that A and B are two simple games and that f is a deterministic strategy of $A \multimap B$. Then, there exists a slender strategy $g : A \rightarrow C$ and a functional strategy $h : C \rightarrow B$ such that $f = h \circ g$.*

The simple game C is defined as $\{B \mid \text{image}(f)\}$ while the slender strategy $g : A \rightarrow C$ is defined as

$$g = \left\{ (e, a, (e, a, b)) \mid (e, a, b) \in f \right\}$$

and $h : C \rightarrow B$ is the functional strategy $\text{supp}_{\text{image}(f)}$ associated in Prop. 3 to the P -strategy $\text{image}(f) \in \mathcal{P}(B)$.

Proposition 5. *Suppose that $s : U \rightarrow V$ and $f : A \rightarrow B$ are two morphisms of the category \mathcal{G} . Suppose moreover that s is slender and that f is functional. Then, $s : X \rightarrow Y$ is orthogonal to $f : A \rightarrow B$ in the sense that for all morphisms $u : X \rightarrow A$ and $v : Y \rightarrow B$ making the diagram (a) commute, there exists a unique morphism $h : Y \rightarrow A$ making the diagram (b) commute in the category \mathcal{G} :*

$$(a) \begin{array}{ccc} X & \xrightarrow{u} & A \\ s \downarrow & & \downarrow f \\ Y & \xrightarrow{v} & B \end{array} \qquad (b) \begin{array}{ccc} X & \xrightarrow{u} & A \\ s \downarrow & \nearrow h & \downarrow f \\ Y & \xrightarrow{v} & B \end{array}$$

The deterministic strategy $h : Y \rightarrow A$ is defined as

$$h = \left\{ (e, y, a) \mid \begin{array}{l} \exists x \in X, b \in B, e', e'' \in \mathcal{T}, \\ (e, y, b) \in v \wedge (c, a, b) \in f \wedge (e', x, y) \in s \wedge (e'', x, a) \in u \end{array} \right\} \\ \uplus \left\{ (e, y, a) \mid \begin{array}{l} \exists x \in X, b \in B, e', e'' \in \mathcal{T}, \\ (e, y, b) \in v \wedge (c, a, b) \in f \wedge (e', x, \pi y) \in s \wedge (e'', x, \pi a) \in u \end{array} \right\}$$

Note that the position b is uniquely determined by the position a because f is functional, and that the pair (e', x) is uniquely determined by the position y because s is slender. Moreover, by determinism of $u = h \circ s$, the schedule e'' is entirely determined by the schedules e and e' .

Theorem 2 (Factorization theorem). *The classes \mathcal{S} of slender morphisms and \mathcal{F} of functional morphisms define a factorization system $(\mathcal{S}, \mathcal{F})$ in the category \mathcal{G} .*

It is a folklore result that, in that situation, the comprehension theorem (Thm. 1) follows from the factorization theorem. The reason is that the category $\mathcal{P}(B)$ is equivalent (by Prop. 3) to the full subcategory \mathcal{BF}^+/B of functional strategies in the slice category \mathcal{G}/B . Seen from that point of view, the comprehension functor $\{B | -\}$ coincides with the embedding of \mathcal{BF}^+/B into \mathcal{G}/B . It is worth noting that for every P -strategy $\sigma \in \mathcal{P}(A)$, one has an isomorphism

$$\sigma \cong \text{image}(\text{supp}_\sigma)$$

in the category $\mathcal{P}(A)$, and that one has an isomorphism

$$\mathcal{P}(f)(\sigma) \cong \text{image}(f \circ \text{supp}_\sigma) \quad (4)$$

in the category $\mathcal{P}(B)$, for every morphism $f : A \rightarrow B$ in the category \mathcal{G} . This provides an alternative way to define the pseudofunctor \mathcal{P} .

6 The bicategory \mathcal{S} of simple games and non-deterministic strategies

In this section, we explain how to construct a bicategory \mathcal{S} of simple games and non-deterministic strategies, starting from the category \mathcal{G} . The first step is to equip the pseudofunctor \mathcal{P} with a lax monoidal structure (See Def 25), based on the definition of tensor product in the category \mathcal{G} formulated in [4], see Appendix B for details. We start by observing that

Proposition 6. *Suppose given two morphisms $f : A \rightarrow B$ and $g : C \rightarrow D$ in the category \mathcal{G} of simple games and deterministic strategies. The morphism*

$$f \otimes g : A \otimes C \longrightarrow B \otimes D$$

is slender when f and g are slender, and functional when f and g are functional.

Proof. See Appendix G.

Note that the isomorphism $\text{image}(f \otimes g) \cong \text{image}(f) \otimes \text{image}(g)$ follows immediately from this statement and from the factorization theorem (Thm. 2), for every pair of morphisms $f : A \rightarrow B$ and $g : C \rightarrow D$ in the category \mathcal{G} . The tensor product $\sigma \otimes \tau$ of two P -strategies σ and τ is defined in the same spirit, using comprehension:

Definition 8. *Suppose that $\sigma \in \mathcal{P}(A)$ is a P -strategy of a simple game A and that $\tau \in \mathcal{P}(B)$ is a P -strategy of a simple game B . The tensor product $\sigma \otimes \tau$ is the P -strategy of the simple game $A \otimes B$ defined as*

$$\sigma \otimes \tau = \text{image}(\text{supp}_\sigma \otimes \text{supp}_\tau).$$

Here, the morphism $\text{supp}_\sigma \otimes \text{supp}_\tau : \{A \mid \sigma\} \otimes \{B \mid \tau\} \rightarrow A \otimes B$ denotes the tensor product (computed in the original category \mathcal{G}) of the morphisms supp_σ and supp_τ . A direct description of $\sigma \otimes \tau \in \mathcal{P}(A \otimes B)$ is also possible, as the presheaf which transports every position (e, a, b) of the simple game $A \otimes B$ to the set-theoretic product below:

$$\sigma \otimes \tau \quad : \quad (e, a, b) \quad \mapsto \quad \sigma(a) \times \tau(b).$$

As indicated in the introduction, the tensor product of P -strategies defines a family of functors $m_{A,B} : \mathcal{P}(A) \times \mathcal{P}(B) \rightarrow \mathcal{P}(A \otimes B)$ which, together with the isomorphism of categories $m_1 : 1 \rightarrow \mathcal{P}(1)$, equips the pseudofunctor \mathcal{P} with a lax monoidal structure:

Theorem 3. *The pseudofunctor \mathcal{P} equipped with the family of functors $m_{A,B}$ and m_1 defines a lax monoidal pseudofunctor from $(\mathcal{G}, \otimes, 1)$ to $(\mathbf{Cat}, \times, 1)$.*

Proof. See Appendix H.

The bicategory \mathcal{S} of simple games and non-deterministic strategies is deduced from the lax monoidal pseudofunctor \mathcal{P} in the following generic way, inspired by the idea of monoidal refinement system [16].

Definition 9. *The bicategory \mathcal{S} has simple games A, B, C as objects, with the hom-category $\mathcal{S}(A, B)$ defined as*

$$\mathcal{S}(A, B) \quad = \quad \mathcal{P}(A \multimap B)$$

the composition functor

$$\circ_{A,B,C} : \mathcal{P}(B \multimap C) \times \mathcal{P}(A \multimap B) \longrightarrow \mathcal{P}(A \multimap C)$$

defined as the composite

$$\mathcal{P}(B \multimap C) \times \mathcal{P}(A \multimap B) \xrightarrow{m_{B \multimap C, A \multimap B}} \mathcal{P}((B \multimap C) \otimes (A \multimap B)) \xrightarrow{\mathcal{P}(\text{comp}_{A,B,C})} \mathcal{P}(A \multimap C)$$

where $\text{comp}_{A,B,C} : (B \multimap C) \otimes (A \multimap B) \rightarrow (A \multimap C)$ is the morphism which internalizes composition in the symmetric monoidal closed category \mathcal{G} . In the same way, the identity in $\mathcal{P}(A \multimap A)$ is defined as the composite

$$1 \xrightarrow{m_1} \mathcal{P}(1) \xrightarrow{\mathcal{P}(\text{id}_A)} \mathcal{P}(A \multimap A)$$

where the morphism $\text{id}_A : 1 \rightarrow (A \multimap A)$ internalizes the identity morphism in \mathcal{G} .

