

# Automata, (semi)groups, dualities

Matthieu Picantin

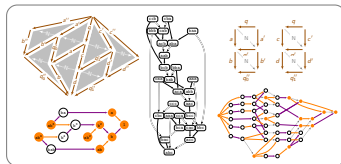
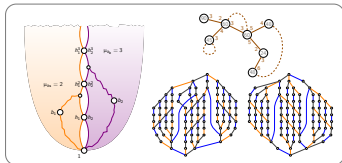
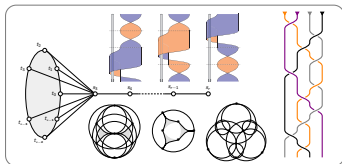
IRIF – UMR 8243 CNRS & Université Paris Diderot



MealyM  
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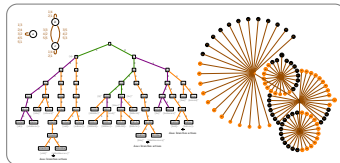
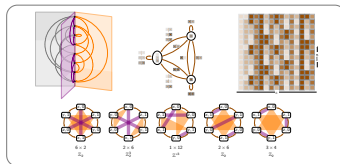
habilitation à diriger des recherches  
amphithéâtre Alan Turing  
10 juillet 2017

## Braid (semi)groups & Garside theory

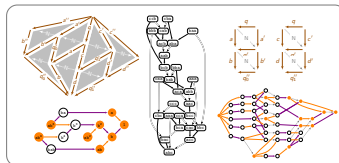
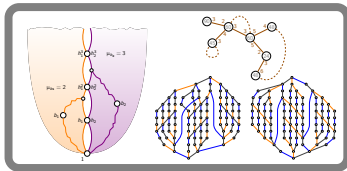
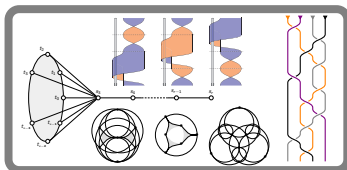


## Quadratic normalisations Thurston vs Mealy automata

## Mealy automata & automaton (semi)groups

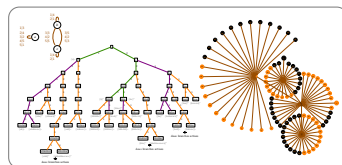
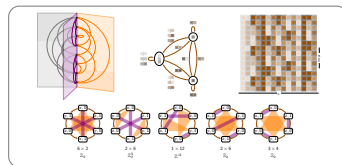


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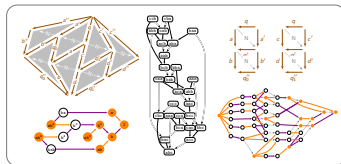
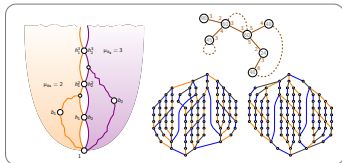
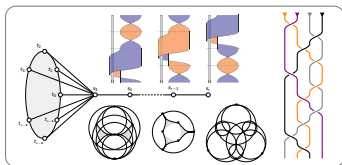


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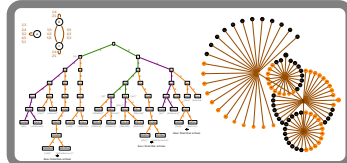
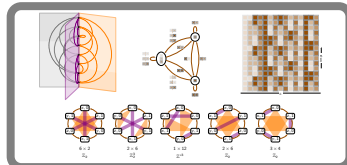


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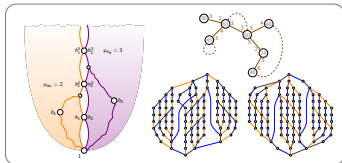
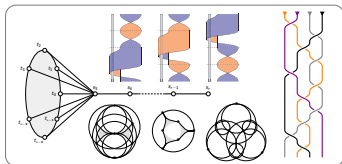


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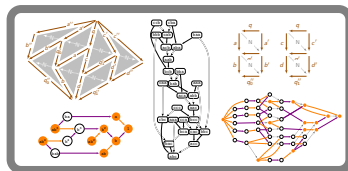
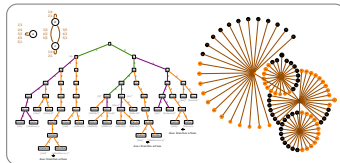
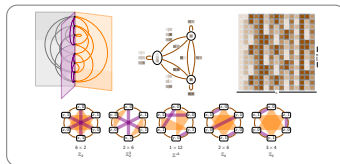
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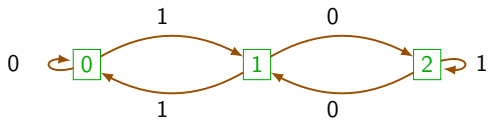
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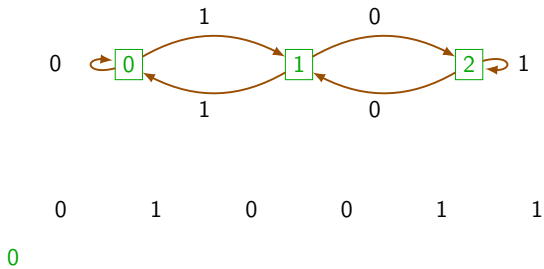


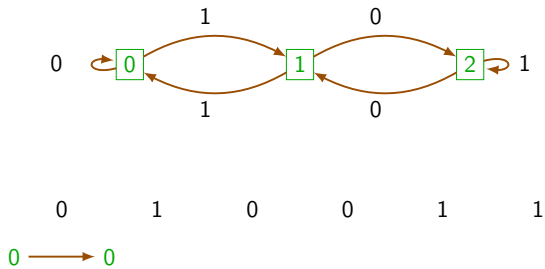
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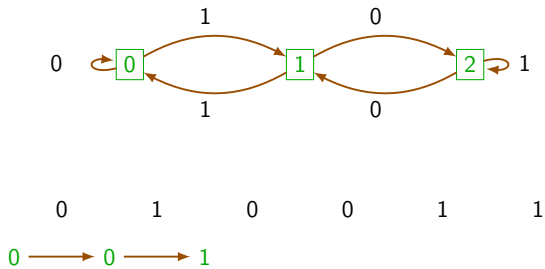
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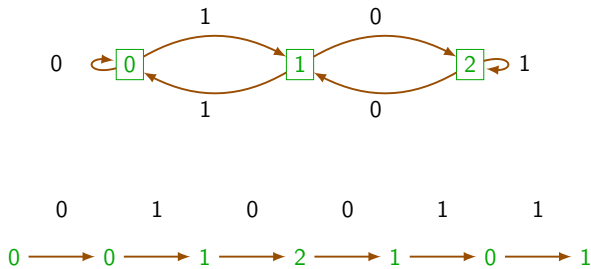


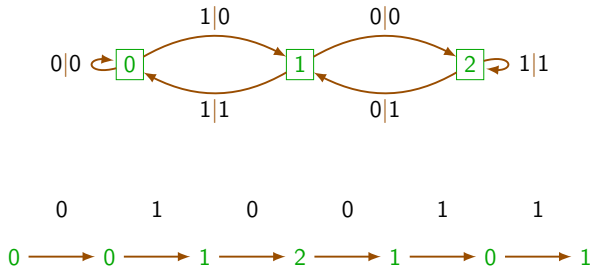


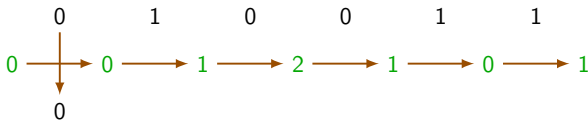
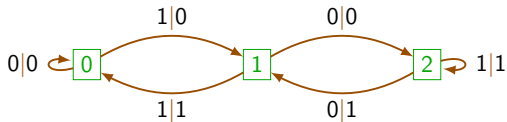


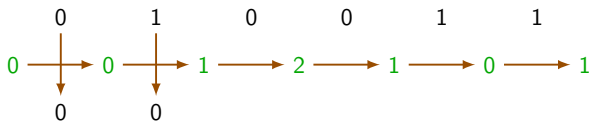
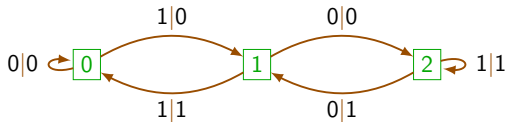


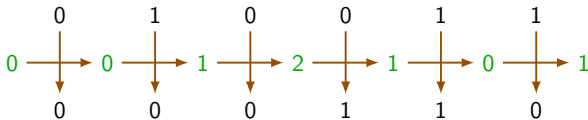
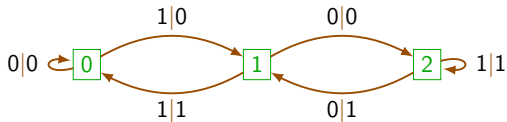


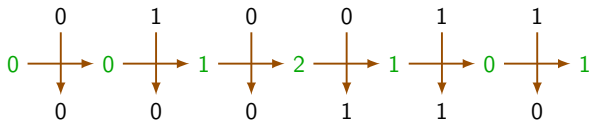
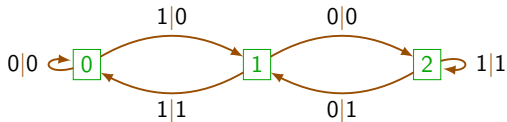




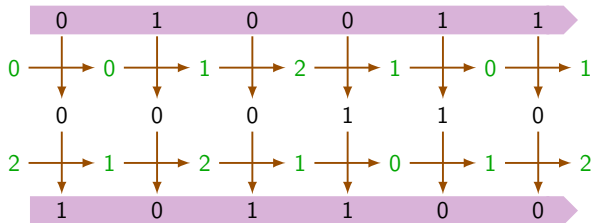
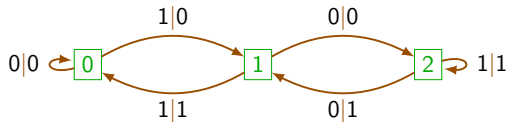




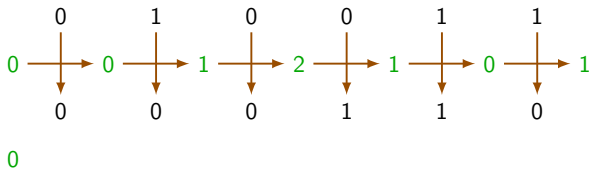
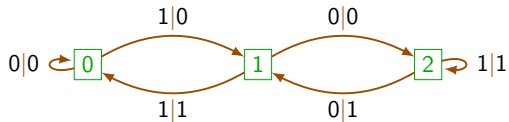


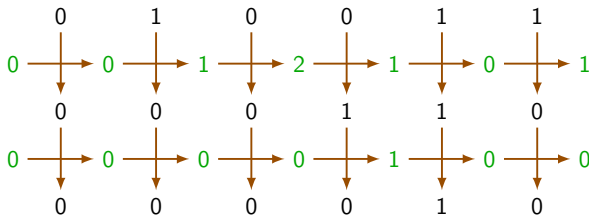
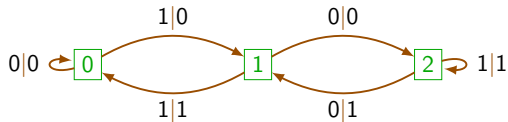


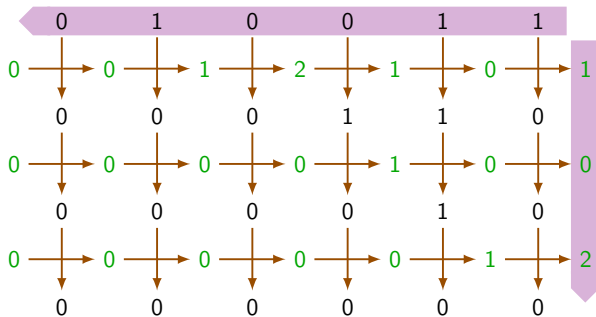
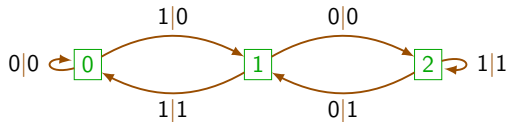
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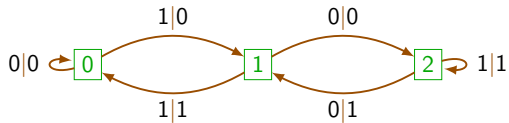








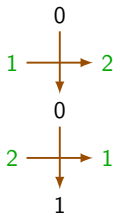
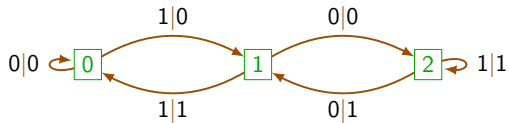


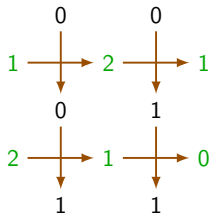
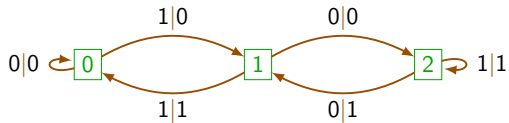


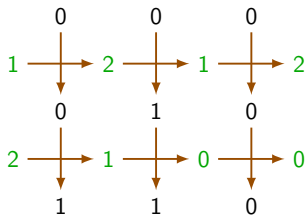
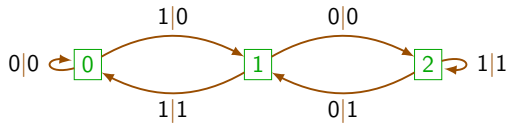
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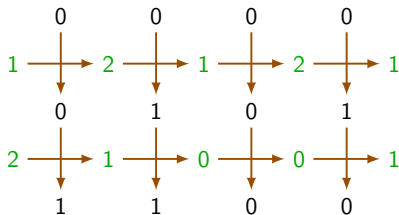
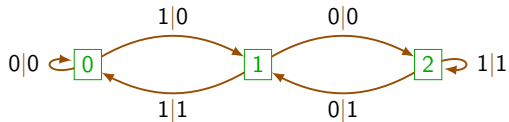
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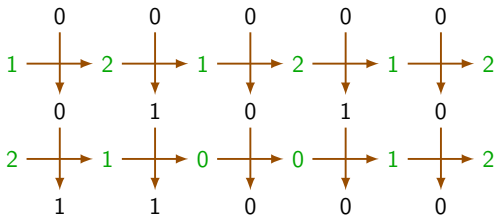
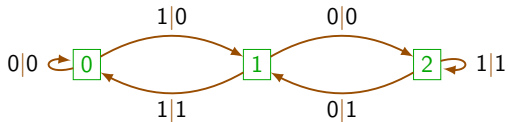


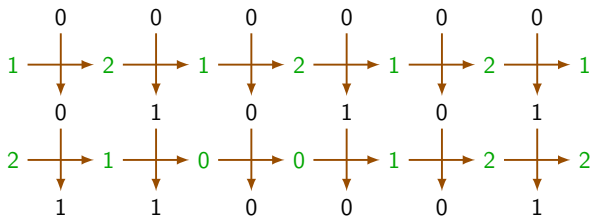
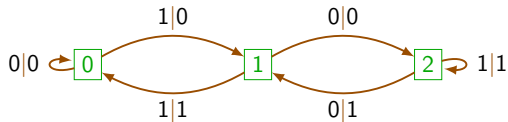


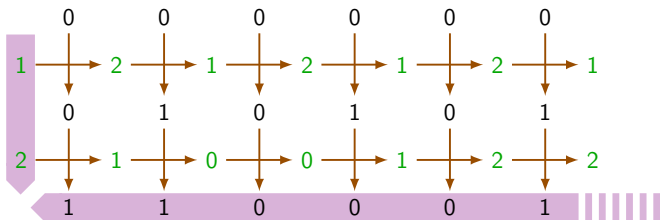
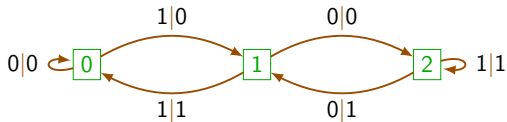


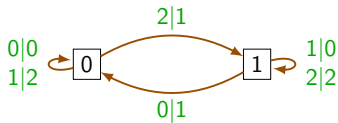
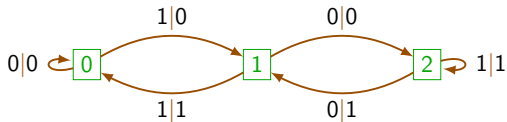




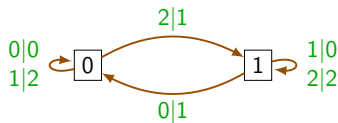
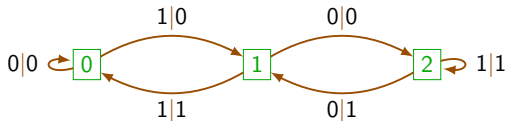




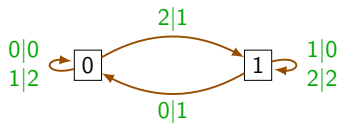
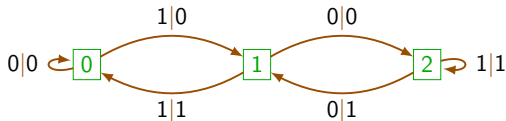




the actions induced by 0, 1, and 2  
generate a rank 3 free semigroup

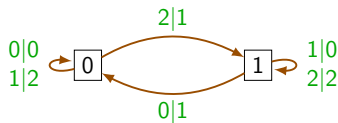
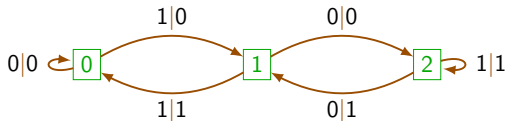


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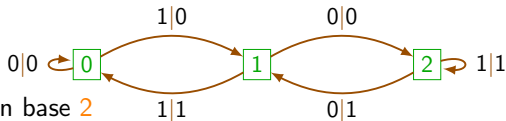
the actions induced by 0 and 1  
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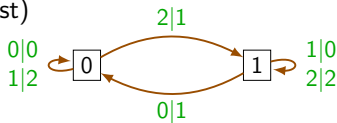
the actions induced by 0 and 1  
generate a rank 2 free semigroup  
and a group isomorphic  
to  $BS(1, 2) = \langle \alpha, \delta : \alpha\delta = \delta\alpha^2 \rangle$