Proposition 7. *The bicategory \mathcal{S} is symmetric monoidal closed in the sense that there exists a family of isomorphisms*

$$\Phi_{A,B,C} \quad : \quad \mathcal{S}(A \otimes B, C) \quad \cong \quad \mathcal{S}(B, A \multimap C).$$

The isomorphism $\Phi_{A,B,C}$ is defined as the image by the pseudofunctor \mathcal{P} of the isomorphism

$$\varphi_{A,B,C} \quad : \quad (A \otimes B) \multimap C \quad \cong \quad B \multimap (A \multimap C)$$

in the category \mathcal{G} between the underlying simple games. One benefit of our conceptual approach is that the monoidal closed structure of \mathcal{S} is neatly deduced from the monoidal closed structure of the original category \mathcal{G} .

7 The exponential modality on the category \mathcal{G}

Now that the monoidal bicategory \mathcal{S} has been defined, we analyze how the exponential modality defined in [4] adapts to our sheaf-theoretic framework.

Definition 10. *Let A be a simple game. $!A$ is the simple game whose set $(!A)_n$ of positions of degree n consists of the pairs (ϕ, \bar{a}) such that:*

- ϕ is a O -heap over n and $\bar{a} = (a_1, \dots, a_n)$ is a sequence of positions of A ,
- for each $k \in \{1, \dots, n\}$, the sequence of positions in $\bar{a} = (a_1, \dots, a_n)$ corresponding to the branch of k in ϕ defines a play

$$\{a_k, a_{\phi(k)}, a_{\phi^2(k)}, \dots\}$$

of the simple game A .

The predecessor function $\pi_n : (!A)_{n+1} \rightarrow (!A)_n$ is defined as $\pi(\phi, \bar{a}) = (\phi \upharpoonright (n), \bar{a} \upharpoonright (n))$.

Definition 11. *Let f be a deterministic strategy of $A \multimap B$. The deterministic strategy $!f$ of $!A \multimap !B$ consists of the positions $(e, (\phi, \bar{a}), (\psi, \bar{b}))$ such that $\phi = e^* \psi$ and, for each branch of (ϕ, e, π) , the positions associated to that branch are played by f .*

It is worth observing that the construction of $!f : !A \rightarrow !B$ can be decomposed in the following way. Consider the morphism

$$n_{A,B} : !(A \multimap B) \longrightarrow !A \multimap !B$$

obtained by currying the composite morphism

$$!(A \multimap B) \otimes !A \xrightarrow{\text{lax monoidal}} !((A \multimap B) \otimes A) \xrightarrow{\text{!evaluation}} !B$$

in the symmetric monoidal closed category \mathcal{G} , where we use the coercion morphism which provides the exponential modality $! : \mathcal{G} \rightarrow \mathcal{G}$ with the structure of a lax monoidal functor.

Definition 12 (#f). *Given a deterministic strategy f of a simple game A , the deterministic strategy $\#f$ of the simple game $!A$ has positions the pairs (ϕ, \bar{a}) such that for each branch of (ϕ, \bar{a}) , the positions associated to that branch are played by the deterministic strategy f .*

Proposition 8. *Given a morphism $f : A \rightarrow B$ of the category \mathcal{G} and its curried form $\lambda_a.f : 1 \rightarrow A \multimap B$, the composite morphism*

$$1 \xrightarrow{\# \lambda_a : A.f} !(A \multimap B) \xrightarrow{n_{A,B}} !A \multimap !B$$

is the curried form $\lambda x : !A. !f$ in the category \mathcal{G} of the morphism $!f : !A \rightarrow !B$.

More details about the original exponential modality in \mathcal{G} will be found in Appendix C. By analogy with Prop. 6, we establish that

Proposition 9. *Suppose that $f : A \rightarrow B$ is a morphism in the category \mathcal{G} . Then, the morphism*

$$!f : !A \longrightarrow !B$$

is slender when f is slender, and functional when f is functional.

Proof. See Appendix I.

8 The exponential modality on the bicategory \mathcal{S}

In this section, we define the linear exponential modality $! : \mathcal{S} \rightarrow \mathcal{S}$ on the symmetric monoidal closed bicategory \mathcal{S} , in order to define a 2-categorical model of intuitionistic linear logic. The construction is inspired by the observation made in the previous section (Prop. 8).

Definition 13. *Given a P -strategy $\sigma \in \mathcal{P}(A)$ of a simple game A , the P -strategy $\#\sigma$ of the simple game $!A$ is defined as the image in $\mathcal{P}(!A)$ of the morphism*

$$!\text{supp}_\sigma : !\{A|\sigma\} \longrightarrow !A.$$

Note that the definition of $\#\sigma$ induces a commutative diagram in the category \mathcal{G}

$$\begin{array}{ccc} !\{A|\sigma\} & \xrightarrow{\text{isomorphism}} & \{!A|\#\sigma\} \\ & \searrow \text{!supp}_\sigma & \swarrow \text{supp}_{\#\sigma} \\ & & !A \end{array}$$

where the top arrow is an isomorphism. Moreover, the definition of $\#\sigma$ coincides with the previous definition (Def. 12) when the P -strategy $\sigma = f$ happens to be deterministic. Consequently, for two games A, B and a deterministic strategy $f : A \multimap B$, we have $\text{image}(!f) \cong \#\mathcal{S}\text{image}(f)$ and $\#\mathcal{S}f = \#f$. As mentioned in the introduction, this construction $\sigma \mapsto \#\sigma$ defines a functor

$$p_A : \mathcal{P}(A) \longrightarrow \mathcal{P}(!A).$$

Now, remember that a morphism $\sigma : A \rightarrow B$ of the bicategory \mathcal{S} is defined as a P -strategy

$$\sigma \in \mathcal{P}(A \multimap B).$$

For that reason, every such morphism $\sigma : A \rightarrow B$ induces a P -strategy

$$\#\sigma \in \mathcal{P}(!(A \multimap B)).$$

In order to turn the P -strategy $\#\sigma$ into a P -strategy

$$!\sigma \in \mathcal{P}(!A \multimap !B)$$

we apply the functor

$$\mathcal{P}(n_{A,B}) : \mathcal{P}!(A \multimap B) \longrightarrow \mathcal{P}(!A \multimap !B)$$

to the P -strategy $\#\sigma$, where

$$n_{A,B} : !(A \multimap B) \longrightarrow !A \multimap !B$$

denotes the structural morphism of \mathcal{G} defined in the previous section. The construction may be summarized as follows:

Definition 14. *The morphism $!\sigma : !A \rightarrow !B$ of the bicategory \mathcal{S} associated to the morphism $\sigma : A \rightarrow B$ is defined as the P -strategy*

$$\mathcal{P}(n_{A,B})(\#\sigma) \in \mathcal{P}(!A \multimap !B).$$

Theorem 4. *With this definition, $! : \mathcal{S} \rightarrow \mathcal{S}$ defines a pseudofunctor from the bicategory \mathcal{S} to itself.*

Proof. See Appendix J.

The family of morphisms

$$\delta_A : !A \rightarrow !!A \qquad \varepsilon_A : !A \rightarrow A$$

are defined with the same deterministic strategies in $\mathcal{P}(!A \multimap !!A)$ and $\mathcal{P}(!A \multimap A)$ as in the original category \mathcal{G} . One checks that the families δ and ε define natural transformations between pseudonatural functors on \mathcal{S} (as defined in Def. 26), and that the 2-functor $! : \mathcal{S} \rightarrow \mathcal{S}$ defines a 2-comonad in the appropriate bicategorical sense (see Def 27). The family of morphisms

$$d_A : !A \rightarrow !A \otimes !A \qquad e_A : !A \rightarrow 1$$

are defined with the same deterministic strategies in $\mathcal{P}(!A \multimap !A \otimes !A)$ and in $\mathcal{P}(!A \multimap 1)$ as in the original category \mathcal{G} , and one checks that they define natural transformations between pseudonatural functors on \mathcal{S} . One obtains that

Theorem 5. *The bicategory \mathcal{S} equipped with the exponential modality $! : \mathcal{S} \rightarrow \mathcal{S}$ defines a bicategorical model of intuitionistic linear logic.*

The formal and rigorous verification of these facts would be extremely tedious if done directly on the bicategory \mathcal{S} of nondeterministic strategies. Our proof relies on the fact that the constructions of the model (Defs 9, 14) are performed by “push” functors $\mathcal{P}(f)$ above a structural morphism f living in the original category \mathcal{G} . The interested reader will find part of the detailed proof in Appendix K.

9 Conclusion

We construct a bicategory \mathcal{S} of simple games and non-deterministic strategies, which is symmetric monoidal closed in the extended 2-dimensional sense. We then equip the bicategory \mathcal{S} with a linear exponential modality $! : \mathcal{S} \rightarrow \mathcal{S}$ which defines a 2-categorical model of intuitionistic linear logic. This provides, as far as we know, the first sheaf-theoretic and non-deterministic game semantics of intuitionistic linear logic — including, in particular, a detailed description of the exponential modality.

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A The category \mathcal{G} of simple games and deterministic strategies

We recall the construction of the category \mathcal{T} of schedules performed in [4] and how we deduce from it the category \mathcal{G} of simple games and deterministic strategies.

Definition 15 (Schedule). *A schedule is defined as a function $e : \{1, \dots, n\} \rightarrow \{0, 1\}$ verifying $e(1) = 1$ and $e(2k+1) = e(2k)$ whenever $1 \leq 2k \leq n-1$. The number of 0's and 1's in e are noted $|e|_0$ and $|e|_1$ respectively. A schedule e is noted $e : |e|_0 \rightarrow |e|_1$.*

A schedule $e : p \rightarrow q$ may be equivalently seen as a couple $l : (p) \rightarrow (p+q)$ and $r : (q) \rightarrow (p+q)$ of order-preserving and globally surjective functions, such that $r(1) = 1$ and

$$l(i) \text{ odd} \Rightarrow l(i+1) = l(i) + 1 \quad r(j) \text{ even} \Rightarrow r(j+1) = r(j) + 1$$

for all $1 \leq i \leq p-1$ and $1 \leq j \leq q-1$, where (n) stands for the finite ordinal $(n) = \{1, \dots, n\}$.

Definition 16. *The category of schedules \mathcal{T} has the natural numbers as objects, the schedules $e : p \rightarrow q$ as morphisms from p to q .*

The identity morphism $c : p \rightarrow p$ is the copycat schedule c characterized by the fact that $c(2k+1) \neq c(2k+2)$ for all $1 \leq 2k \leq 2p$. Details on the composition of two schedules $e : p \rightarrow r$ and $e' : r \rightarrow q$ as a schedule $e.e' : p \rightarrow q$ can be found in [4]. Now, we explain how we derive the category \mathcal{G} from the category \mathcal{T} . We start by defining the simple game $A \multimap B$ of linear maps from A to B :

Definition 17. *The simple game $A \multimap B$ is defined as the set $(A \multimap B)_n$ of all the triples (e, a, b) consisting of a schedule $e : p \rightarrow q$ with $p+q = n$, a position $a \in A_p$ and $b \in B_q$. The predecessor function π is defined as*

$$\pi(e, a, b) = \begin{cases} (e \upharpoonright (n-1), \pi(a), b) & \text{if } e(n) = 0 \\ (e \upharpoonright (n-1), a, \pi(b)) & \text{if } e(n) = 1 \end{cases}$$

Definition 18. *The category \mathcal{G} has simple games A, B as objects, and deterministic P -strategies f, g of $A \multimap B$ as morphisms from A to B . Note that we use latin letters instead of greek letters for deterministic strategies. The identity morphism $i_A : A \rightarrow A$ is defined as the P -strategy of $A \multimap A$ whose positions of degree $2n$ are the triples (c, a, a) where $c : n \rightarrow n$ is the copycat schedule, and $a \in A_n$. The composite $g \circ f : A \rightarrow C$ of two deterministic P -strategies $f : A \rightarrow B$ and $g : B \rightarrow C$ is the deterministic P -strategy whose set of positions of degree $2n$ is defined as*

$$(g \circ f)_{2n} = \coprod_{\substack{e : p \rightarrow r, e' : r \rightarrow q \\ p+q=2n}} \left\{ (e.e', a, c) \mid \exists b \in B_r, (e, a, b) \in \sigma_{p+r}, (e', b, c) \in \tau_{r+q} \right\}$$

B The tensor product in the category \mathcal{G}

Definition 19 (Tensorial schedule). A \otimes -schedule is a function $e : \{1, \dots, n\} \rightarrow \{0, 1\}$ verifying $e(2k+1) = e(2k+2)$ whenever $0 \leq 2k \leq n-2$.

Definition 20 ($A \otimes B$). The positions of the simple game $A \otimes B$ of degree n are the triples (e, a, b) where $e : p \otimes q$ is a \otimes -schedule with $p+q = n$, $a \in A_p$ and $b \in B_q$. The predecessor function π is defined as

$$\pi(e, a, b) = \begin{cases} (e \upharpoonright (n-1), \pi(a), b) & \text{if } e(n) = 0 \\ (e \upharpoonright (n-1), a, \pi(b)) & \text{if } e(n) = 1 \end{cases}$$

The simple game 1 is the simple game with a unique position $*$, of degree 0.

We can also define \otimes on strategies. Intuively, for $f : A \rightarrow B$ and $g : C \rightarrow D$ two morphisms of the category \mathcal{G} , the plays of the strategy $f \otimes g$ of the simple game $(A \otimes C) \multimap (B \otimes D)$ are obtained by combining through a tensorial schedule plays of f and g .

The intuition is that, once we know the structure of f and g , the structure of plays of $f \otimes g$ is entirely directed by what happens in $B \otimes D$. The only agency that Opponent really has is to decide at some points whether to play on B or D , the rest being handled by the plays of f , g and the structure of $(A \otimes C) \multimap (B \otimes D)$. Formally, this gives the proposition :

Proposition 10. Let $f : A \multimap B, g : C \multimap D$ be two deterministic strategies. Assuming a valid play of $f \otimes g : A \otimes C \multimap B \otimes D$ and the associated schedules $e : A \otimes C \rightarrow B \otimes D, t_1 : A \times C, t_2 : B \times D, e_1 : A \rightarrow B, e_2 : C \rightarrow D$, the knowledge of t_2, e_1, e_2 is enough to reconstruct e and t_1 .

Proof. The first O move of such a play is in $B \otimes D$ to follow the structure of $A \otimes C \multimap B \otimes D$. This is given to us by t_2 . Let us assume it is a move in D (The other case is handled similarly).

The P move after that will necessarily be a move in C or D , as playing a move in A, B would break the structure of $A \multimap B, B \otimes D$ respectively. e_2 gives us the information.

- If it is a move in D , We go back to a situation equivalent to the initial one. We have also started to reconstruct e , which starts by 11.
- If it is a move in C , we start to reconstruct both e which starts by 10 and t_1 which starts by 1.

In this last case, the following O move will be a move in C as a move in A, B, D would break the structure of $A \multimap B, B \otimes D, C \multimap D$ respectively. e is then at 100 and t_1 at 11.

Finally, the following P move will be a move in either C or D as a move in A, B would break the structure of $A \multimap B, B \otimes D$ respectively. e_2 gives us this information.

- If it is a move in D , We go back to a situation equivalent to the initial one. We have also started to reconstruct e , which starts by 1001 and t_1 which starts by 11. We've also played the first two moves of t_2 which is at 11.
- If it is a move in C , we go back to the precedent situation (the one with a fixed O move in C) with e at 1000 and t_1 at 111.

To sum up the described construction, once an opponent move in B or D is played, the play is stuck playing in either $A \multimap B$ or $C \multimap D$ until a player move is played in B, D respectively. t_2 decides whether to play the opponent move in B or D and e_1 guides the play in $A \multimap B$ in the first case, e_2 guides it in $C \multimap D$ in the second. This guides us through the whole play and allows us to reconstruct both e and t_1 .

In particular, any compatible plays of $f, g, B \otimes D$ induce a play of $f \otimes g$.

This proposition and its proof are key in several proofs we will make in the rest of the paper.

Proposition 11. *The category $(\mathcal{G}, \otimes, 1, \multimap)$ is symmetric monoidal closed.*

C The exponential modality on the category \mathcal{G}

In this section, we recall the combinatorial structures introduced in [4] to construct the linear exponential comonad $! : \mathcal{G} \rightarrow \mathcal{G}$ on the symmetric monoidal closed category \mathcal{G} .

Definition 21 (Pointer function). *A pointer function on n is a parity-reversing function*

$$\phi : \{1, \dots, n\} \longrightarrow \{0, \dots, n-1\}$$

such that $\phi(i) < i$ for all i . A pointer function ϕ is called an O-heap if $\phi(2k) = 2k-1$ for all k , and a P-heap if $\phi(2k+1) = 2k$ for all k . The set $\{k, \phi(k), \phi^2(k), \dots\}$ will be called the branch of ϕ associated to the integer k . Note that the predecessor function π defined as $\pi(i) = i-1$ for all i is both an O-heap and a P-heap.