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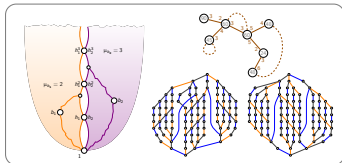
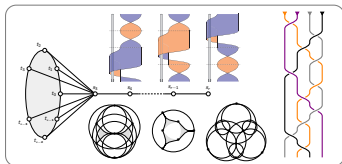
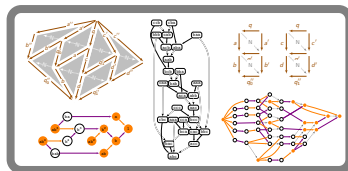
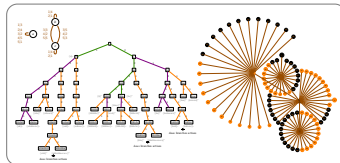
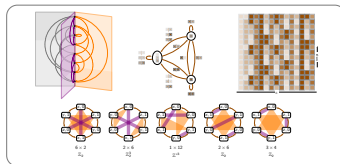
division by 3 in base 2  
(most significant digit first)

multiplication by 2 in base 3  
(less significant digit first)

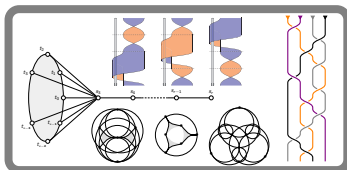


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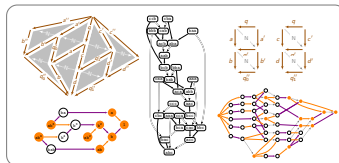
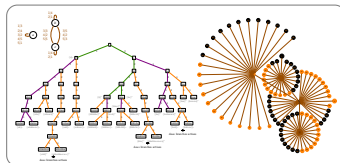
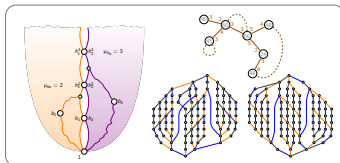
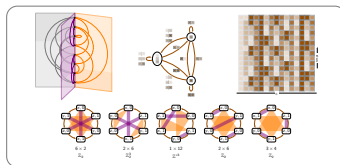


Braid (semi)groups  
& Garside theoryMealy automata  
& automaton (semi)groupsQuadratic normalisations  
Thurston vs Mealy automata

# Braid (semi)groups & Garside theory

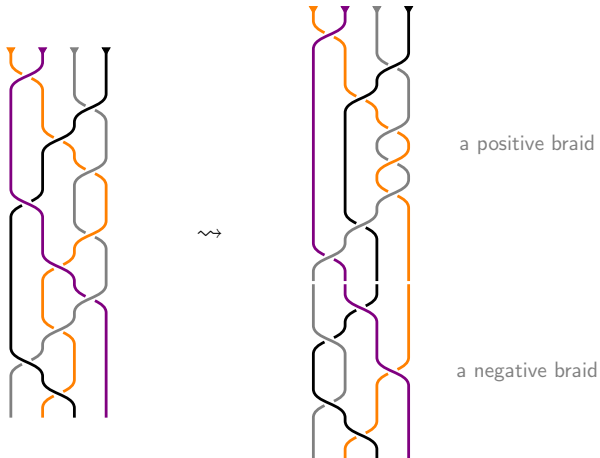


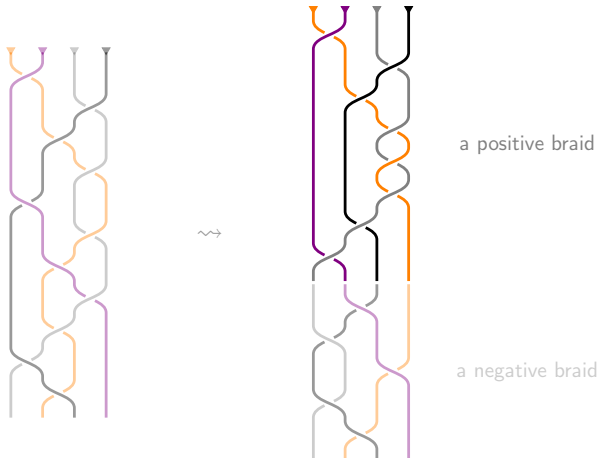
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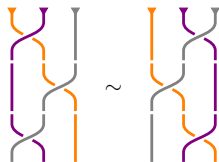


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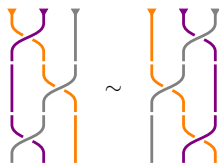








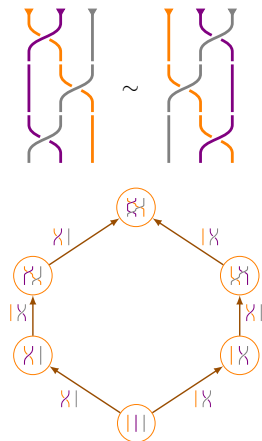
a positive braid



a positive braid

Garside 1965

The braid group  $\mathbf{B}_3$  is the group of **fractions** of the monoid  $\mathbf{B}_{3+}^1 = \langle \sigma_1, \sigma_2 : \sigma_1 \sigma_2 \sigma_1 = \sigma_2 \sigma_1 \sigma_2 \rangle_+^1$ .



a positive braid

Garside 1965


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$$\text{EV} : Q^+ \longrightarrow S$$

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A **normal form** for  $(S, Q)$  is a map NF that assigns to each element of  $S$  a distinguished representative  $Q$ -word.

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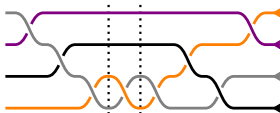
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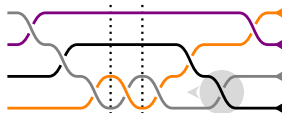
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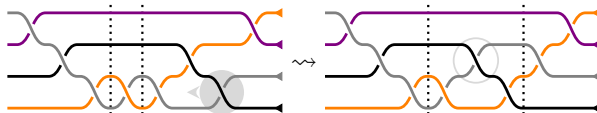
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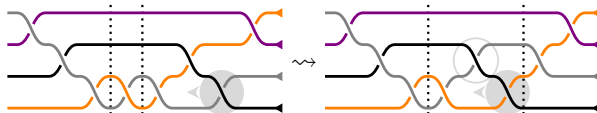
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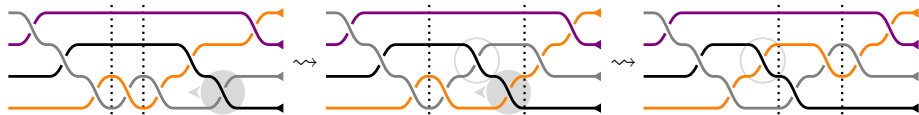


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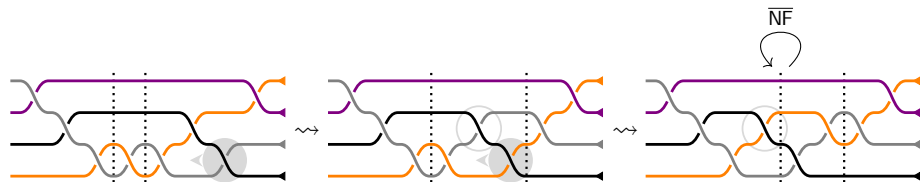
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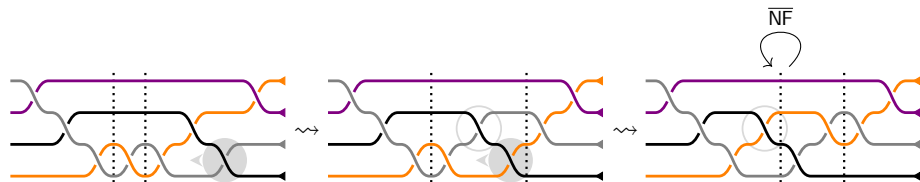
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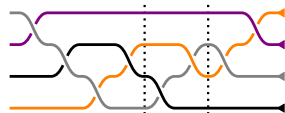
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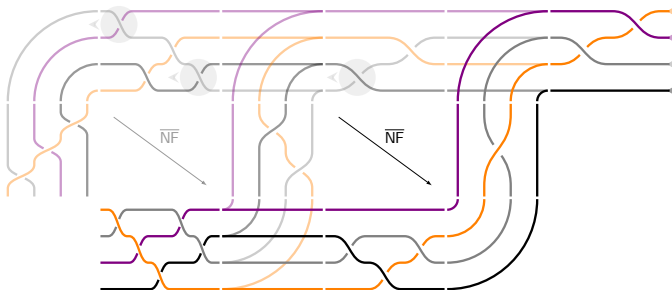
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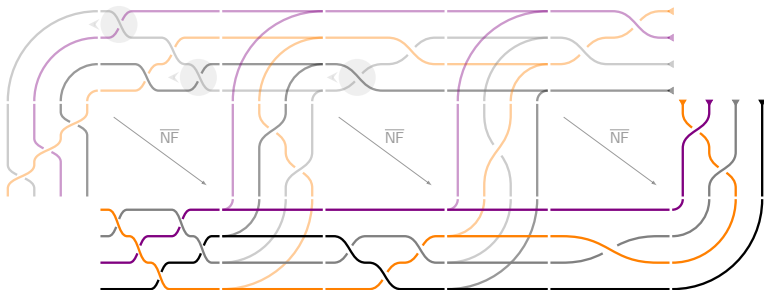


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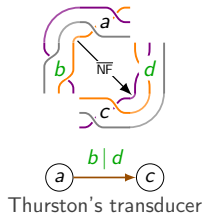
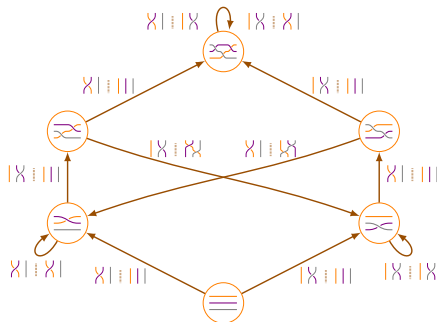
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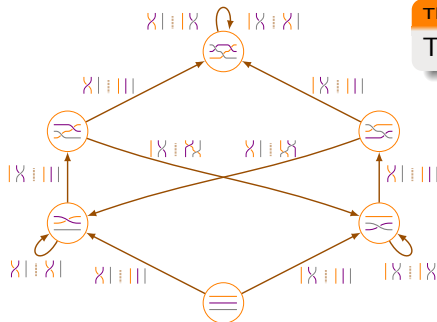
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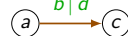
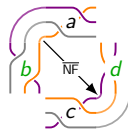
  
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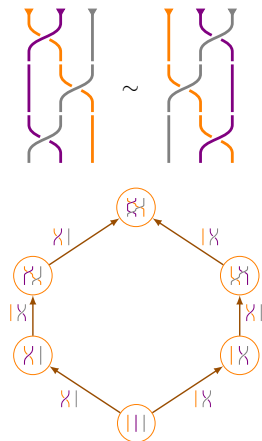
Thurston 1988

The braid groups are automatic.



Thurston's transducer

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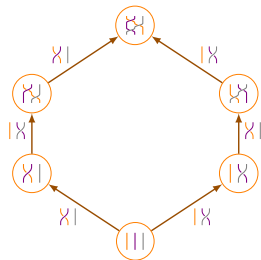
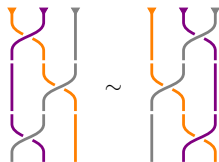


a positive braid

Garside 1965

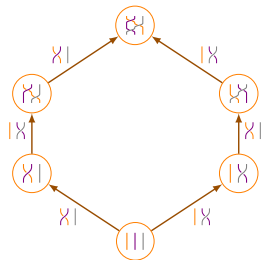
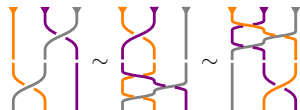
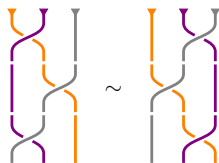
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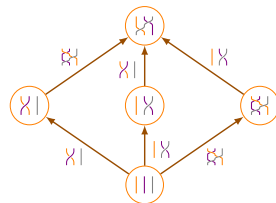
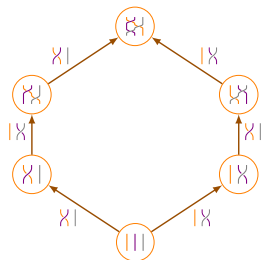
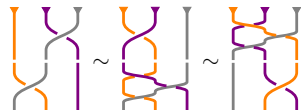
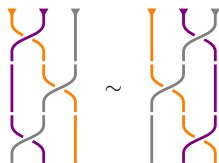
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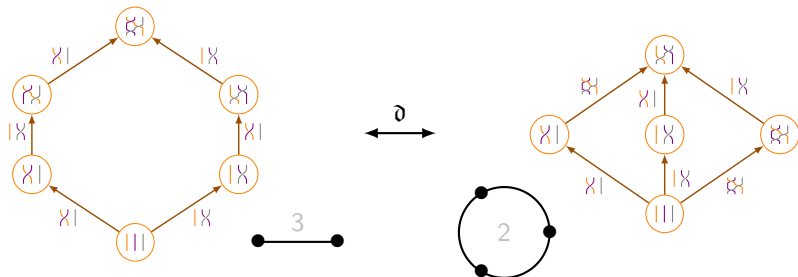
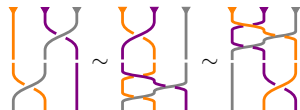
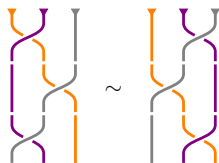
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Garside 1965

Birman Ko Lee 1998

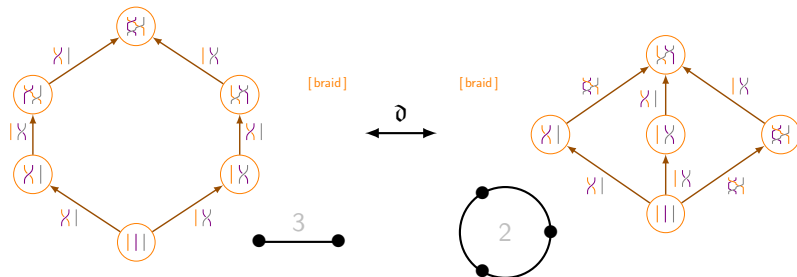
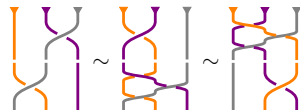
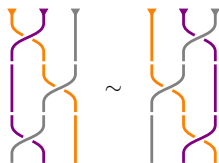
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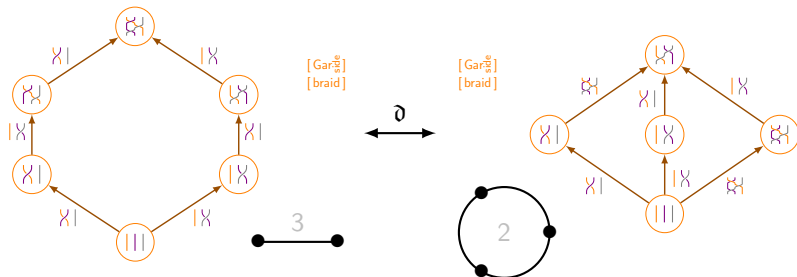
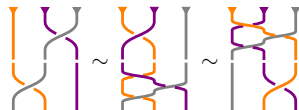
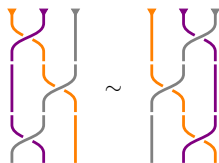
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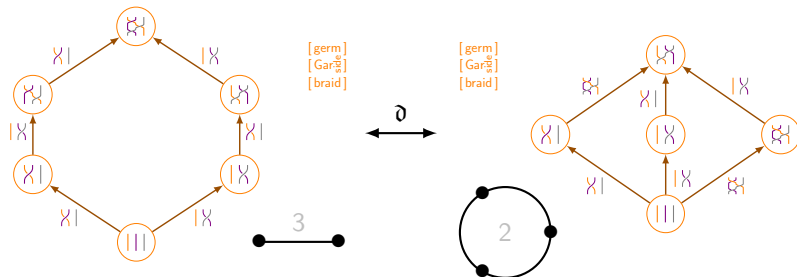
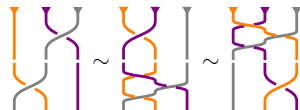
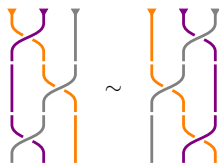
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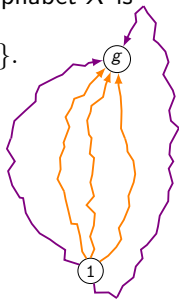
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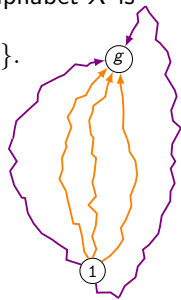
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$$h \preccurlyeq_X g \text{ if and only if } \ell_X(h) + \ell_X(h^{-1}g) = \ell_X(g) .$$



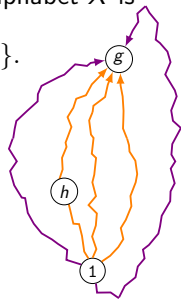
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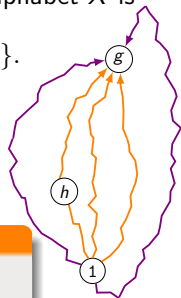
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#### Procedure

- ▷ Start from a finite group  $G$ .
- ▷ Choose a set  $X$  generating  $G$  as a monoid.
- ▷ Build the associated poset  $(G, \preccurlyeq_X)$ .
- ▷ Pick a maximal element  $d$  dominating  $X$ .
- ▷ Extract the monoid presentation  $(X : R_d)$ .

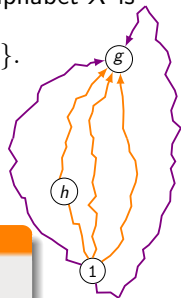
Let  $G$  be a finite group generated as a monoid by a set  $X$ .

The **word length**  $\ell_X(g)$  of an element  $g$  of  $G$  with respect to the alphabet  $X$  is

$$\ell_X(g) = \min\{p \in \mathbb{N} : \exists(x_1, \dots, x_p) \in X^p, g = x_1 \cdots x_p\}.$$

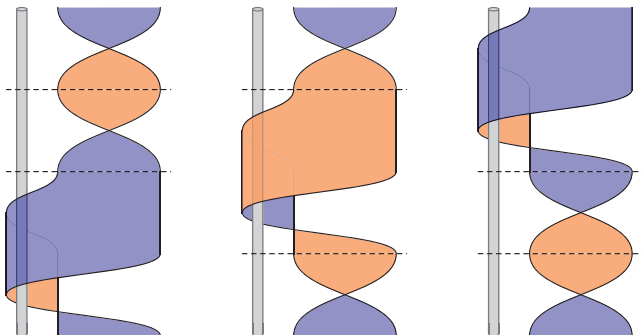
We consider the **associated partial order**  $\preceq_X$  on  $G$ :

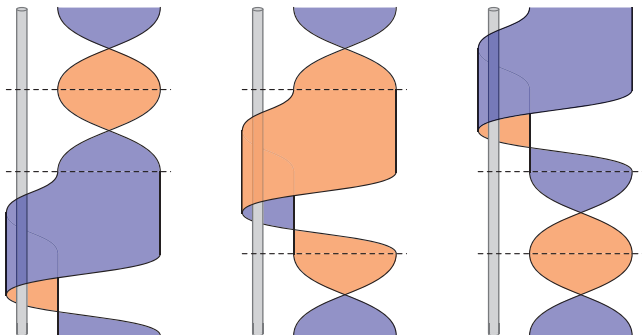
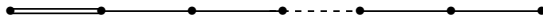
$$h \preceq_X g \text{ if and only if } \ell_X(h) + \ell_X(h^{-1}g) = \ell_X(g).$$



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- ▷ Extract the monoid presentation  $(X : R_d)$ .
- ▷ Check whether or not:
  - [**germ**]  $\langle X : R_d \cup X^{\text{ord}(x)} \rangle$  is isomorphic to  $G$ ;
  - [**Gar:side**]  $\langle X : R_d \rangle_+^1$  is a Garside monoid;
  - [**braid**]  $\langle X : R_d \rangle$  is isomorphic to  $\mathbf{B}(G)$  (if defined).





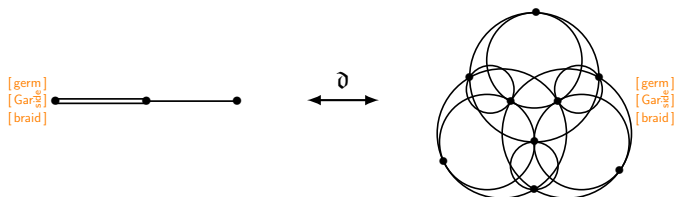


P 2002 Bessis 2003

The dual braid monoid  $\mathbf{B}^\times(B_n)$  admits the presentation

$$\begin{aligned} \langle & \alpha_{ts}, \beta_{ts}, \tau_t : [\alpha_{ts}, \tau_s, \beta_{ts}, \tau_t] \text{ for } t > s, \\ & [\alpha_{ts}, \alpha_{sr}, \alpha_{tr}] , [\beta_{ts}, \alpha_{sr}, \beta_{tr}] , [\alpha_{ts}, \beta_{sr}, \beta_{tr}] \text{ for } t > s > r, \\ & [\alpha_{ts}, \tau_r] , [\tau_t, \alpha_{sr}] , [\beta_{tr}, \tau_s] \text{ for } t > s > r, \\ & [\alpha_{ts}, \alpha_{rq}] , [\alpha_{ts}, \beta_{rq}] , [\beta_{ts}, \alpha_{rq}] , \\ & [\alpha_{tq}, \alpha_{sr}] , [\beta_{tq}, \alpha_{sr}] , [\beta_{tq}, \beta_{sr}] \text{ for } t > s > r > q \rangle_+^1. \end{aligned}$$

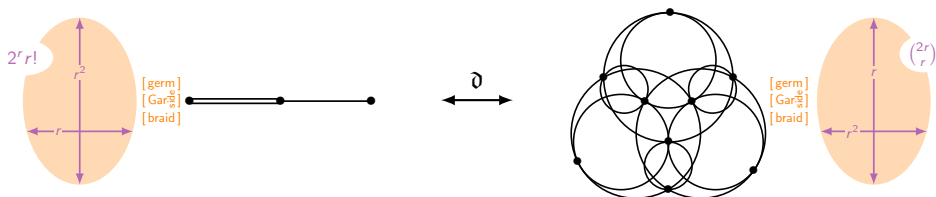




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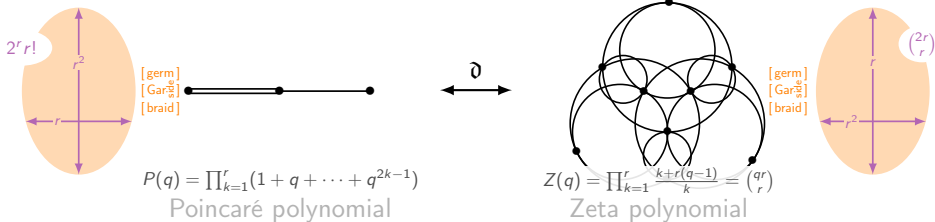
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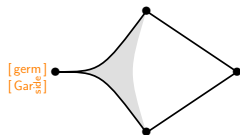
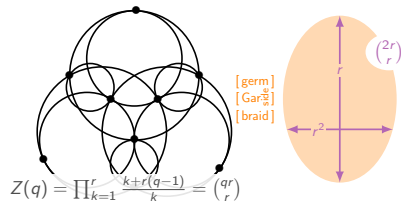
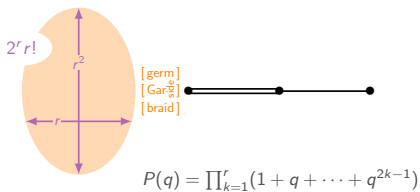


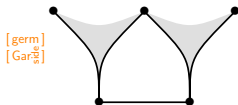
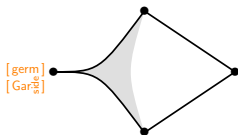
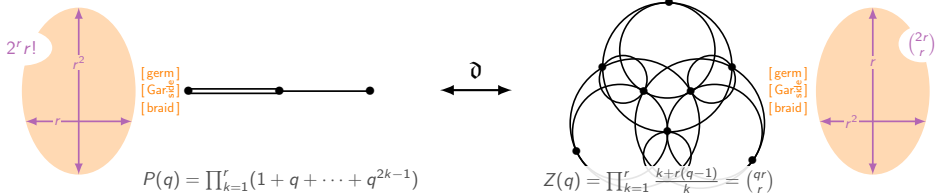
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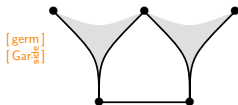
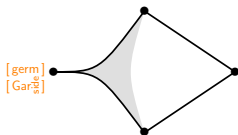
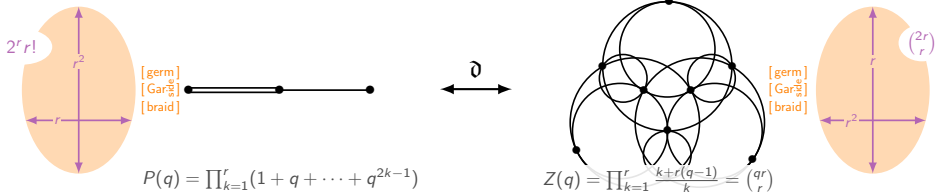
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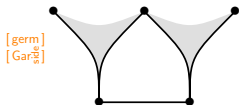
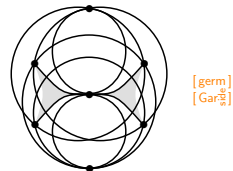
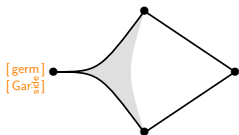
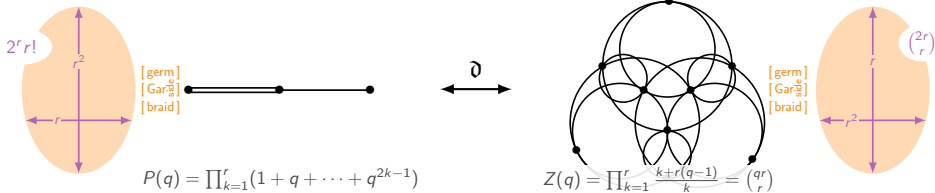
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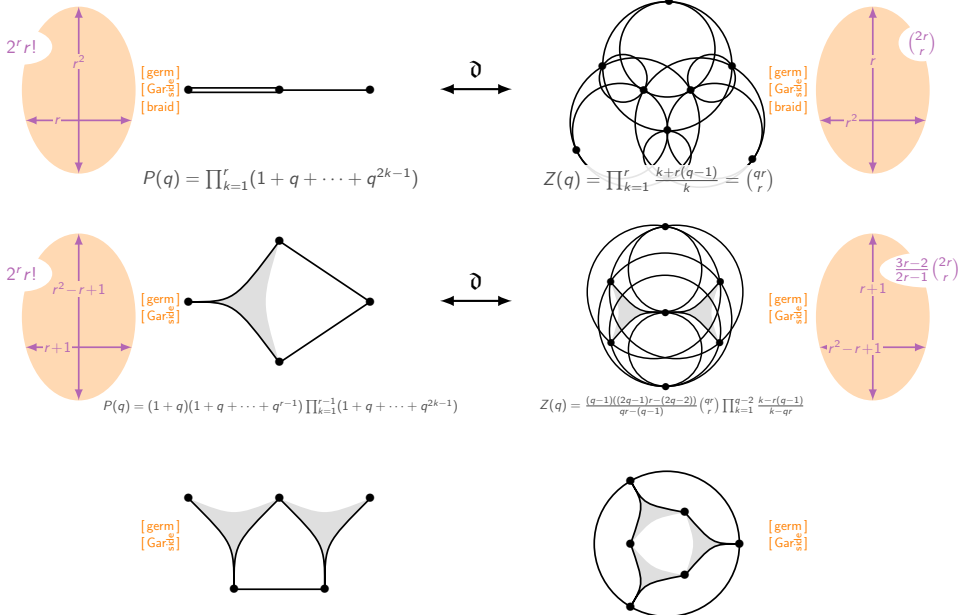




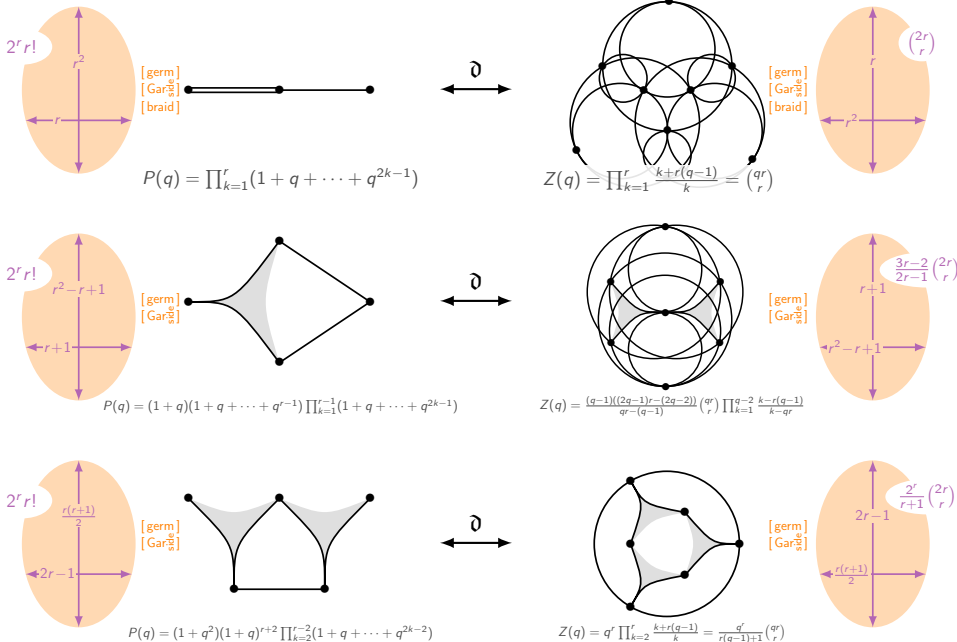








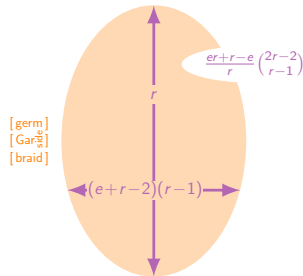




Bessis Corran 2006

The dual braid monoid  $\mathbf{B}^\times(e, e, r)$  satisfies

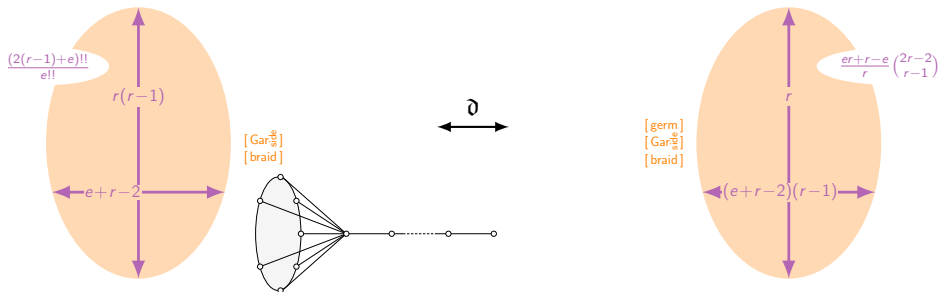
$$Z(q) = \frac{r+e(r-1)(q-1)}{r} \prod_{k=1}^{r-1} \frac{ek+e(r-1)(q-1)}{ek}.$$



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Corran P 2011

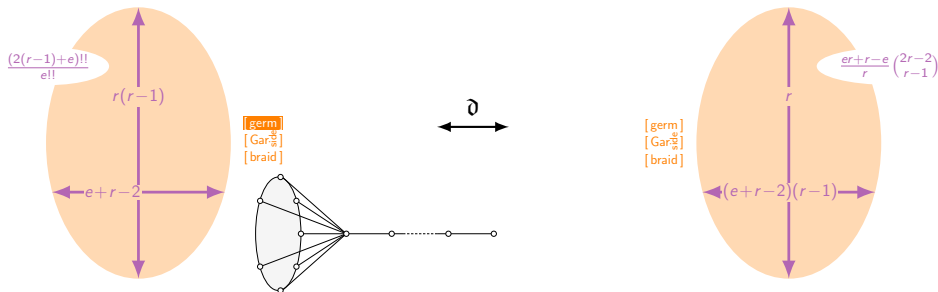
The **post-classical** braid monoid  $\mathbf{B}^\oplus(e, e, r)$  satisfies

$$P(q) = \prod_{k=1}^{r-1} (1 + q + \cdots + q^{k-1} + eq^k + q^{k+1} + \cdots + q^{2k}).$$

Bessis Corran 2006

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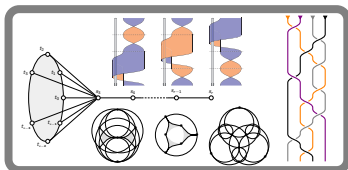
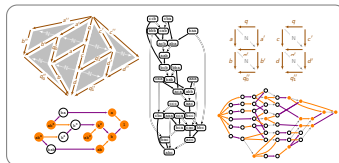
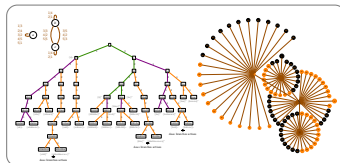
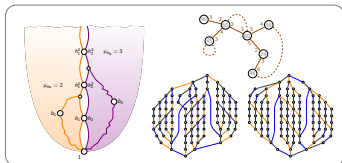
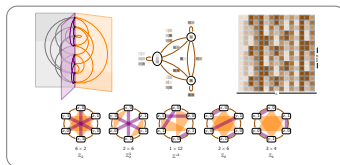
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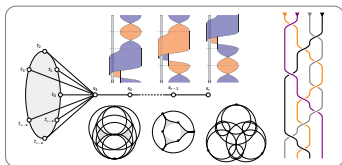
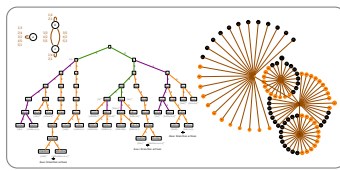
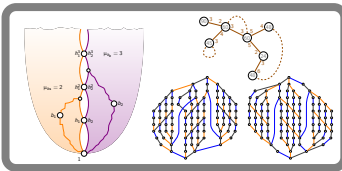
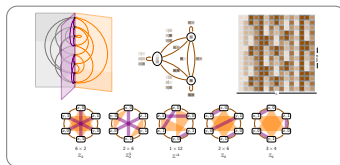
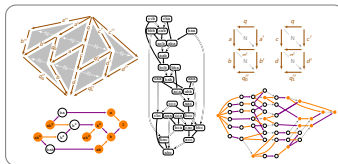


Corran P 2011    Neaime 2017

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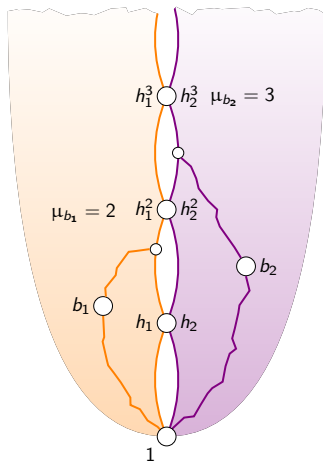
Braid (semi)groups  
& Garside theoryMealy automata  
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Let  $M_1, M_2, H$  be monoids with  $\begin{cases} \phi_1 : H \hookrightarrow M_1, \\ \phi_2 : H \hookrightarrow M_2. \end{cases}$

The amalgamated free product is

$$\langle M_1 \star M_2 : \phi_1(h) = \phi_2(h), h \in H \rangle_+^1.$$



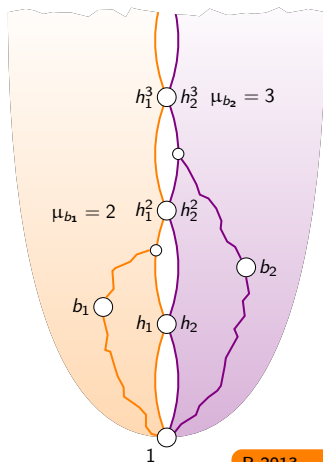
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P 2013

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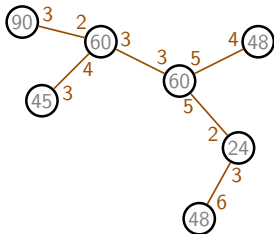
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P 2013

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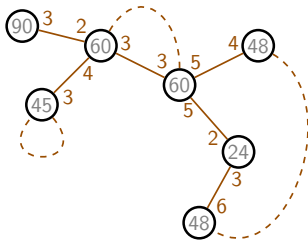
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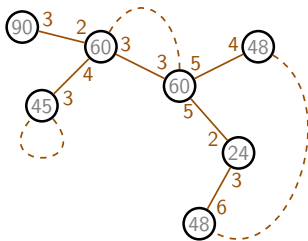
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P 2013

A non-cyclic one-relator group is Garside iff its center is non-trivial.