Definition 22. *Suppose that $e : p \rightarrow q$ is a schedule, that ϕ is a O-heap over q and that ψ is a P-heap over p . The O-heap (ϕ, e, ψ) on $p+q$ is defined as follows:*

$$(\phi, e, \psi)(k) = \begin{cases} r(\phi(j)) & \text{if } k = r(j) \text{ is odd} \\ l(\psi(i)) & \text{if } k = l(i) \text{ is odd} \\ k-1 & \text{otherwise} \end{cases}$$

where the schedule e is represented as a pair (l, r) as explained in §A. Intuitively, the O-heap (ϕ, e, ψ) points alongside ϕ when the schedule e is at 1 and alongside ψ otherwise. The fact that (ϕ, e, ψ) defines an O-heap is ensured by the even case.

We recall the partial order over the set of pointer functions introduced in [4].

Definition 23 (Generalization). *Given two pointer functions ϕ, ψ , we say that ϕ is a generalization of ψ , and note $\phi \succeq \psi$, if the branch of ϕ associated to $k \in \{1, \dots, n\}$ can be injected in the branch of ψ associated to k , or, in other words, if for all k , there exists j such that $\phi(k) = \psi^j(k)$.*

Further in the paper, and in certain proofs, we will also need to look into the structure of $!!A$. Intuitively, positions of $!!A$ are pairs (ϕ, \bar{u}) where \bar{u} is a sequence of positions of $!A$ and ϕ an O -heap. It is equivalent to another representation using only a sequence of positions of A :

Proposition 12. *A position (ϕ, \bar{u}) of $!!A$ is equivalent to (ϕ, ψ, \bar{a}) with $\phi \succeq \psi$, ψ an O -heap, \bar{a} a sequence of positions of A , verifying*

$$\forall i, j \in \{1, \dots, n\}, (i \neq j) \Rightarrow \exists k, a_{\phi^k(i)} \neq a_{\phi^k(j)}$$

The moves alongside the branches of ψ are then plays of the simple game A .

From this follows a description of the strategy

$$!!f : !!A \longrightarrow !!B$$

for a deterministic strategy $f : A \multimap B$. The positions of $!!f$ are of the form

$$(e, (\phi, \psi, \bar{a}), (\phi', \psi', \bar{b}))$$

where $e^* \phi' = \phi, e^* \psi' = \psi$ and each thread of (ψ, e, π) is a play of the strategy f .

D Some bicategorical definitions

In this section, we recall a few definitions required by our bicategorical setting.

Definition 24. *A pseudofunctor is a mapping between bicategories \mathcal{C} and \mathcal{D} where the usual functorial equations $F(f \circ g) = F(f) \circ F(g)$ and $F(Id_A) = Id_{F(A)}$ are only valid up to natural bijective 2-morphisms in \mathcal{D} .*

Definition 25. *Let $(\mathcal{C}, \otimes_{\mathcal{C}}, 1_{\mathcal{C}})$ and $(\mathcal{D}, \otimes_{\mathcal{D}}, 1_{\mathcal{D}})$ be two monoidal bicategories. A lax monoidal pseudofunctor between them is given by :*

- a pseudofunctor $F : \mathcal{C} \rightarrow \mathcal{D}$
- a morphism $\epsilon : 1_{\mathcal{D}} \rightarrow F(1_{\mathcal{C}})$
- for every pair of objects $A, B \in \mathcal{C}$, a natural transformation $\mu_{A,B} : F(A) \otimes_{\mathcal{D}} F(B) \rightarrow F(A \otimes_{\mathcal{C}} B)$

satisfying the following conditions :

- associativity : For every triple of objects $A, B, C \in \mathcal{C}$, the following diagram commutes :

$$\begin{array}{ccc}
(F(A) \otimes_{\mathcal{D}} F(B)) \otimes_{\mathcal{D}} F(C) & \xrightarrow{a_{F(A), F(B), F(C)}^{\mathcal{D}}} & F(A) \otimes_{\mathcal{D}} (F(B) \otimes_{\mathcal{D}} F(C)) \\
\mu_{A, B} \otimes id \downarrow & & id \otimes \mu_{B, C} \downarrow \\
F(A \otimes_{\mathcal{C}} B) \otimes_{\mathcal{D}} F(C) & & F(A) \otimes_{\mathcal{D}} F(B \otimes_{\mathcal{C}} C) \\
\mu_{A \otimes B, C} \downarrow & & \mu_{A, B \otimes C} \downarrow \\
F((A \otimes_{\mathcal{C}} B) \otimes_{\mathcal{C}} C) & \xrightarrow{F(a_{A, B, C}^{\mathcal{C}})} & F(A \otimes_{\mathcal{C}} (B \otimes_{\mathcal{C}} C))
\end{array}$$

where the two morphisms $a^{\mathcal{C}}, a^{\mathcal{D}}$ denote the associators of the two tensor products.

- unality : For every object $A \in \mathcal{C}$, the following diagram and its right symmetry both commute :

$$\begin{array}{ccc}
1_{\mathcal{D}} \otimes_{\mathcal{D}} F(A) & \xrightarrow{\epsilon \otimes id} & F(1_{\mathcal{C}}) \otimes_{\mathcal{D}} F(A) \\
l_{F(A)}^{\mathcal{D}} \downarrow & & \mu_{1_{\mathcal{C}}, A} \downarrow \\
F(A) & \xleftarrow{F(l^{\mathcal{C}} A)} & F(1_{\mathcal{C}} \otimes_{\mathcal{C}} A)
\end{array}$$

where $l^{\mathcal{C}}, l^{\mathcal{D}}$ denote the left unitors of the two tensor products.

Definition 26. Let F, G be two pseudofunctors between two bicategories \mathcal{C} and \mathcal{D} . A pseudonatural transformation $\phi : F \rightarrow G$ is given by :

- for every object A of \mathcal{C} , a morphism $\phi(A) : F(A) \rightarrow G(A)$ of \mathcal{D} .
- for every morphism $f : A \rightarrow B$ of \mathcal{C} , a bijective 2-morphism $\phi(f) : \phi(B) \circ F(f) \Rightarrow G(f) \circ \phi(A)$

such that

- ϕ respects composition of morphisms, meaning that we have an equivalence between

$$(\phi(A) \triangleleft G(f, g)) \cdot (\phi(f) \triangleright G(g)) \cdot (F(f) \triangleleft \phi(g))$$

and

$$\phi(g \circ f) \cdot (F(f, g) \triangleright \phi(C)),$$

both being 2-morphisms from

$$\phi(C) \circ F(g) \circ F(f) \Rightarrow G(g \circ f) \circ \phi(A),$$

where \cdot is the vertical composition between 2-morphisms, $\triangleleft, \triangleright$ the two versions of the horizontal composition between a morphism and a 2-morphism, (also called whiskering), and $F(f, g) : F(g) \circ F(f) \Rightarrow F(g \circ f)$ is the bijective 2-morphism coming from the pseudofunctor F .

– ϕ respects the identity morphisms, meaning we have an equivalence between

$$L_{\phi(A)}^{\mathcal{D}} \cdot \epsilon_{id_A}^F \triangleright \phi(A)$$

and

$$R_{\phi(A)}^{\mathcal{D}} \cdot \phi(A) \triangleleft \epsilon_{id_A}^G \cdot \phi(id_A)$$

both being 2-morphisms from

$$\phi(A) \circ F(id_A) \Rightarrow \phi(A)$$

where $L_{\phi(A)}^{\mathcal{D}} : \phi(A) \circ id_{F(A)} \Rightarrow \phi(A)$ is the left unitor coming from the bicategory \mathcal{D} and $\epsilon_{id_A}^F : F(id_A) \Rightarrow id_{F(A)}$ is the bijective 2-morphism coming from the pseudofunctor F .

– ϕ is natural in the following sense : for every 2-morphism $\psi : f \Rightarrow g$ with $f, g : A \rightarrow B$, we have an equivalence between

$$\phi(g) \cdot F(\psi) \triangleright \phi(B)$$

and

$$\phi(A) \triangleleft G(\psi) \cdot \phi(f).$$

Definition 27. A fully weak comonad G on a bicategory \mathcal{C} is a pseudofunctor, along with pseudonatural transformations δ and ϵ that satisfy the usual laws of a comonad up to natural bijective 2-morphisms in \mathcal{C} .