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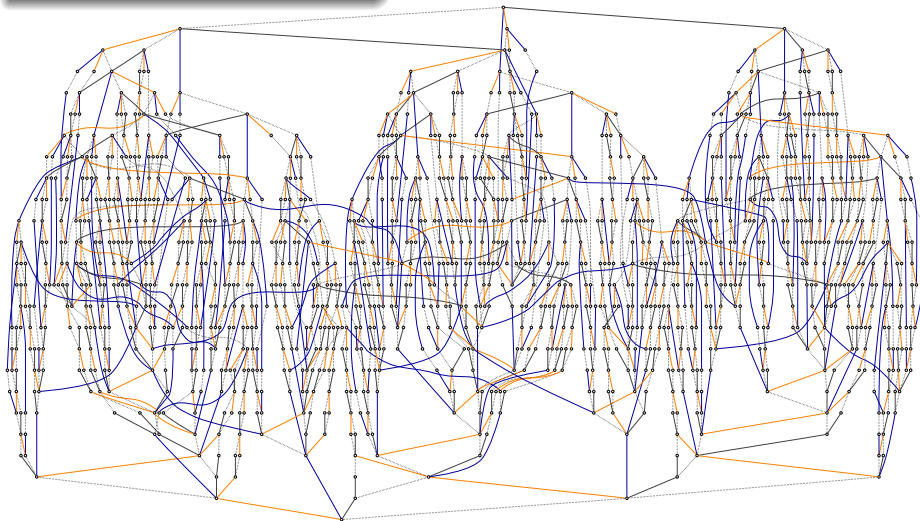
P 2013

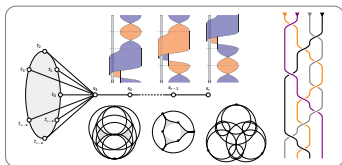
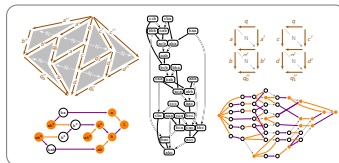
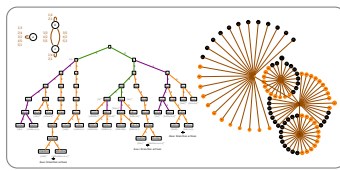
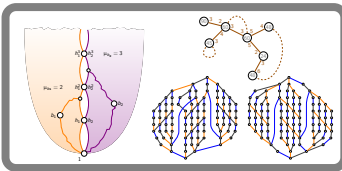
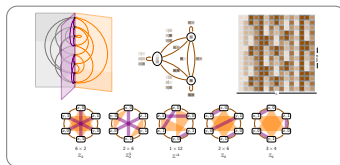
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P 2013

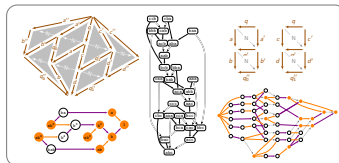
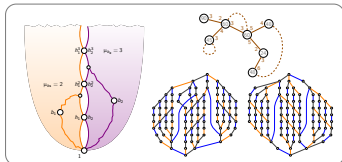
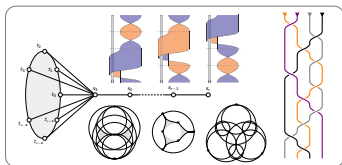
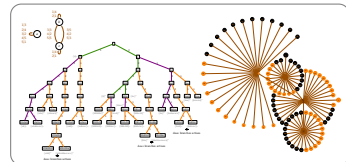
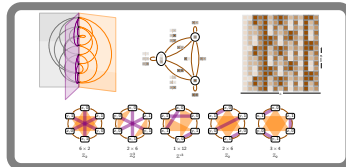
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$$\langle a, x : x^8 a x^{-6} a^{-1} x^4 a x^{-6} a^{-1} \rangle$$



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& automaton (semi)groupsQuadratic normalisations  
Thurston vs Mealy automata

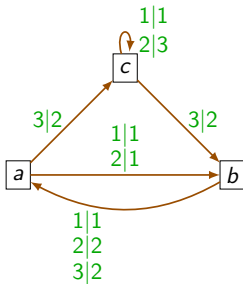


Braid (semi)groups  
& Garside theoryQuadratic normalisations  
Thurston vs Mealy automataMealy automata  
& automaton (semi)groups



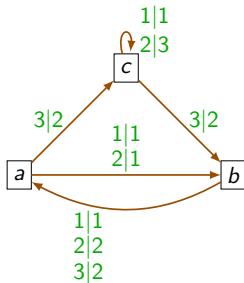
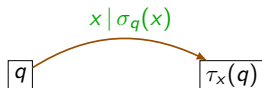
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output

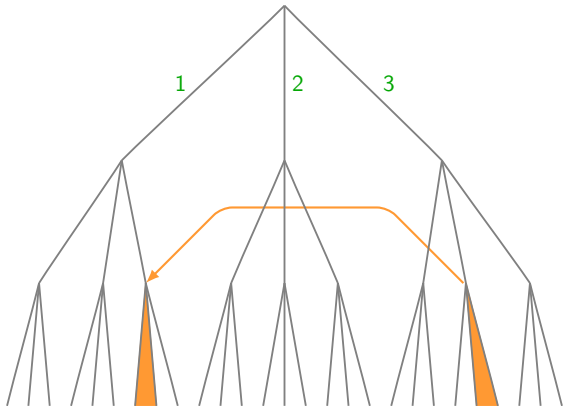
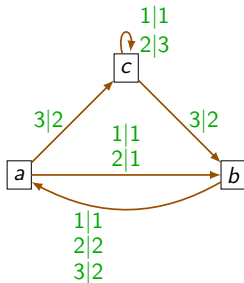
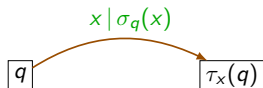


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

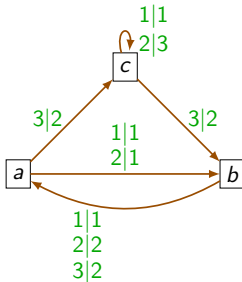
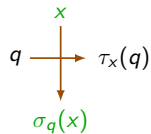
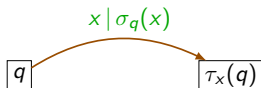


$$\mathcal{M} = (\overset{\text{stateset}}{Q}, \overset{\text{alphabet}}{X}, \overset{\text{transition}}{\tau}, \overset{\text{output}}{\sigma})$$



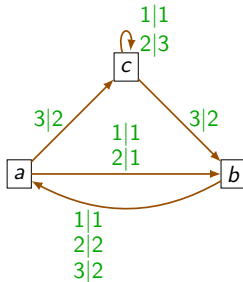
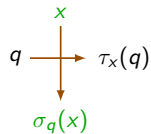
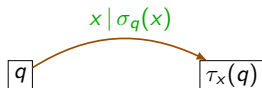
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output



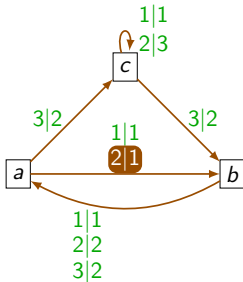
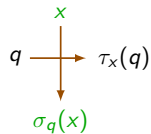
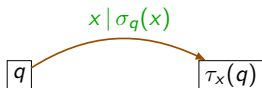
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output



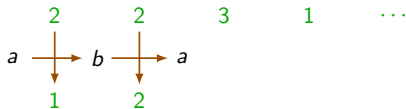
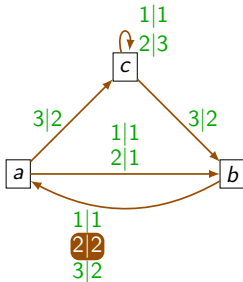
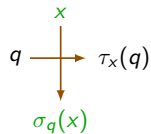
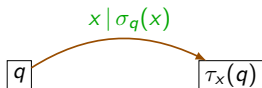
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output



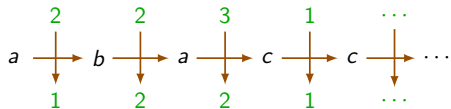
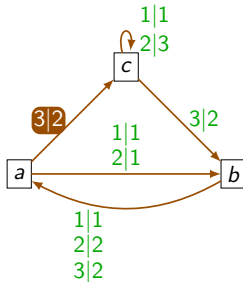
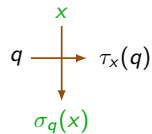
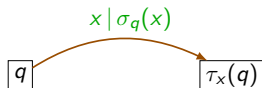
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output



$$\mathcal{M} = (Q, X, \tau, \sigma)$$

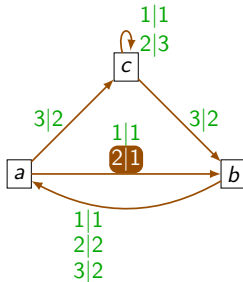
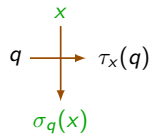
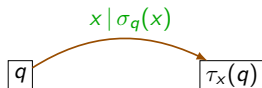
transition  
 alphabet  
 stateset  
 output





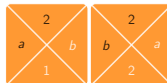
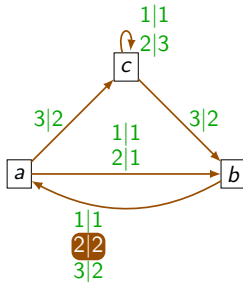
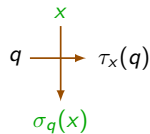
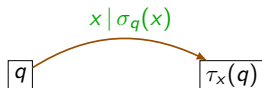
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output



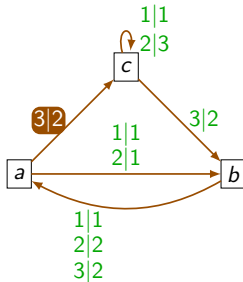
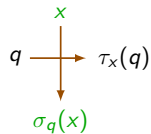
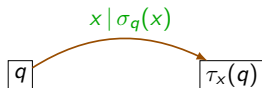
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
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 output



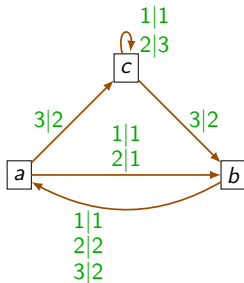
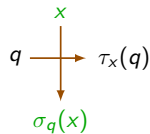
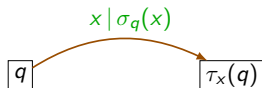
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output



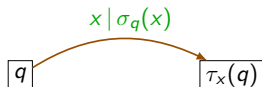
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output

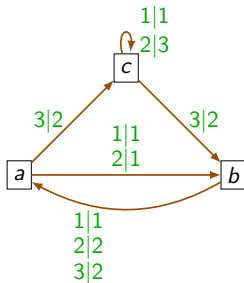
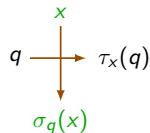


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

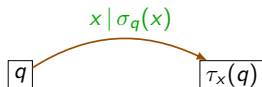


$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$

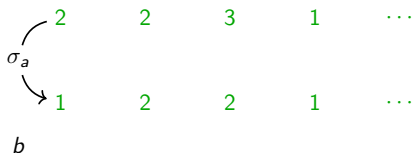
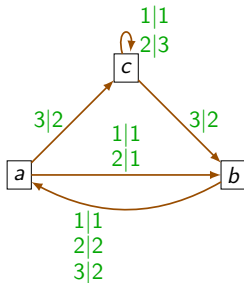
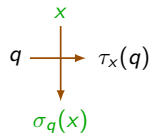


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

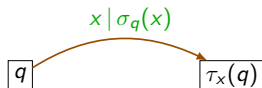


$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$

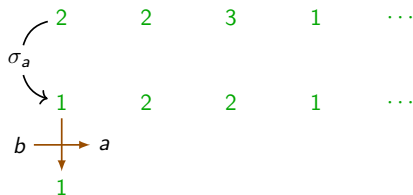
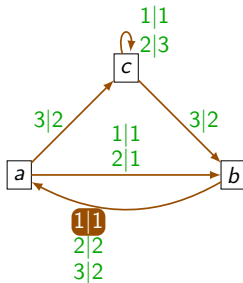
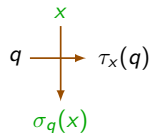


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

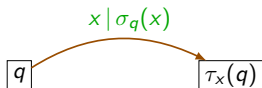


$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$

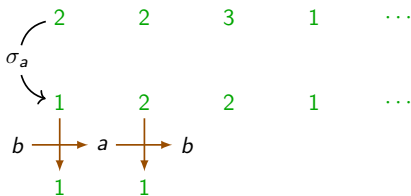
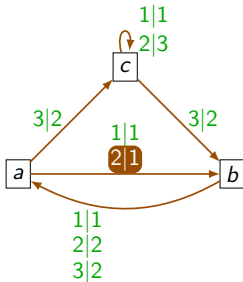
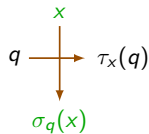


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  $Q$ , alphabet  $X$ , transition  $\tau$ , output  $\sigma$



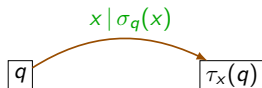
$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$



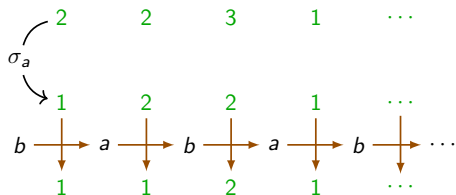
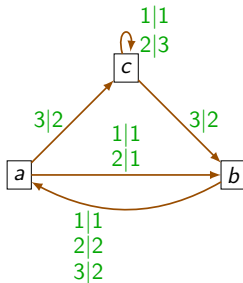
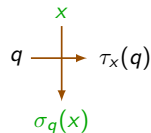


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

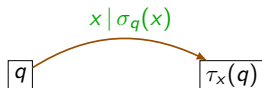


$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$

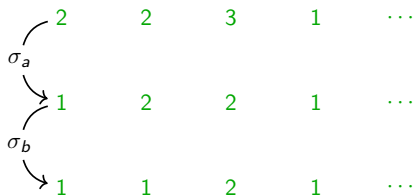
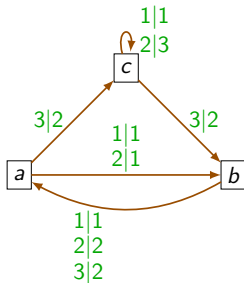
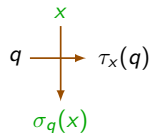


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  $Q$ , alphabet  $X$ , transition  $\tau$ , output  $\sigma$



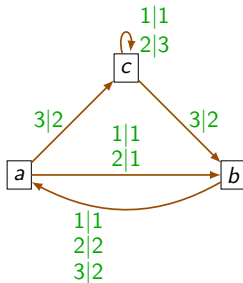
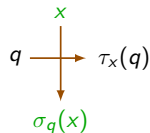
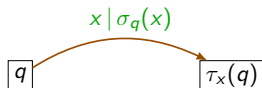
$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$



$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

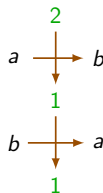
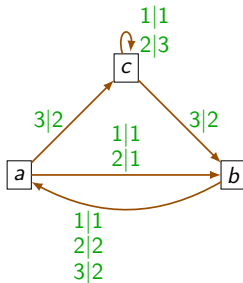
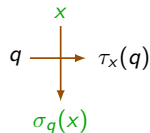
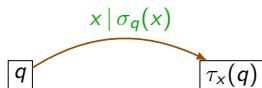
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$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output

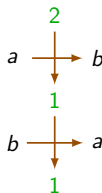
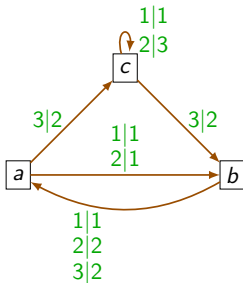
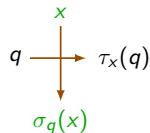
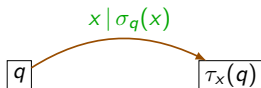
$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$



$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output

$$\langle \mathcal{M} \rangle_+ = \langle \sigma_q, q \in Q \rangle_{X^* \rightarrow X^*}$$

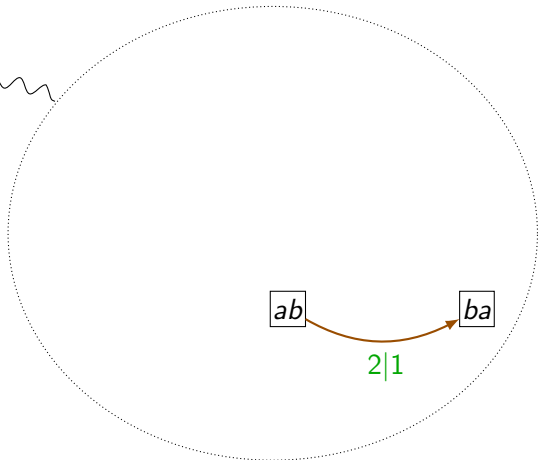
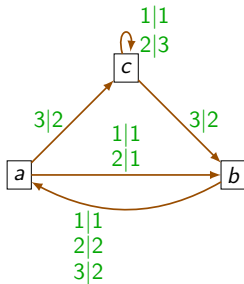


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

stateset  
 alphabet  
 transition  
 output

$$\mathcal{M}^2$$

exponentiation



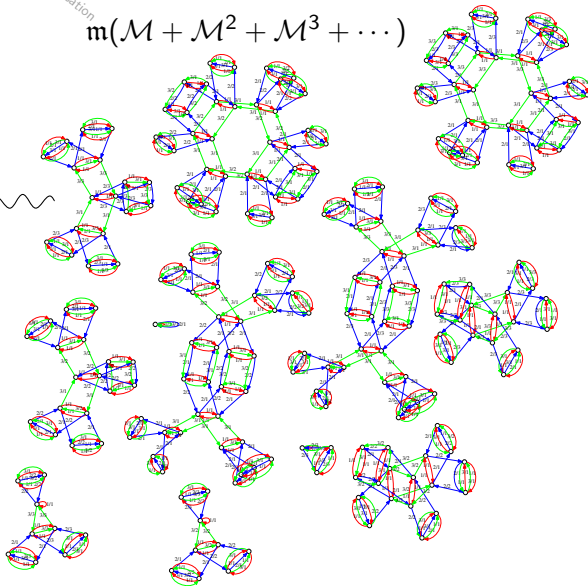
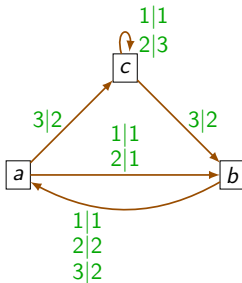
$$\mathcal{M} = (Q, X, \tau, \sigma)$$

transition  
 alphabet  
 stateset  
 output

$$m(\mathcal{M} + \mathcal{M}^2 + \mathcal{M}^3 + \dots)$$

minimisation

completion  
attempt

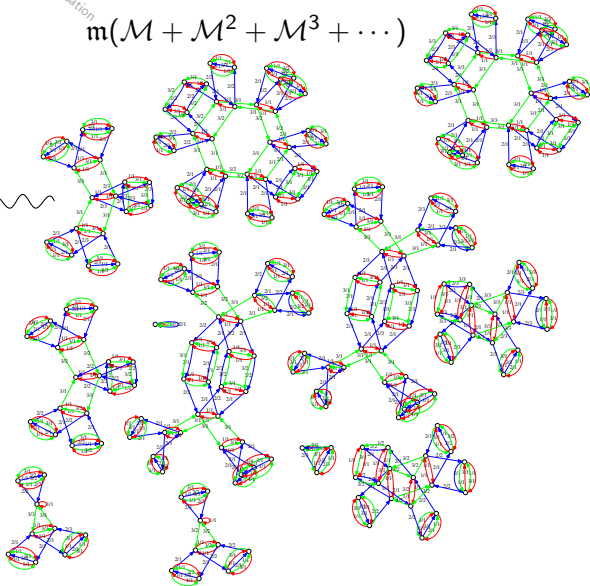
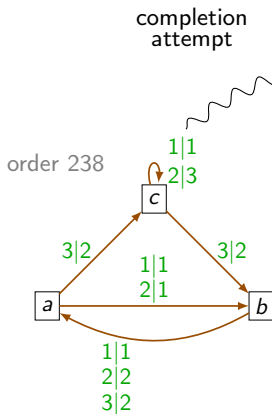


$$\mathcal{M} = (Q, X, \tau, \sigma)$$

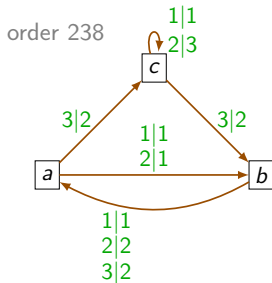
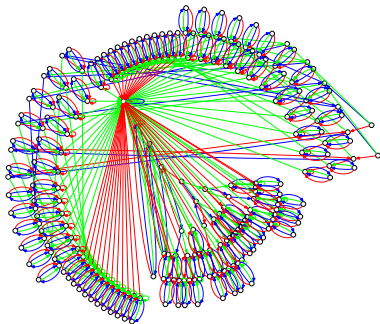
transition  
 alphabet  
 stateset  
 output

$$m(\mathcal{M} + \mathcal{M}^2 + \mathcal{M}^3 + \dots)$$

minimisation

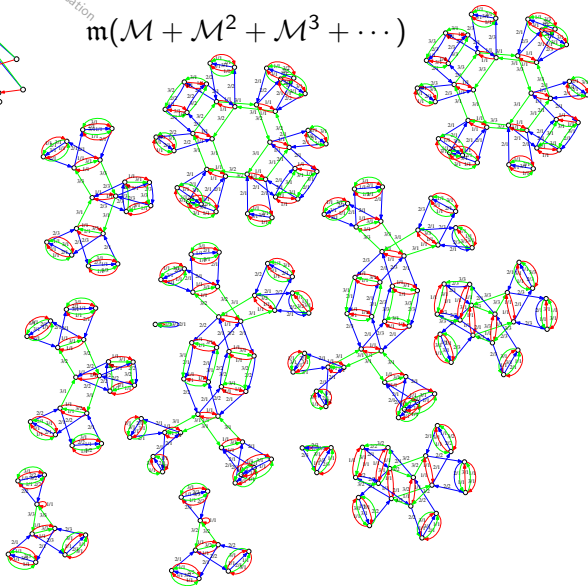


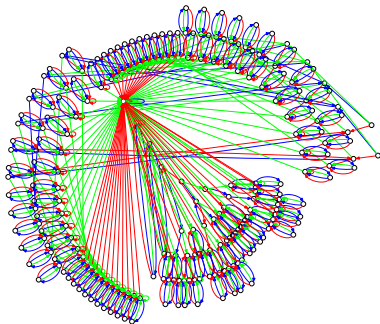




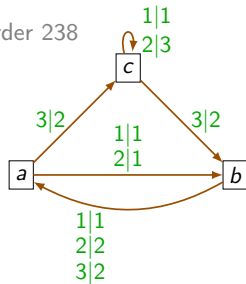
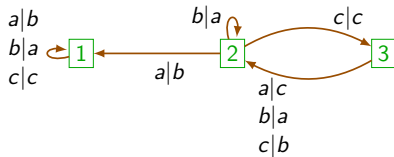
minimisation

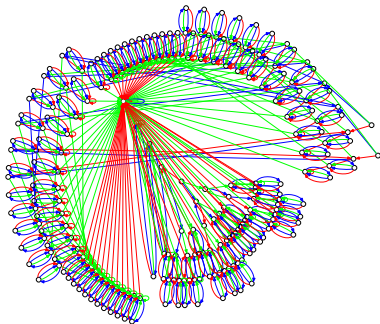
$$m(\mathcal{M} + \mathcal{M}^2 + \mathcal{M}^3 + \dots)$$



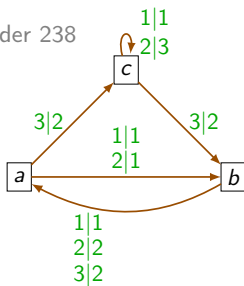


order 238

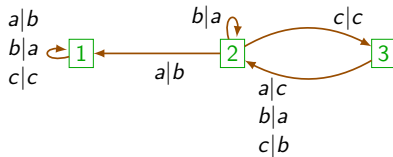
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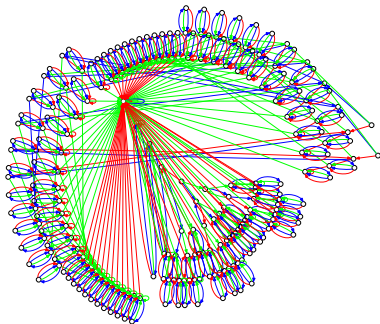


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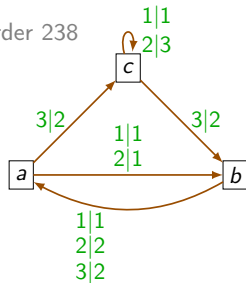
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order ?

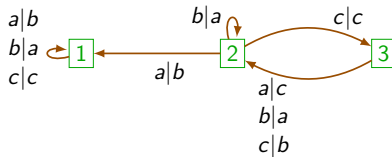


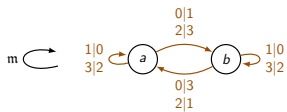


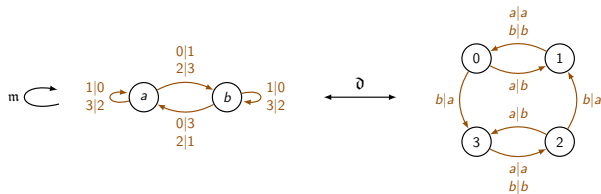
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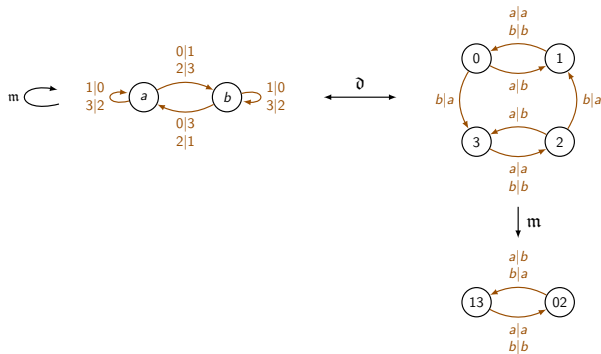
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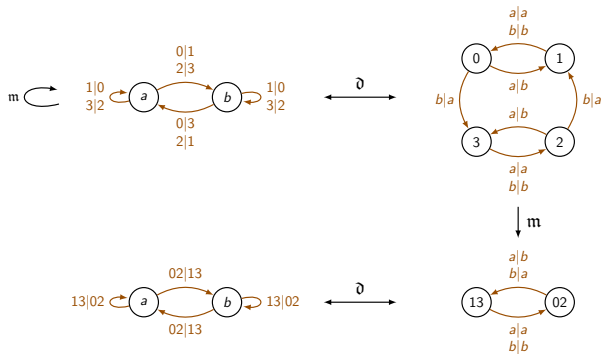
order 1 494 186 269 970 473 680 896



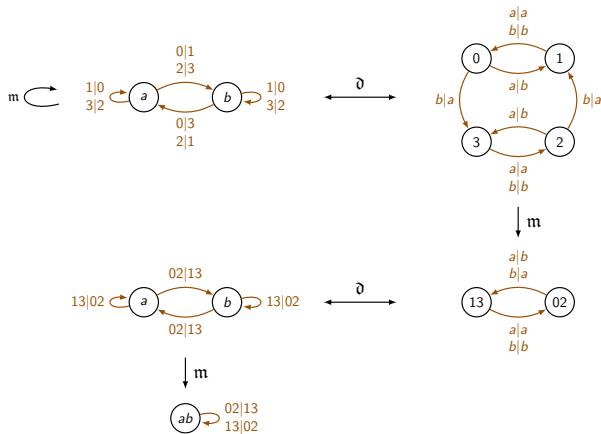


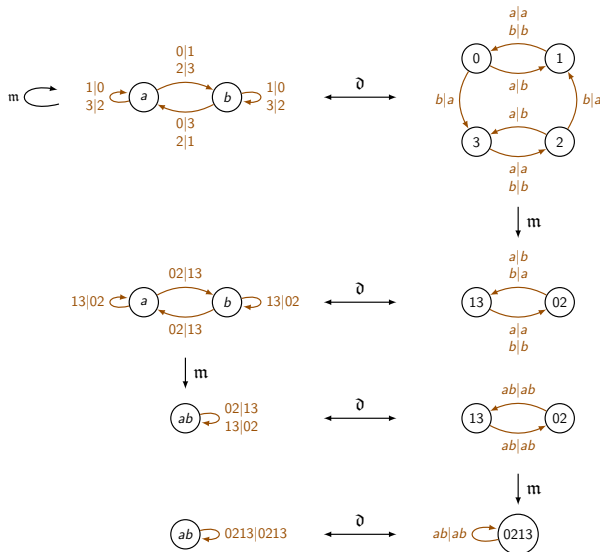






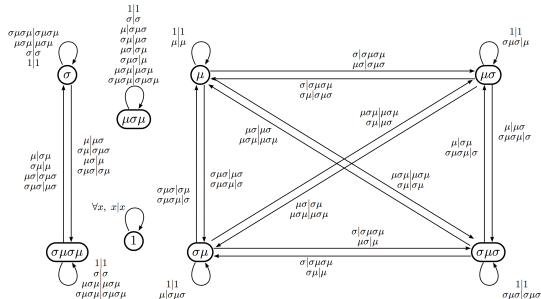






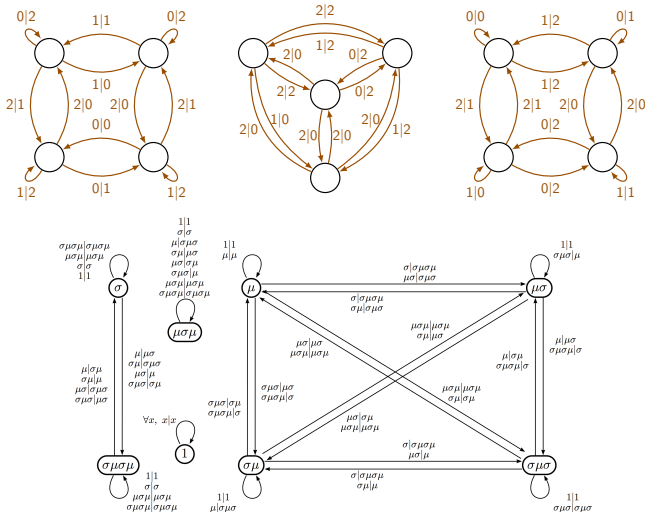
Akhavi Klimann Lombardy Mairesse P 2012

A Mealy automaton generates a finite (semi)group iff its  $m\bar{\partial}$ -reduced pair does.



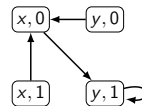
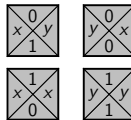
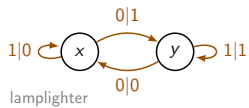
Akhavi Klimann Lombardy Mairesse P 2012

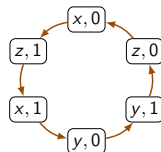
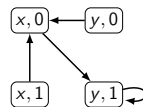
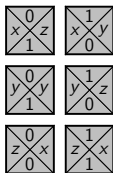
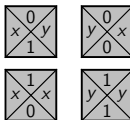
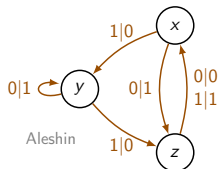
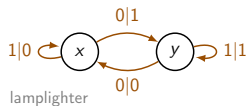
Even for bireversible automata, finiteness cannot be decided via  $m\partial$ -triviality.

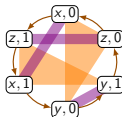
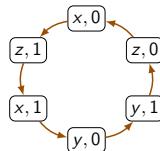
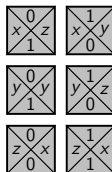
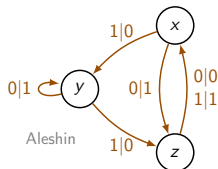
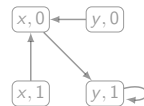
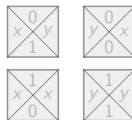
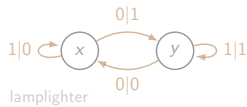


Akhavi Klimann Lombardy Mairesse P 2012

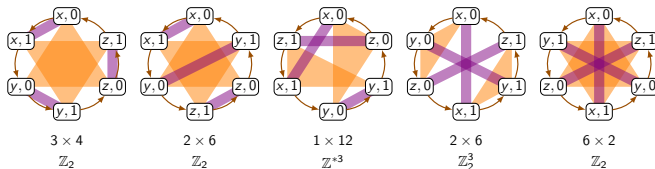
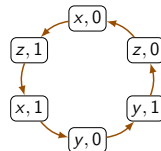
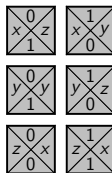
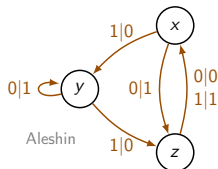
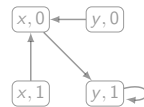
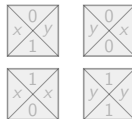
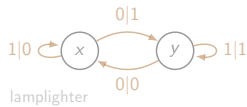
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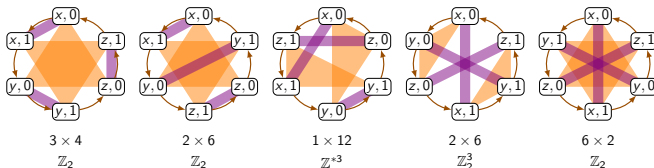
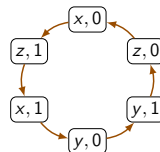
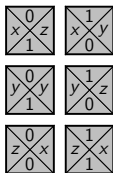
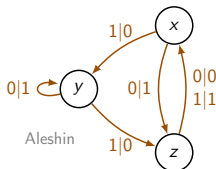
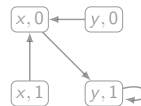
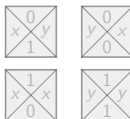
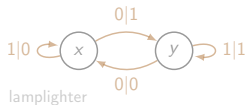




$1 \times 12$   
 $\mathbb{Z}^{*3}$

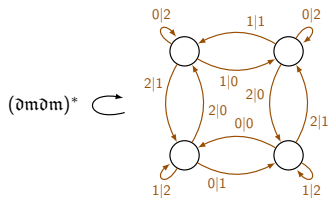


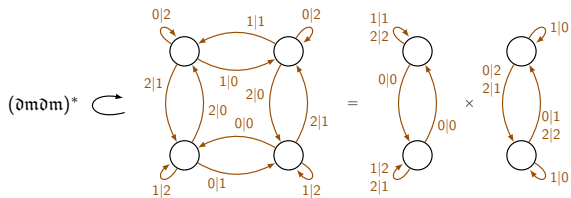


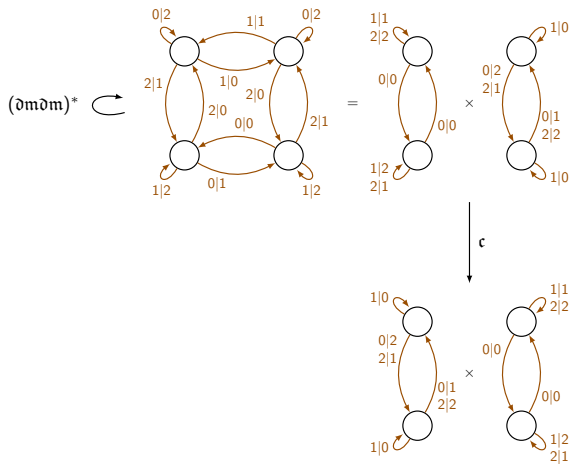


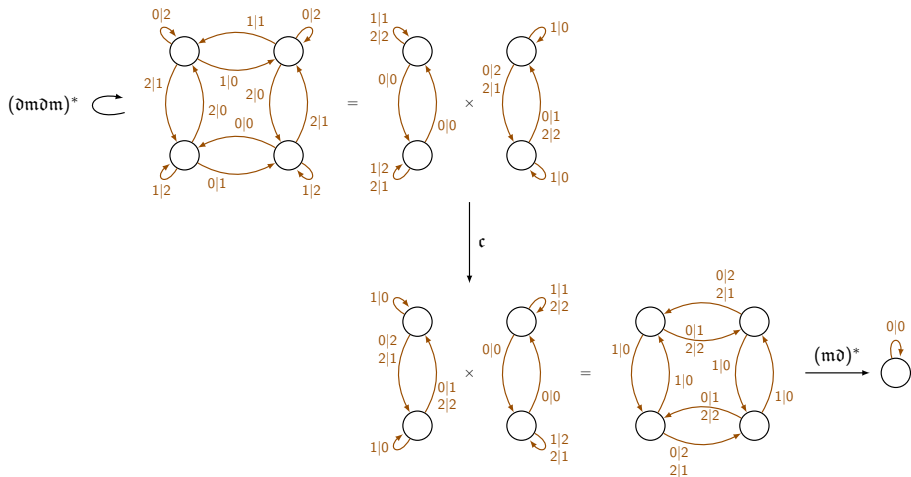
### Conjecture

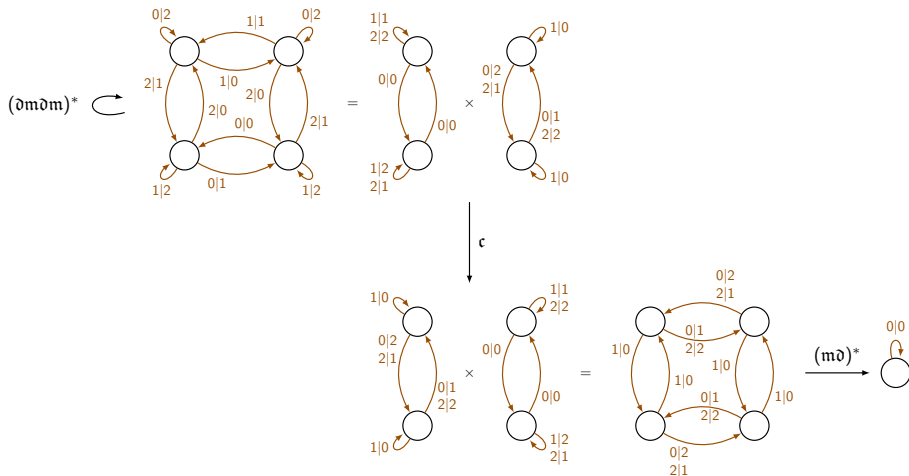
If a non-trivial  $m\partial$ -reduced bireversible automaton is **rigid**, it generates an infinite group.