E Proof of proposition 2

Proof. Let A, B be two games.

Let σ be a P -cartesian transduction between A and B . The associated deterministic strategy f_σ is simply given by :

$$f_\sigma(2n) = \{(c, a, \sigma(a)) \mid a \in A(n)\}$$

This definition clearly gives a functional strategy, the determinism being given by the fact that σ is P -cartesian.

Conversely, let f be a functional strategy of $A \multimap B$. The associated P -cartesian transduction σ_f is given by :

$$\sigma_f(2n)(a) = b \text{ s.t. } (c, a, b) \in f(4n)$$

Such a b is unique by functionality of f .

F Proof that \mathcal{P} is a pseudofunctor

Proof. First we need to complete the definition of \mathcal{P} by detailing why, for f a deterministic strategy of $A \rightarrow B$ and σ a P -strategy over A , $\mathcal{P}(f)(\sigma)$ is indeed a P -strategy over B , and thus a presheaf over $\mathbf{tree}(B_P)$. For this, we need to define the collection of projector functions $\pi_{2n} : \mathcal{P}(f)(\sigma)(2n) \rightarrow \mathcal{P}(f)(\sigma)(2n-2)$ as follows :

For $x \in \mathcal{P}(f)(\sigma)(2n)$ over b (meaning $x \in \mathcal{P}(f)(\sigma)(b)$ and $b \in B_{2n}$), there exists by definition a unique e, a such that $(e, a, b) \in f$ and $x \in \sigma(a)$. From this, we define :

$$\pi_{2n}(x) = \pi_{\sigma}^k(x), (\pi^{2k+2}(e), \pi_A^{2k}(a), \pi_B^2(b)) \in f.$$

By determinism of f , there is only one such k . Moreover, we also have $\pi_{\sigma}^k(x) \in \sigma(\pi_A^{2k}(a))$. Consequently, by definition of $\mathcal{P}(f)(\sigma)$, we have $\pi_{\sigma}^k(x) \in \mathcal{P}(f)(\sigma)(\pi_B^2(b))$ as expected.

Next step is to show that, for a strategy $f : A \rightarrow B$, $\mathcal{P}(f)$ is a functor from $\mathcal{P}(A)$ to $\mathcal{P}(B)$. For that, we need to define its effects on simulations. For $\alpha : \sigma \rightarrow \tau$, $\mathcal{P}(f)(\alpha) : \mathcal{P}(f)(\sigma) \rightarrow \mathcal{P}(f)(\tau)$ is simply defined by applying α to all positions of $\mathcal{P}(f)(\sigma)$, as all those are induced from positions of σ by definition. With this, it is easy to verify that $\mathcal{P}(f)$ preserves identities and composition of simulations.

Finally, let us show that \mathcal{P} is a pseudofunctor.

First, $\mathcal{P}(Id_A)\sigma$ associates to a position a of A the set :

$$\mathcal{P}(Id_A)(\sigma) : a \mapsto \coprod_{(c, a, a) \in Id_A} \sigma(a).$$

which is instantly isomorphic to $\sigma(a)$. Factoring the effect on simulations, it is easy to build a bijective natural transformation between $\mathcal{P}(Id_A) \cong Id_{\mathcal{P}(A)}$. Thus $\mathcal{P}(Id_A) \cong Id_{\mathcal{P}(A)}$.

Next, let $f : A \rightarrow B$ and $g : B \rightarrow C$ two deterministic strategies and σ a P -strategy of A . We have :

$$\mathcal{P}(g)(\mathcal{P}(f)(\sigma)) : c \mapsto \coprod_{(e_2, b, c) \in g} \coprod_{(e_1, a, b) \in f} \sigma(a).$$

This is easily isomorphic to $\mathcal{P}(g \circ f)\sigma$ which is given by :

$$\mathcal{P}(g \circ f)(\sigma) : c \mapsto \coprod_{(e, a, c) \in g \circ f} \sigma(a).$$

This isomorphism is a consequence of the definition of composition for deterministic strategies, as there is only one triple e_1, e_2, b such that $(e_1, a, b) \in f$,

$(e_2, b, c) \in g$ and $e = e_1 \cdot e_2$ for a position $(e, a, c) \in g \circ f$.

This extends into a natural isomorphism between the functors $\mathcal{P}(g \circ f)$ and $\mathcal{P}(g)(\mathcal{P}(f))$, giving us the fact that \mathcal{P} is indeed a pseudofunctor.

G Proof of Proposition 6

Proof. – Let $f : A \multimap B, g : C \multimap D$ be two slender strategies. Let (t_2, b, d) be a player position of $B \otimes D$. Since f and g are slender, there exist unique e_f, a, e_g, c such that $(e_f, a, b) \in f, (e_g, c, d) \in g$. Using t_2, e_f, e_g and proposition 10, we reconstruct e, t_1 such that $(e, (t_1, a, c), (t_2, b, d))$ is a position of $f \otimes g$. This position is unique as the reconstruction of proposition 10 is unique, and thus $f \otimes g$ is a slender strategy.

– Let $f : A \multimap B, g : C \multimap D$ be two functional strategies. Let (t_1, a, c) be an opponent position of $A \otimes C$. Since f and g are functional strategies, there exist unique b, d such that $(cp_f, a, b) \in f, (cp_g, c, d) \in g$. The study of $f \otimes g$ done in the proof of proposition 10 gives us that any valid position of $f \otimes g$ would have a copycat schedule (as the schedule is built from sequences $1.0^k.1$ of cp_f and cp_g). This implies immediately that the only possible position is $cp, (t_1, a, c), (t_1, b, d)$ as no other play would verify the needed structures, and thus $f \otimes g$ is a functional strategy.

H Proof of Theorem 3

Proof. First, we can note that the unit 1 of \mathcal{G} has a unique P -strategy, the empty strategy. Consequently, $\mathcal{P}(1)$ is the singleton category, which is the unit of the cartesian product in **Cat**.

Moreover, to extend \mathcal{P} as a lax monoidal pseudofunctor, we need a transformation $\mu_{A,B} : \mathcal{P}(A) \times \mathcal{P}(B) \rightarrow \mathcal{P}(A \otimes B)$ natural in A and B .

Since the morphisms of that transformation live in **Cat**, they are functors. We thus define :

for σ an object of $\mathcal{P}(A)$ and τ an object of $\mathcal{P}(B)$,

$$\mu_{A,B}(\sigma, \tau) = \sigma \otimes \tau$$

for $\alpha : \sigma \rightarrow \sigma'$ a morphism of $\mathcal{P}(A)$ and $\beta : \tau \rightarrow \tau'$ a morphism of $\mathcal{P}(B)$, $\mu_{A,B}(\alpha, \beta) : \sigma \otimes \tau \rightarrow \sigma' \otimes \tau'$ is defined by :

$$\mu_{A,B}(\alpha, \beta)(t, x, y) = (t, \alpha(x), \beta(y))$$

We now need to prove that this transformation is natural in A and B , and that it verifies the two commutative diagrams of a lax monoidal functor (associativity and unitality), up to bijective simulations. Those last two are easy to

verify and use similar arguments, so we will focus on the naturality.

We need our transformation to verify the following commutative diagram for A, B, A', B' four games and $f : A \multimap A', g : B \multimap B'$ two deterministic strategies:

$$\begin{array}{ccc}
\mathcal{P}(A) \times \mathcal{P}(B) & \xrightarrow{\mu_{A,B}} & \mathcal{P}(A \otimes B) \\
\mathcal{P}(f) \times \mathcal{P}(g) \downarrow & & \mathcal{P}(f \otimes g) \downarrow \\
\mathcal{P}(A') \times \mathcal{P}(B') & \xrightarrow{\mu_{A',B'}} & \mathcal{P}(A' \otimes B')
\end{array}$$

Let σ be a P -strategy of A and τ a P -strategy of B . Verifying the commutative diagram amounts to finding two reciprocal morphisms between $\mathcal{P}(f)(\sigma) \otimes \mathcal{P}(g)(\tau)$ and $\mathcal{P}(f \otimes g)(\sigma \otimes \tau)$.

$$\mathcal{P}(f)(\sigma) \otimes \mathcal{P}(g)(\tau) \cong \text{image}(f \circ \text{supp}_\sigma) \otimes \text{image}(g \circ \text{supp}_\tau)$$

$\mathcal{P}(f)(\sigma) \otimes \mathcal{P}(g)(\tau) \cong \text{image}(f \circ \text{supp}_\sigma \otimes g \circ \text{supp}_\tau)$ by consequences of prop 6

$$\mathcal{P}(f \otimes g)(\sigma \otimes \tau) \cong \text{image}((f \otimes g) \circ \text{supp}_{\sigma \otimes \tau})$$

$\mathcal{P}(f \otimes g)(\sigma \otimes \tau) \cong \text{image}((f \otimes g) \circ \text{supp}_\sigma \otimes \text{supp}_\tau)$ by consequences of prop 6

By bifunctionality of \otimes , we have $f \circ \text{supp}_\sigma \otimes g \circ \text{supp}_\tau \cong (f \otimes g) \circ \text{supp}_\sigma \otimes \text{supp}_\tau$, giving us the equality of the images we need, up to bijective simulations.