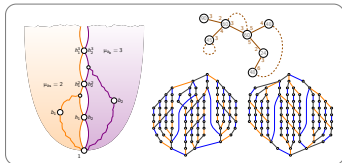
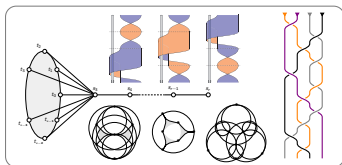
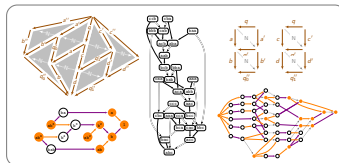
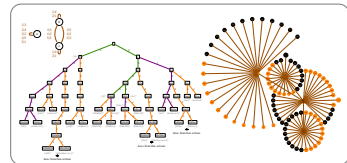
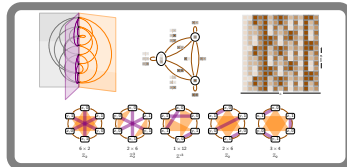


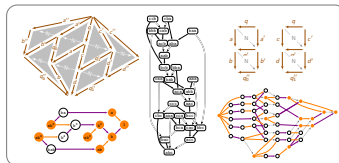
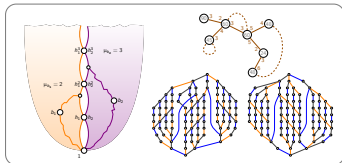
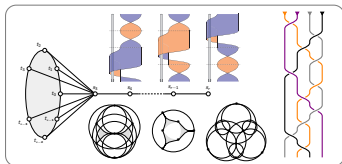
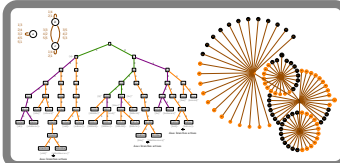
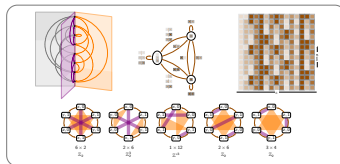




## Conjecture

A bireversible automaton generates a finite group iff it is  $m\partial\mathbf{c}$ -trivial.

Braid (semi)groups  
& Garside theoryMealy automata  
& automaton (semi)groupsQuadratic normalisations  
Thurston vs Mealy automata

Braid (semi)groups  
& Garside theoryQuadratic normalisations  
Thurston vs Mealy automataMealy automata  
& automaton (semi)groups



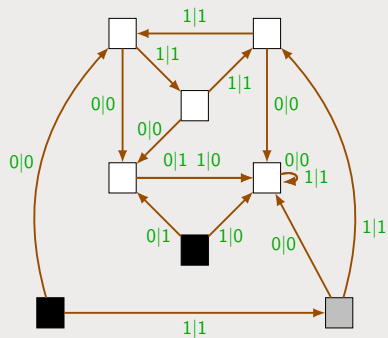
Burnside 1902

Is a finitely generated torsion group  
necessarily finite?

Burnside 1902

Is a finitely generated torsion group necessarily finite?

Alëšin 1972      Grigorchuk 1980

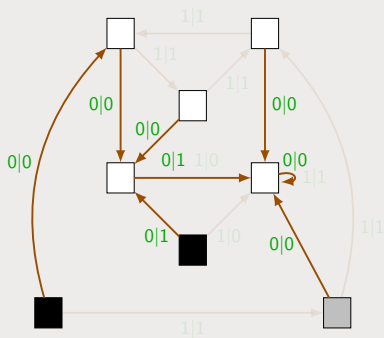


Burnside 1902

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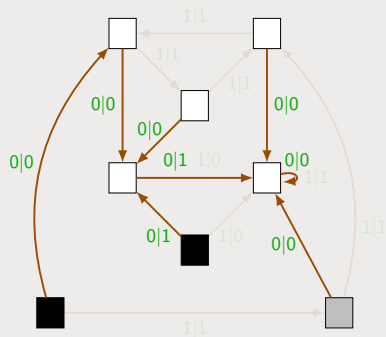
Grigorchuk 1980



Burnside 1902

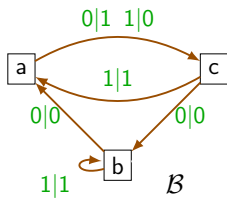
Is a finitely generated torsion group necessarily finite?

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### Question

And what about reversible automata?

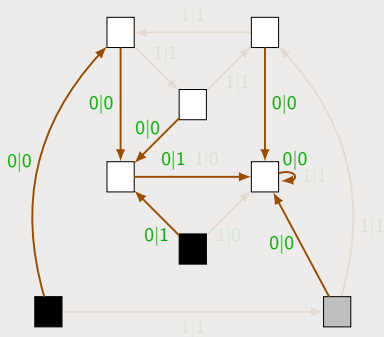


Burnside 1902

Is a finitely generated torsion group necessarily finite?

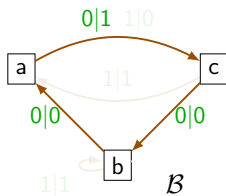
Alëšin 1972

Grigorchuk 1980



Question

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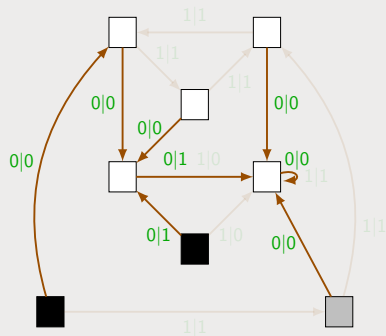


Burnside 1902

Is a finitely generated torsion group necessarily finite?

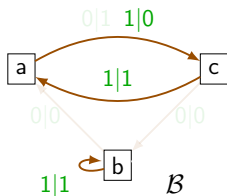
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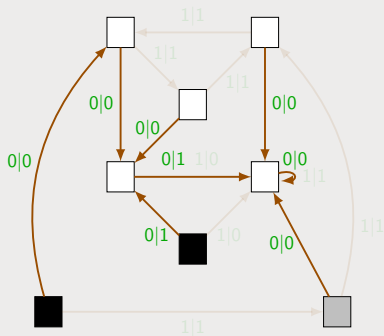


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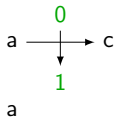
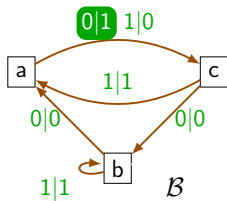
Alëšin 1972

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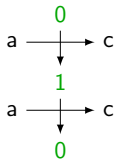
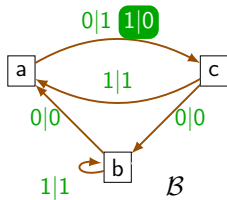


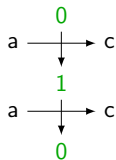
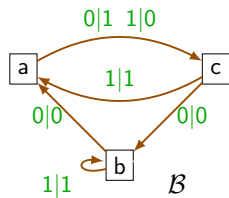
Question

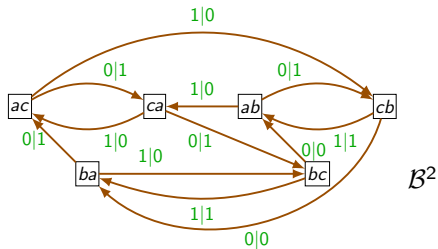
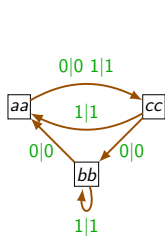
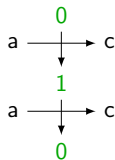
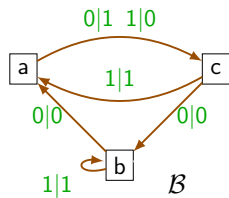
And what about reversible automata?

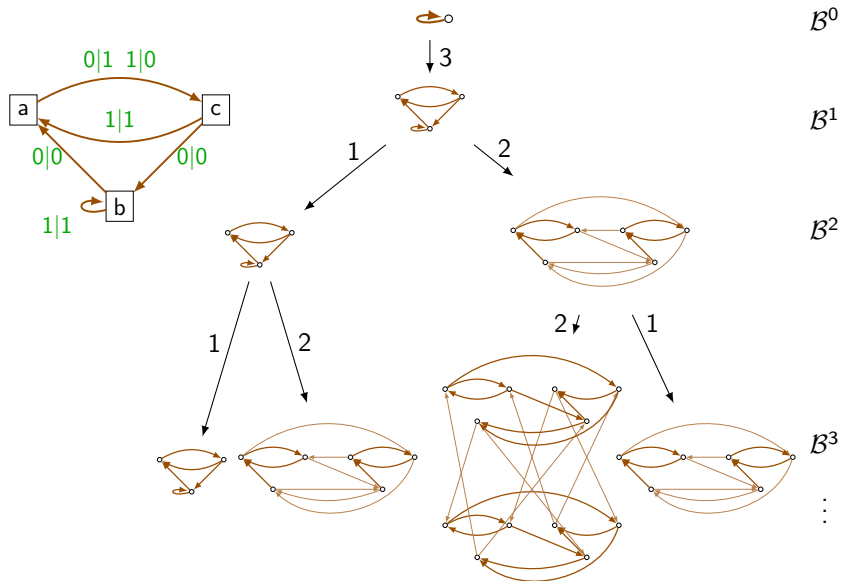


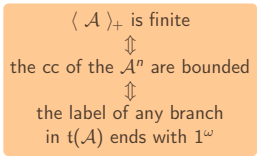


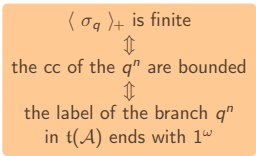


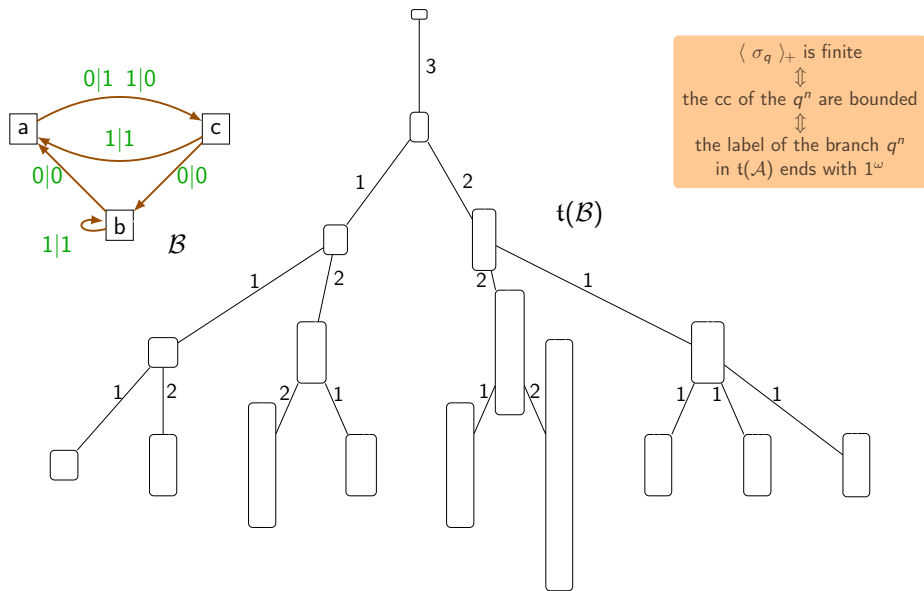


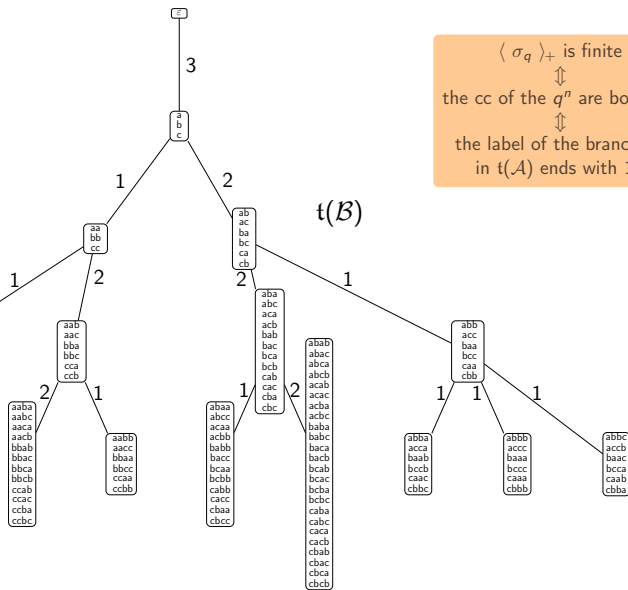
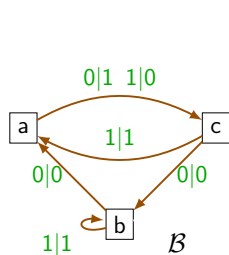






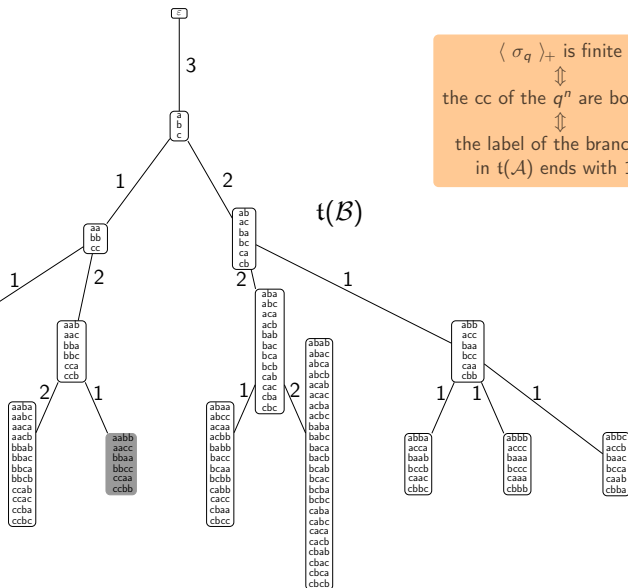
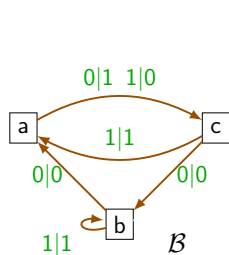




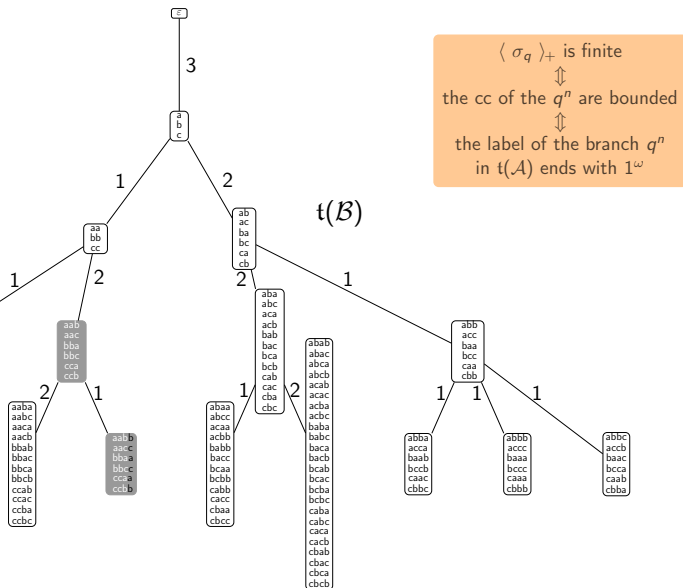
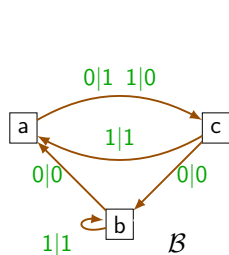


$\langle \sigma_q \rangle_+$  is finite  
 $\iff$   
 the cc of the  $q^n$  are bounded  
 $\iff$   
 the label of the branch  $q^n$   
 in  $t(\mathcal{A})$  ends with  $1^\omega$

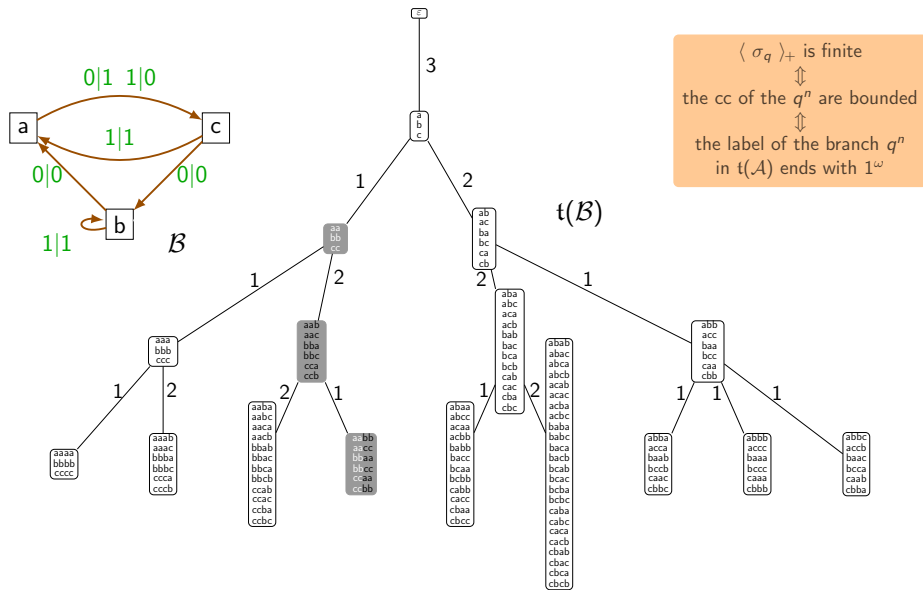


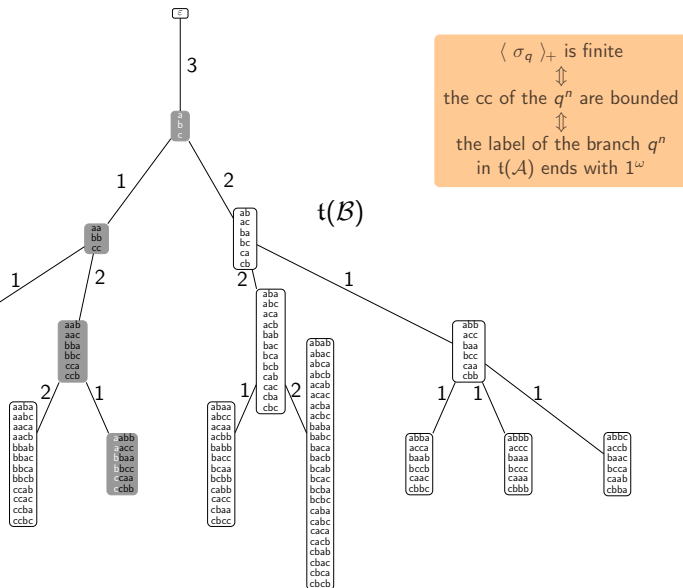
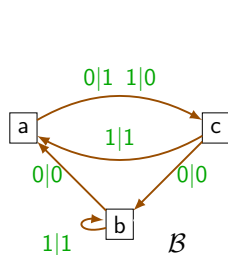


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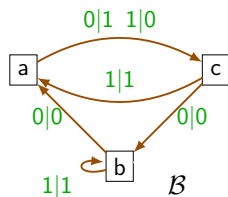


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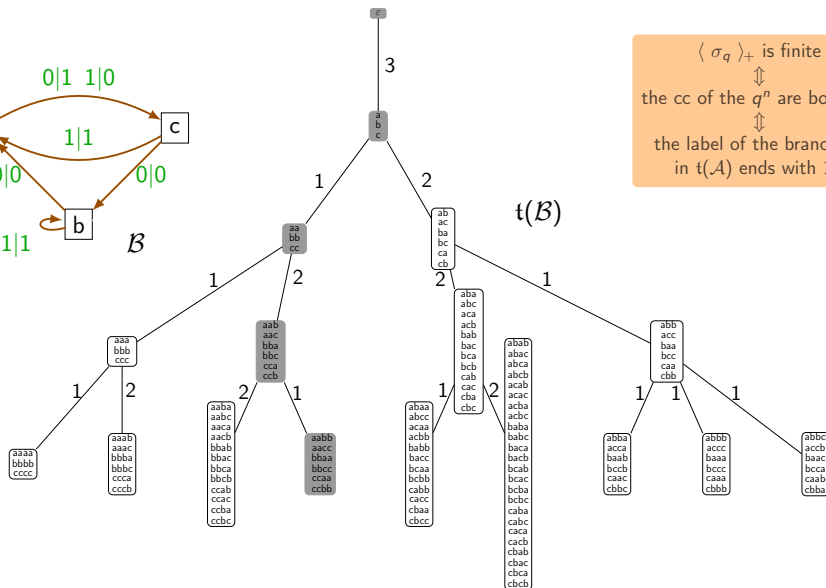


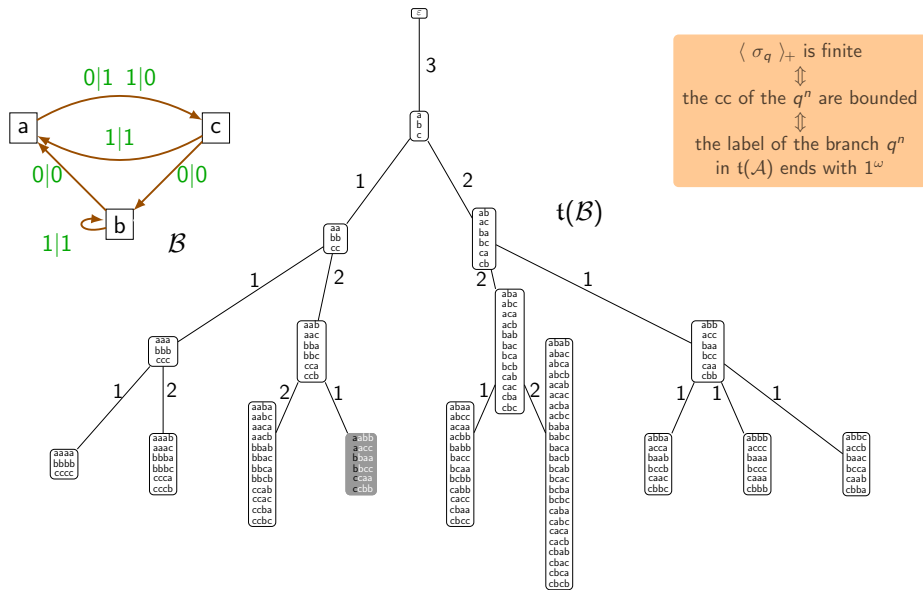


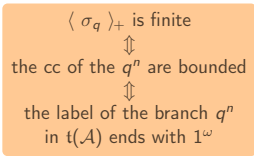
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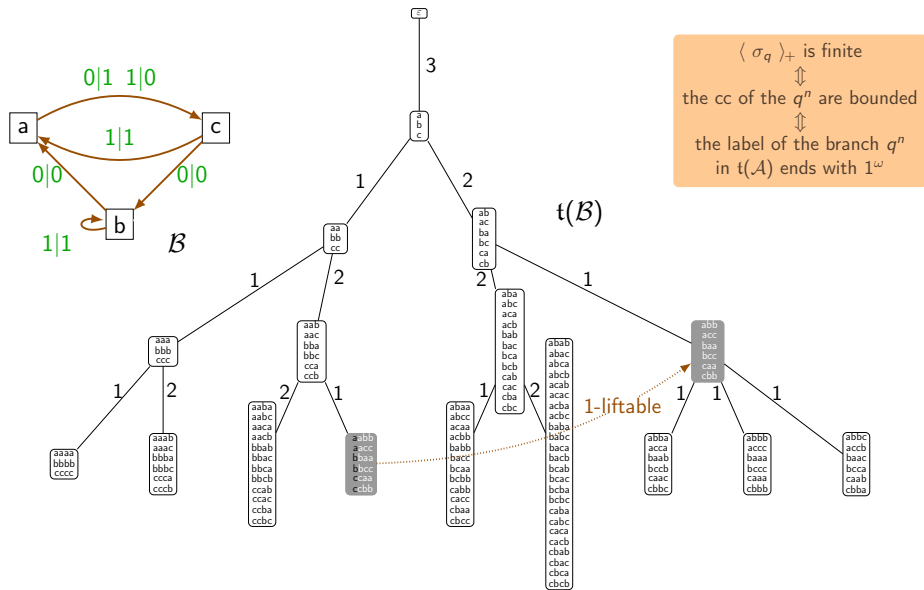


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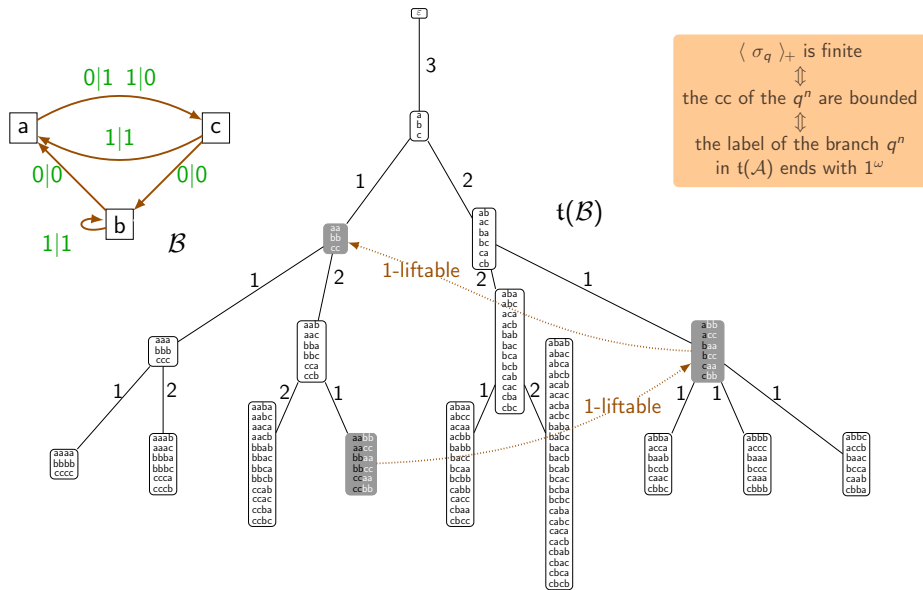


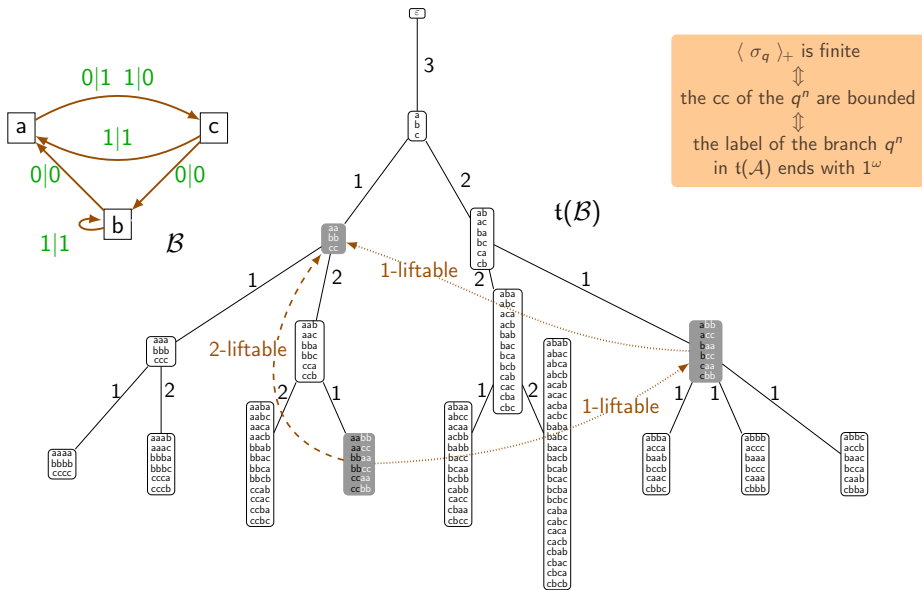


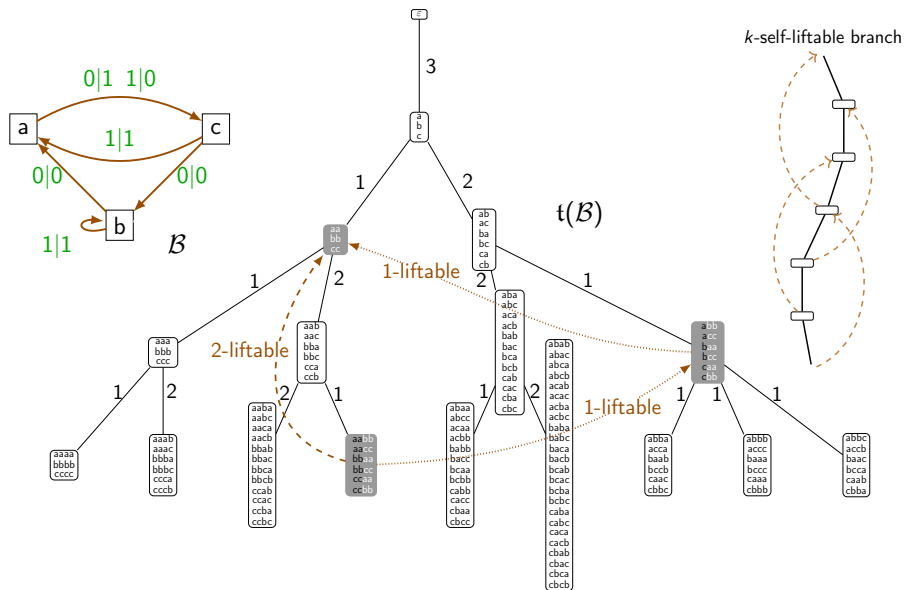


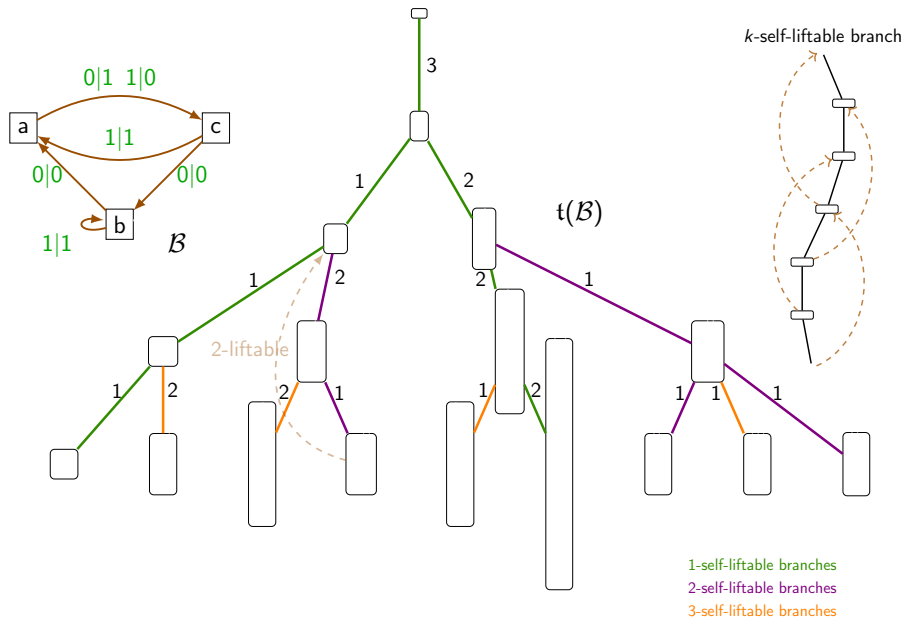












Godin P 2015

Assume that  $\mathcal{A}$  is an invertible reversible  $q$ -state Mealy automaton.  
 Let  $\lambda_{\mathcal{A},k}$  be the number of strict  $k$ -self-liftable branches in  $t(\mathcal{A})$  for  $k \geq 1$ .  
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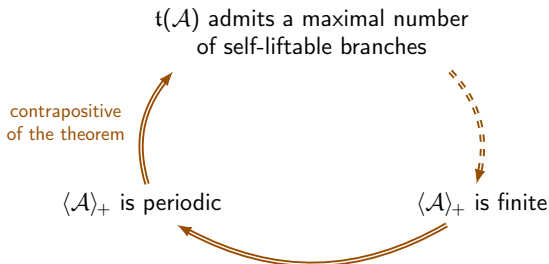
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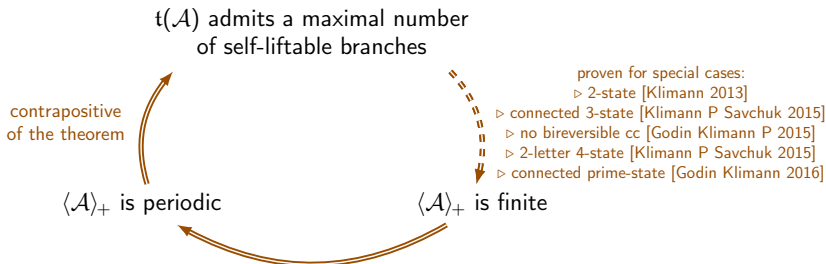
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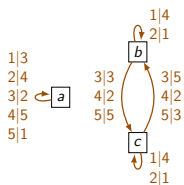
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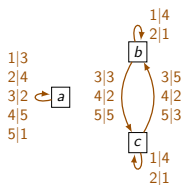
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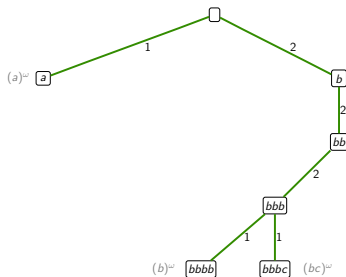