I Proof of Proposition 9

Proof. – Let $(\psi, \bar{b} = b_1, \dots, b_n)$ a P position of $!B$. Since f is slender, for all b_i player positions of \bar{b} , there exists a unique pair (e_i, a_i) such that $(e_i, a_i, b_i) \in f$.

We use a method similar to the one used in the proof of proposition 10. Instead of using the tensorial schedule to guide us in reconstructing the play of $!A \multimap !B$, we use ψ , which indicates us what is the next player move b_i to get to (starting from b_{i-2} , and assuming we have reconstructed e and ϕ so far), and then use the play (e_i, a_i, b_i) to construct the play.

The sequence of moves we add is the suffix of the play (e_i, a_i, b_i) looking like $b_{i-1}a_i^1 \dots a_i^k b_i$ (with $a_i^k = a_i$) as any other move in the play (e_i, a_i, b_i) has already been played (since in particular any b move prior to b_{i-1} has been played).

Player cannot backtrack in the middle of the sequence $b_{i-1}a_i^1 \dots a_i^k b_i$ without breaking the fact that the full play is associated to a O -heap in $!(A \multimap B)$.

This allows us to extend e into $e.1.0^k.1$ and ϕ by linking a_i^1 to its predecessor

in A of the play (e_i, a_i, b_i) .

This method constructs a valid position of $!f$ as all branches are played following f and ϕ is a O-Heap. It is the only possible position including ψ, \bar{b} as everything we have done was determined by ψ, f and \bar{b} . Thus $!f$ is a slender strategy.

- Let $(\phi, \bar{a} = a_1, \dots, a_n)$ an O position of $!A$. Since f is a functional strategy, for all a_i opponent positions of \bar{a} , there exists a unique b_i such that $(c, a_i, b_i) \in f$. By determinism of f , it is also true for all player positions of \bar{a} . By using ϕ as a guide, this easily allows us to construct the position of $!f$: $(c, (\phi, \bar{a}), (\phi, \bar{b} = b_1, \dots, b_n))$.
It is the unique such position for (ϕ, \bar{a}) for reasons similar to the ones evoked in the proof for slender strategies. Thus $!f$ is a functional strategy.

J Proof of Theorem 4

Proof. – For a game A , we have by construction :

$$(!\mathcal{P})_{A,B}(Id_A) = \mathcal{P}(n_{A,B}) \circ \#^S(Id_A)$$

$$(!\mathcal{P})_{A,B}(Id_A) = \mathcal{P}(n_{A,B})(\#Id_A) = Id_{!A}$$

- Let A, B, C be three games and σ a P -strategy of $A \multimap B$, τ a P -strategy of $B \multimap C$. We need to prove that there is a natural isomorphic simulation between $!\mathcal{P}(\tau \circ \sigma)$ and $!\mathcal{P}(\tau) \circ !\mathcal{P}(\sigma)$.

First we will simplify those two strategies through the various properties we have seen so far :

First $!\mathcal{P}(\tau \circ \sigma)$:

$$!\mathcal{P}(\tau \circ \sigma) = \mathcal{P}(n_{A,C})(\#^S(\tau \circ \sigma))$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ \text{supp}_{\#^S(\tau \circ \sigma)}) \text{ by equation 4}$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ !\text{supp}_{\tau \circ \sigma}) \text{ by consequence of def 13}$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ !\text{supp}_{\mathcal{P}(\text{comp}_{A,B,C})(\sigma \otimes \tau)}) \text{ by definition 9}$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ !\text{supp}_{\text{image}(\text{comp}_{A,B,C} \circ \text{supp}_{\sigma \otimes \tau})}) \text{ by equation 4}$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ \text{supp}_{\text{image}(!(\text{comp}_{A,B,C} \circ \text{supp}_{\sigma \otimes \tau}))}) \text{ by consequence of def 13}$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ !(\text{comp}_{A,B,C} \circ \text{supp}_{\sigma \otimes \tau})) \text{ by theorem 1}$$

$$!\mathcal{P}(\tau \circ \sigma) \cong \text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \text{supp}_{\#^S(\sigma \otimes \tau)}) \text{ by functoriality of ! and consequence of def 13}$$

Then , $!\mathcal{P}(\tau) \circ !\mathcal{P}(\sigma)$:

$$!\mathcal{P}(\tau) \circ !\mathcal{P}(\sigma) = \mathcal{P}(n_{B,C})(\#^S \tau) \circ \mathcal{P}(n_{A,B})(\#^S \sigma)$$

$$!\mathcal{P}(\tau) \circ !\mathcal{P}(\sigma) \cong \text{image}(n_{B,C} \circ \text{supp}_{\#^S(\tau)}) \circ \text{image}(n_{A,B} \circ \text{supp}_{\#^S(\sigma)}) \text{ by equation 4}$$

$$!\mathcal{P}(\tau) \circ !\mathcal{P}(\sigma) \cong \mathcal{P}(\text{comp}_{!A,!B,!C})(\text{image}(n_{A,B} \circ \text{supp}_{\#^S(\sigma)}) \otimes \text{image}(n_{B,C} \circ \text{supp}_{\#^S(\tau)})) \text{ by definition 9}$$

$!_{\mathcal{P}}(\tau) \circ !_{\mathcal{P}}(\sigma) \cong \mathcal{P}(\text{comp}_{!A,!B,!C})(\text{image}(n_{A,B} \circ \text{supp}_{\#^s(\sigma)} \otimes n_{B,C} \circ \text{supp}_{\#^s(\tau)}))$ by consequence of prop 6
 $!_{\mathcal{P}}(\tau) \circ !_{\mathcal{P}}(\sigma) \cong \text{image}(\text{comp}_{!A,!B,!C} \circ (\text{supp}_{\text{image}(n_{A,B} \circ \text{supp}_{\#^s(\sigma)} \otimes n_{B,C} \circ \text{supp}_{\#^s(\tau)})}))$ by equation 4
 $!_{\mathcal{P}}(\tau) \circ !_{\mathcal{P}}(\sigma) \cong \text{image}(\text{comp}_{!A,!B,!C} \circ (n_{A,B} \circ \text{supp}_{\#^s(\sigma)} \otimes n_{B,C} \circ \text{supp}_{\#^s(\tau)}))$ by theorem 1
 $!_{\mathcal{P}}(\tau) \circ !_{\mathcal{P}}(\sigma) \cong \text{image}(\text{comp}_{!A,!B,!C} \circ n_{A,B} \otimes n_{B,C} \circ \text{supp}_{\#^s(\sigma)} \otimes \text{supp}_{\#^s(\tau)})$ by bifactoriality of \otimes
 $!_{\mathcal{P}}(\tau) \circ !_{\mathcal{P}}(\sigma) \cong \text{image}(\text{comp}_{!A,!B,!C} \circ n_{A,B} \otimes n_{B,C} \circ !\text{supp}_{(\sigma)} \otimes !\text{supp}_{(\tau)})$ by consequence of def 13

We intend to prove that those two images are isomorphic. For that, we will make the following remark :

$!$ is lax monoidal in \mathcal{G} , meaning that there exists a transformation $\mu_{A,B} : !A \otimes !B \rightarrow !(A \otimes B)$ natural in A and B . Thus we have the following diagram with the top square commuting by naturality of μ :

$$\begin{array}{ccc}
 !(\{\sigma | A \multimap B\} \otimes \{\tau | B \multimap C\}) & \xleftarrow{\mu_{\{\sigma | A \multimap B\}, \{\tau | B \multimap C\}}} & !\{\sigma | A \multimap B\} \otimes !\{\tau | B \multimap C\} \\
 \downarrow !(\text{supp}_{\sigma} \otimes \text{supp}_{\tau}) & & \downarrow !\text{supp}_{\sigma} \otimes !\text{supp}_{\tau} \\
 !(A \multimap B \otimes B \multimap C) & \xleftarrow{\mu_{A \multimap B, B \multimap C}} & !(A \multimap B) \otimes !(B \multimap C) \\
 \downarrow !\text{comp}_{A,B,C} & & \downarrow n_{A,B} \otimes n_{B,C} \\
 !(A \multimap C) & & !A \multimap !B \otimes !B \multimap !C \\
 \downarrow n_{A,C} & & \downarrow \text{comp}_{!A,!B,!C} \\
 !A \multimap !C & & !A \multimap !C
 \end{array}$$

In more details, positions of $\mu_{A,B}$ are of the form : $(e, (t, \phi, \bar{a}, \psi, \bar{b}), (\Phi, \overline{t', a, b}))$, where, for a position $(\Phi, \overline{t', a, b})$ of $!(A \otimes B)$, one can rebuild the unique associated position by playing the moves in order and building the tensorial schedule and the O-heaps incrementally, the general structure ensuring that we do get them in the end. Consequently $\mu_{A,B}$ is slender and induces a transduction from B to A .

Note that it is not bijective as the play of $!(A \otimes B)$ where we play in B , then backtrack to play in A would produce the same play in $!A \otimes !B$ than playing in B then in A without backtracking.

Thus, we have, since $\mu_{\{\sigma \mid A \multimap B\}, \{\tau \mid B \multimap C\}}$ is slender :

$$\text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \text{supp}_{\#^s(\sigma \otimes \tau)}) \cong \text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \text{supp}_{\#^s(\sigma \otimes \tau)} \circ \mu_{\{\sigma \mid A \multimap B\}, \{\tau \mid B \multimap C\}})$$

Then, by naturality,

$$\text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \text{supp}_{\#^s(\sigma \otimes \tau)}) \cong \text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \mu_{A \multimap B, B \multimap C} \circ \text{supp}_{\#^s \sigma \otimes \#^s \tau})$$

Consequently,

$$\text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \text{supp}_{!(\sigma \otimes \tau)}) \cong \text{image}(\text{comp}_{!A, !B, !C} \circ n_{A,B} \otimes n_{B,C} \circ !\text{supp}_{(\sigma)} \otimes !\text{supp}_{(\tau)})$$

if and only if

$$\text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \mu_{A \multimap B, B \multimap C} \circ \text{supp}_{!(\sigma \otimes \tau)}) \cong \text{image}(\text{comp}_{!A, !B, !C} \circ n_{A,B} \otimes n_{B,C} \circ !\text{supp}_{(\sigma)} \otimes !\text{supp}_{(\tau)})$$

meaning if and only if

$$\text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \mu_{A \multimap B, B \multimap C}) \cong \text{image}(\text{comp}_{!A, !B, !C} \circ n_{A,B} \otimes n_{B,C})$$

An important remark is that $\mu_{A \multimap B, B \multimap C}$ transfers plays p of $(!(A \multimap B) \otimes !(B \multimap C))$ such that there exists $(e, (\phi, \bar{a}), (\psi, \bar{c}))_p \in \text{image}(\text{comp}_{!A, !B, !C} \circ n_{A,B} \otimes n_{B,C})$ to plays p' of $(!(A \multimap B \otimes B \multimap C))$ such that there exists $(e, (\phi, \bar{a}), (\psi, \bar{c}))'_p \in \text{image}(n_{A,C} \circ !\text{comp}_{A,B,C})$.

In other words μ , when restricted to plays that play a role in the images we outlined, acts as a function from the set of plays of $(!(A \multimap B) \otimes !(B \multimap C))$ to the set of plays of $(!(A \multimap B \otimes B \multimap C))$. This can be proved by looking at the respective structures of the plays and induces one half of the isomorphism we need.

We do a similar study by introducing a P -strategy of $(!(A \multimap B \otimes B \multimap C) \multimap (!(A \multimap B) \otimes !(B \multimap C)))$ that acts as a converse of $\mu_{A \multimap B, B \multimap C}$ for such plays and thus get a converse to our morphism, which will give us the second half of the isomorphism we need. Here is how we proceed :

Let $(t, (\phi, \overline{e, a, b}), (\psi, \overline{f, b, c}))$ be a play of $(!(A \multimap B) \otimes !(B \multimap C))$ such that there exists

$$(e_{!A \multimap !C}, (\phi_{!A}, \bar{a}), (\phi_{!C}, \bar{c}))_{e, (t, \phi, \overline{e, a, b}, \psi, \overline{f, b, c})} \in \text{image}(\text{comp}_{!A, !B, !C} \circ n_{A,B} \otimes n_{B,C}).$$

In particular, that implies that, since $n_{A,B} \otimes n_{B,C}$ doesn't change the order of moves, the sequence of moves of $(t, (\phi, \overline{e, a, b}), (\psi, \overline{f, b, c}))$ must be able to be the left projection of $\text{comp}_{!A, !B, !C}$. This restricts the way the moves can be played.

In particular, B moves from the two components must answer each other right away, giving sequences without backtrack of the form $c(b_r . b_l . b_l . b_r) * c$, with similar structures for sequences starting and/or finishing with a A move. In addition, there cannot be any backtrack in A or any of the two B component that would not be initiated by a backtrack in a C component.

The idea is that a backtrack in C induces a backtrack in B which is mirrored on the left component and induces a backtrack in A . Those backtracks give us a heap

structure and the moves inside a sequence follow a proper tensor schedule, so it can be seen as a play of $!(A \multimap B \otimes B \multimap C)$ and it is easy to verify that this play would produce an element of $\text{image}(n_{A,C} \circ !\text{comp}_{A,B,C} \circ \mu_{A \multimap B, B \multimap C})$ and that the P -strategy of $!(A \multimap B \otimes B \multimap C) \multimap (!(A \multimap B) \otimes !(B \multimap C))$ built by reorganizing structure without changing order of moves is a converse to $\mu_{A \multimap B, B \multimap C}$.

Consequently, we have the bijection of images we needed and thus an isomorphic simulation between $!_{\mathcal{P}}(\tau \circ \sigma)$ and $!_{\mathcal{P}}(\tau) \circ !_{\mathcal{P}}(\sigma)$. It is natural since μ and the isomorphisms involved in the manipulation of images are natural.

The few additional diagrams that must be checked are easy to verify with similar methods, and thus we have that $!_{\mathcal{P}}$ is a pseudofunctor.

K Proof that ! is a pseudocomonad

In the following section, we'll detail the construction of the pseudonatural transformations δ and ϵ and prove their naturality. From those definitions, verifying that ! is a pseudocomonad is easy as the morphism part of the two natural transformations coincides with their definition in the deterministic case, making the diagrams commute instantly. After that, we may do a similar study on d, e to give ! the necessary structure to be a linear exponential modality.

We will handle here the case of δ_σ for a P -strategy $\sigma : A \rightarrow B$. This is, by definition 26, a bijective 2-morphism between $!_{\mathcal{P}}!_{\mathcal{P}}\sigma \circ \delta_A$ and $\delta_B \circ !_{\mathcal{P}}\sigma$, both being P -strategies of $!A \multimap !!B$.

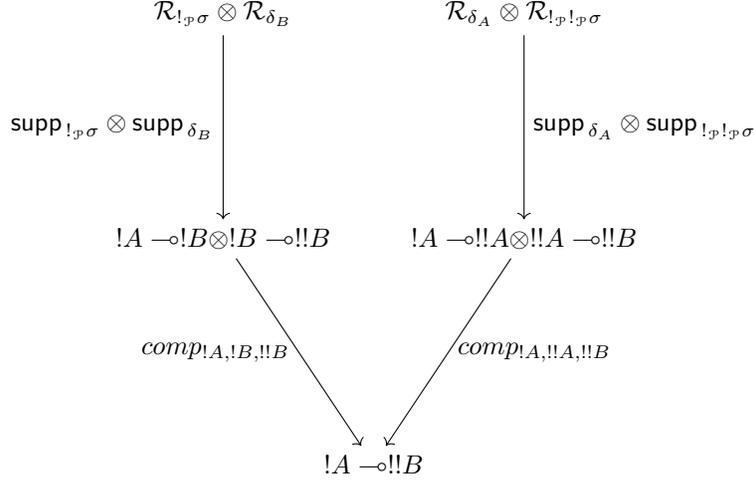
First note that

$$!_{\mathcal{P}}!_{\mathcal{P}}\sigma \circ \delta_A = \text{image}(\text{comp}_{!A, !!A, !!B} \circ \text{supp}_{!_{\mathcal{P}}!_{\mathcal{P}}\sigma} \otimes \text{supp}_{\delta_A})$$

and that

$$\delta_B \circ !_{\mathcal{P}}\sigma = \text{image}(\text{comp}_{!A, !B, !!B} \circ \text{supp}_{\delta_B} \otimes \text{supp}_{!_{\mathcal{P}}\sigma}).$$

We want to study the structure of both images to find an isomorphic simulation between them.



What we will do is start from a position

$$e, (\phi_A, \bar{a}), (\psi_B, \phi_B, \bar{b})$$

of $!A \multimap !!B$ and go back along the arrows to see what structure the positions that produce this position must have.

First, on the left branch, the presence of $\text{comp}_{!A,!B,!!B}$ indicates that the position in $!A \multimap !B \otimes !B \multimap !!B$ must be of the form

$$t, (e_1, (\phi_A, \bar{a}), (\Phi_B, \bar{b}'), (e_2, (\Phi_B, \bar{b}'), (\psi_B, \phi_B, \bar{b})))$$

for some $t, e_1, e_2, \Phi_B, \bar{b}'$ such that $e_1 \cdot e_2 = e$.

Since the right component of this position comes from δ_B , we actually have $\bar{b}' = \bar{b}$, $\Phi_B = \phi_B$, $e_2 = c$ and thus $e_1 = e$ and we actually have the position

$$t, (e, (\phi_A, \bar{a}), (\phi_B, \bar{b}), (c, (\phi_B, \bar{b}), (\psi_B, \phi_B, \bar{b})))$$

for some t which is fixed by the two components for the composition to work.

And thus, this gives us the following position of $\mathcal{R}_{!_p\sigma} \otimes \mathcal{R}_{\delta_B}$:

$$(t, ((\phi_A, e, \pi), \bar{x}), (c, (\phi_B, \bar{b}), (\psi_B, \phi_B, \bar{b})))$$

where \bar{x} is a sequence of moves that gets projected to the sequence of moves of $(e, (\phi_A, \bar{a}), (\phi_B, \bar{b}))$. There is no modification of the order the moves are played in this step, just a reorganization of the structure.

Thus a position of $\mathcal{R}_{\delta_B \circ !_p\sigma}$ is of the form

$$(e, (\phi_A, \bar{a}), (\psi_B, \phi_B, \bar{b}))_{(t, ((\phi_A, e, \pi), \bar{x}), (c, (\phi_B, \bar{b}), (\psi_B, \phi_B, \bar{b})))}$$

We apply a similar reasoning to the right branch to obtain the form of a position of $\mathcal{R}_{!_P!_P\sigma\delta_A}$:

$$(e, (\phi_A, \bar{a}), (\psi_B, \phi_B, \bar{b}))_{(t', (c, (\phi_A, \bar{a}), (e*\psi_B, \phi_A, \bar{a})), ((e*\psi_B, e, \pi), (\phi_A, e, \pi), \bar{x}'))}$$

where t' is fixed by the composition and the sequence of moves \bar{x}' gets projected to the same sequence of moves than \bar{x} in the left branch. In particular, both sequences have the same length.

Since everything is fixed from the initial position $(e, (\phi_A, \bar{a}), (\psi_B, \phi_B, \bar{b}))$ but the two sequences \bar{x} and \bar{x}' , we can then build δ_σ as the simulation sending one position to the other one sharing that same initial structure and the same sequence \bar{x} .

With a similar study, we build ϵ_σ as the simulation that sends positions of the form

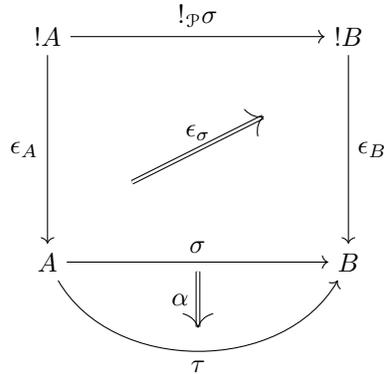
$$(e, (\pi, \bar{a}), b)_{t, (c, (\pi, \bar{a}), a), x)}$$

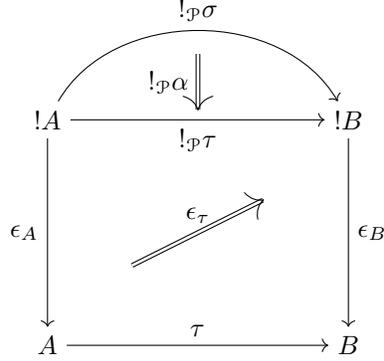
to positions of the form

$$(e, (\pi, \bar{a}), b)_{t', (\pi, \bar{x}), (c, (\pi, \bar{b}), b)}.$$

where t, t' are fixed by construction and \bar{x} is the branch of positions finishing in x in \mathcal{R}_σ .

Proof. We will now prove the pseudonaturality of ϵ, δ is handled in a similar way. Let us look at the naturality first. Let A, B be two games, σ, τ two P -strategies of $A \multimap B$ and $\alpha : \sigma \rightarrow \tau$ a simulation We require that the two following pasting diagrams are equivalent :





This amounts to the following equality of simulations :

$$(\epsilon_A \triangleleft \alpha) \cdot \epsilon_\sigma^{-1} = \epsilon_\tau^{-1} \cdot (!_P \alpha \triangleright \epsilon_B)$$

where $\triangleleft, \triangleright$ indicate the whiskering that results from the composition of P -strategies and \cdot indicates the vertical composition which is simply the composition of functions. Thus, for a position

$$(e, (\pi, \bar{a}), b)_{t', (\pi, \bar{x}), (c, (\pi, \bar{b}), b)}$$

of $\epsilon_B \circ !_P \sigma$, we have :

$$(\epsilon_A \triangleleft \alpha) \cdot \epsilon_\sigma^{-1} ((e, (\pi, \bar{a}), b)_{t', (\pi, \bar{x}), (c, (\pi, \bar{b}), b)}) = (\epsilon_A \triangleleft \alpha) ((e, (\pi, \bar{a}), b)_{t, (c, (\pi, \bar{a}), a), x}) \text{ by def of } \epsilon_\sigma$$

$$(\epsilon_A \triangleleft \alpha) \cdot \epsilon_\sigma^{-1} ((e, (\pi, \bar{a}), b)_{t', (\pi, \bar{x}), (c, (\pi, \bar{b}), b)}) = (e, (\pi, \bar{a}), b)_{t, (c, (\pi, \bar{a}), a), \alpha(x)} \text{ by def of } \mathcal{P}, \epsilon_A$$

On the other hand,

$$\epsilon_\tau^{-1} \cdot (!_P \alpha \triangleright \epsilon_B) ((e, (\pi, \bar{a}), b)_{t', (\pi, \bar{x}), (c, (\pi, \bar{b}), b)}) = \epsilon_\tau^{-1} ((e, (\pi, \bar{a}), b)_{t', (\pi, \overline{\alpha(x)}), (c, (\pi, \bar{b}), b)}) \text{ by def of } \mathcal{P}, \epsilon_B, !_P$$

$$\epsilon_\tau^{-1} \cdot (!_P \alpha \triangleright \epsilon_B) ((e, (\pi, \bar{a}), b)_{t', (\pi, \bar{x}), (c, (\pi, \bar{b}), b)}) = (e, (\pi, \bar{a}), b)_{t, (c, (\pi, \bar{a}), a), \alpha(x)} \text{ by def of } \epsilon_\tau$$

And thus, we have the equivalence we require. The other diagram equalities we need to verify are done in a similar way.

The key point to remember from this proof and the similar ones that need to be done, is that, while the form of the positions is a bit heavy, the structures that underly them do most of the work for us, making most of the needed verifications very easy, once the positions have been properly described.

We apply those methods to verify that $!$ is indeed a pseudocomonad, to define and verify that d_A, e_A are proper pseudonatural transformations and to check that $!$, along with those transformations, does have the structure of a linear exponential modality.