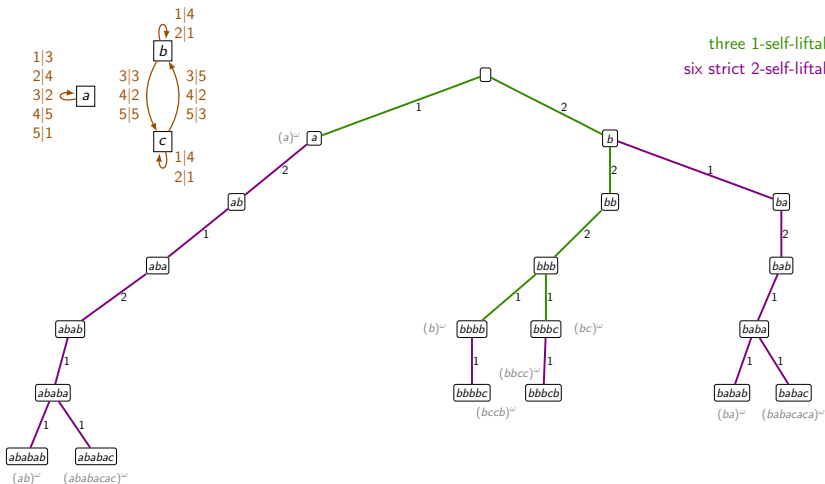






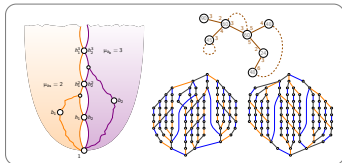
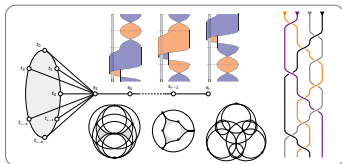
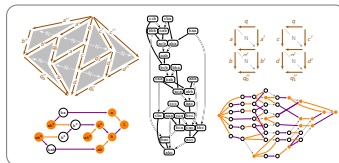
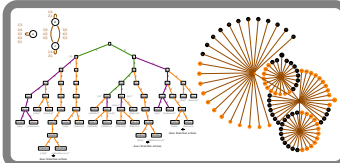
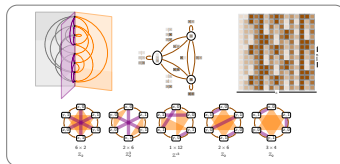
three 1-self-liftable branches

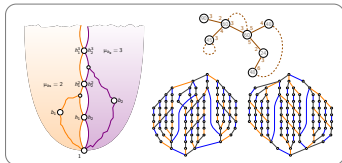
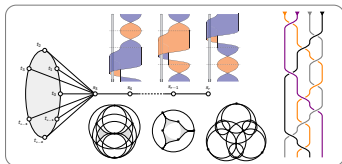
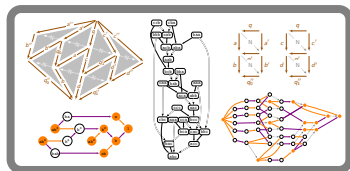
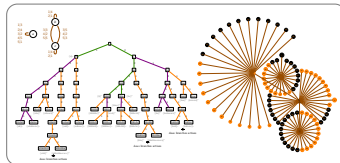
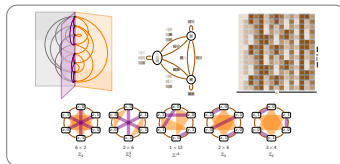


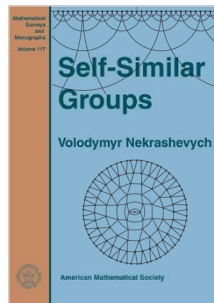
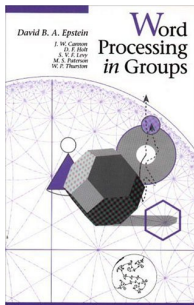






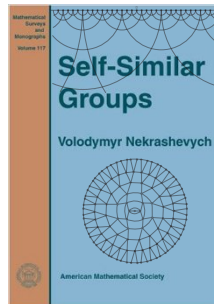
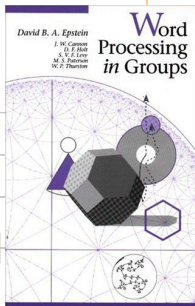
Braid (semi)groups  
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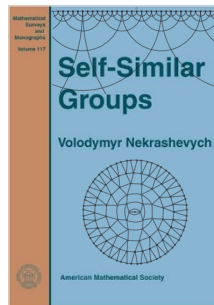
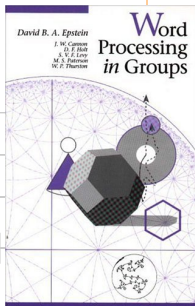




# geometric properties of the Cayley graph

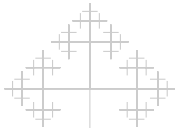


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of the Cayley graph



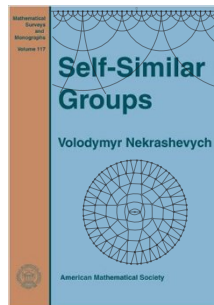
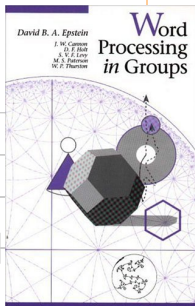
(semi)groups acting  
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▷ recognize the language of normal forms

▷ execute the (semi)group operations

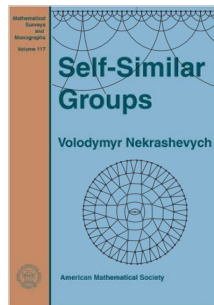
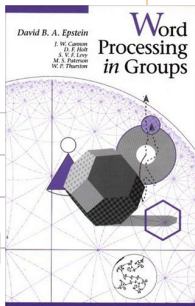


(semi)groups acting  
on regular rooted trees



▷ recognize the language of normal forms

▷ execute the (semi)group operations



▷ define sequential transformations

▷ represent the elements themselves

▷ recognize the language

▷ execute the (semi)group

We should emphasize that, despite their similar names, the notions of automaton (semi)groups are entirely separate from the notions of automatic (semi)groups.

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Why should we compare Edouard Manet and Claude Monet?

▷ represent the elements themselves

# Groups defined by automata

*Laurent Bartholdi*

*Pedro V. Silva*

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automaton

groups

semigroups

automatic

automaton

groups

Grigorchuk groups  
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semigroups

automatic



automaton

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 $\langle a, b : ab = b^m a \rangle$

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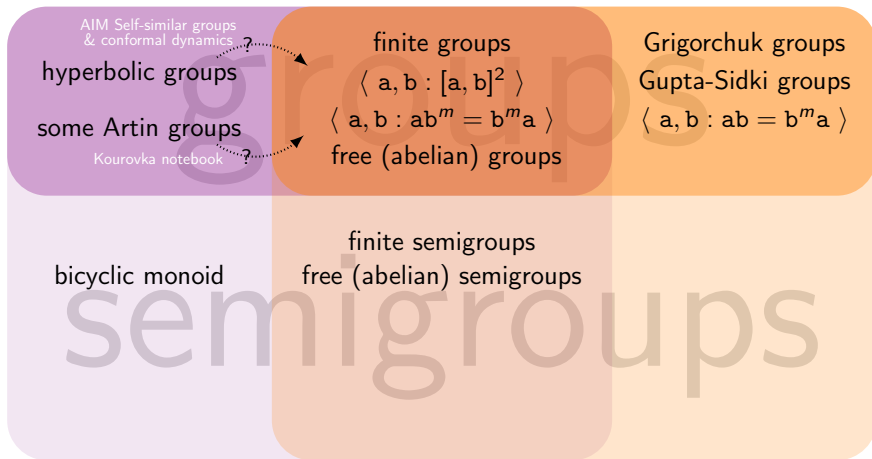
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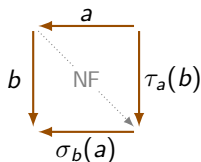
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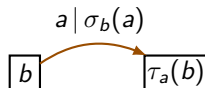
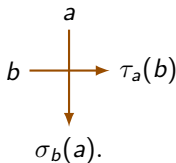
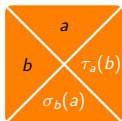
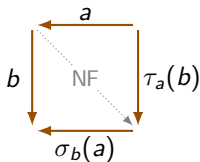


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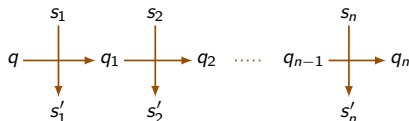
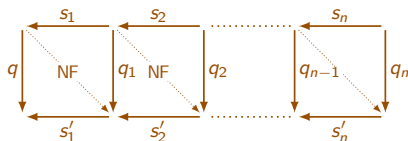
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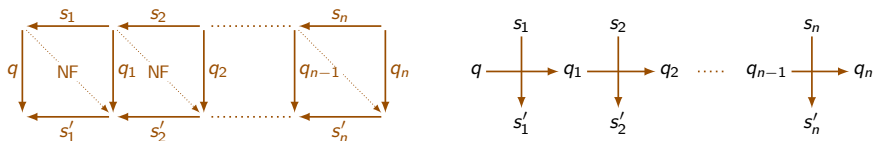
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We deduce  $\sigma_q(s_1 \cdots s_n) = s'_1 \cdots s'_n$  for any  $q \in \mathcal{Q}$ .

Theorem [P 2015]

$$S \cong \langle \mathcal{M}_{S, \mathcal{Q}, \text{NF}} \rangle_+^1$$

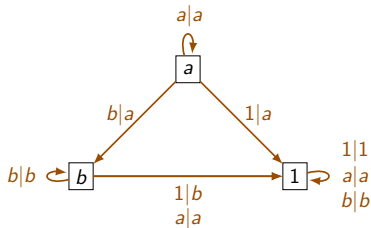
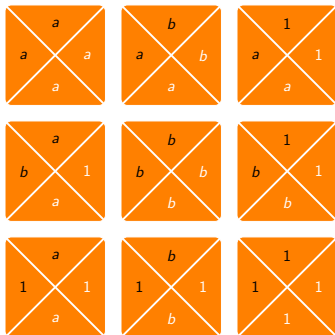
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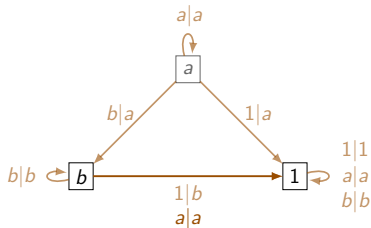
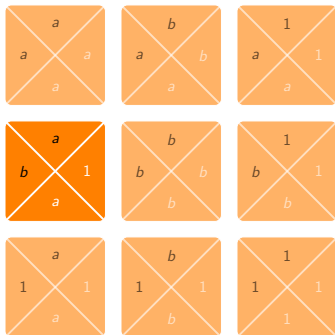
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Baumslag-Solitar

Artin-Krammer

$$\mathrm{BS}_+^1(1,0) = \langle a, b : ab = a \rangle_+^1 = \mathrm{AK}_+^1\left(\begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}\right)$$



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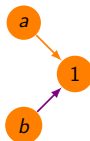
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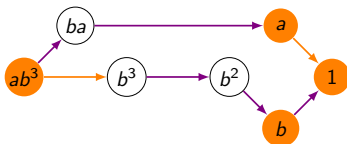


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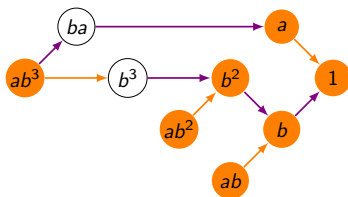


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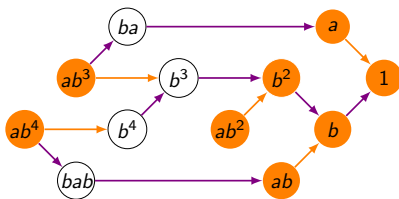


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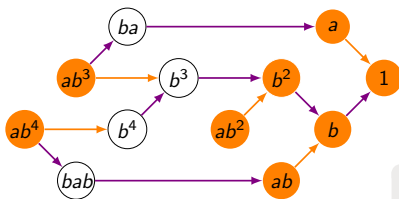


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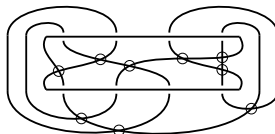
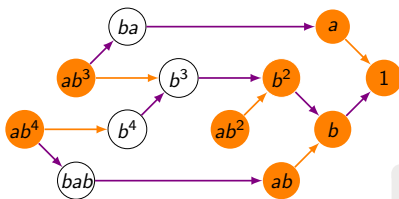
There exists a group-embeddable automaton monoid whose enveloping group is not an automaton group

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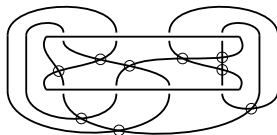
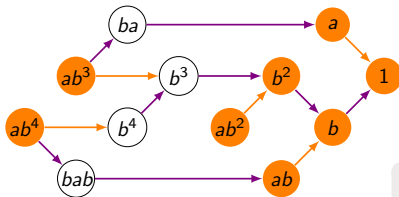
There exists a group-embeddable automatic monoid whose enveloping group is not an automatic group

Baumslag-Solitar

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Hoffmann 2001 P 2015

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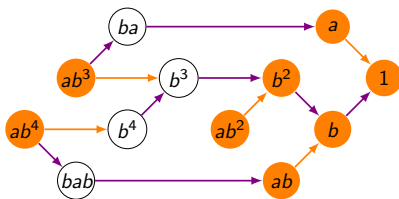
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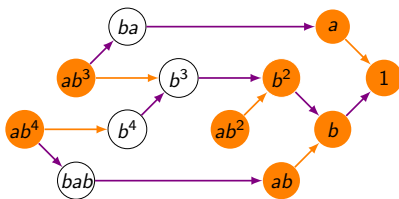
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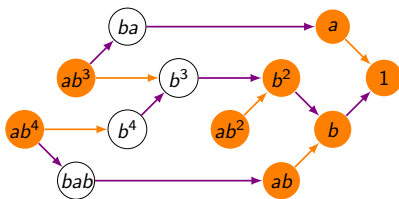
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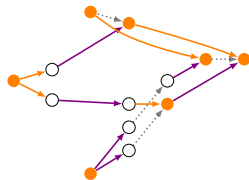
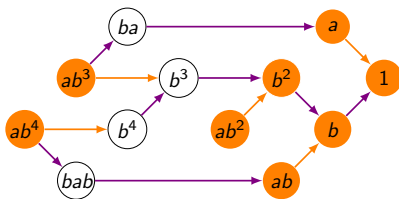
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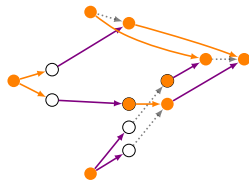
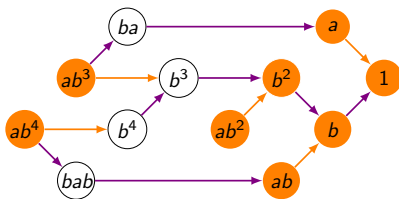
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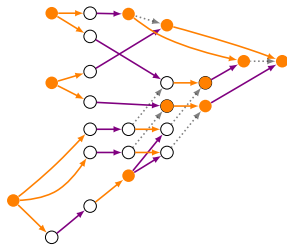
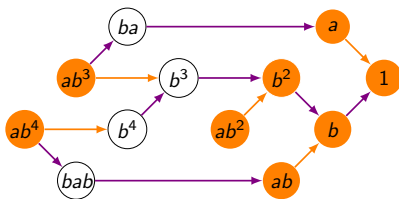
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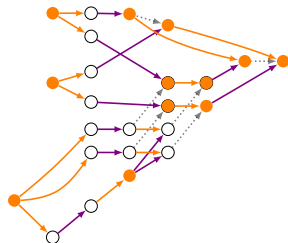
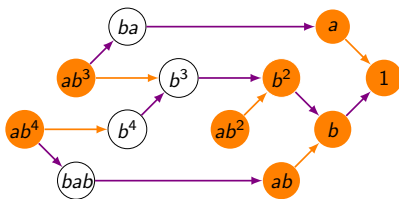
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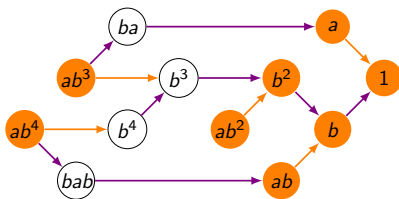
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Hoffmann 2001 P 2015

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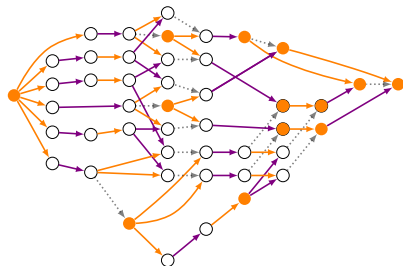
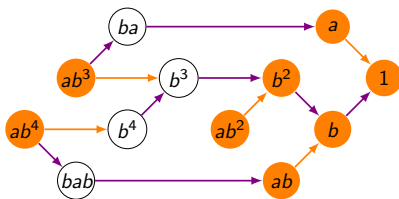
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Hoffmann 2001 P 2015

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Dehornoy Guiraud 2016 P 2016

 $\text{AK}_+^1(\Gamma)$  is an automaton monoid

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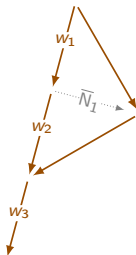
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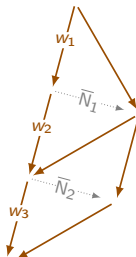
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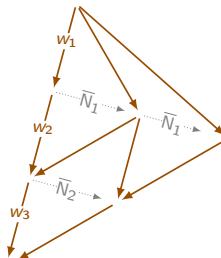
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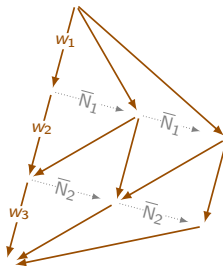
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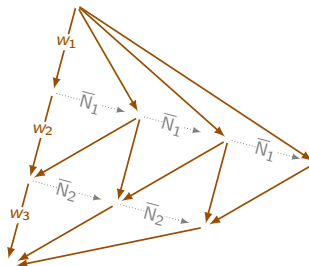
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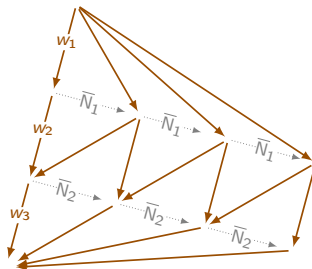
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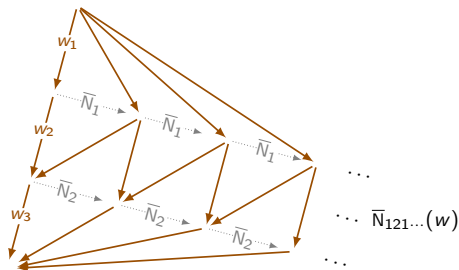
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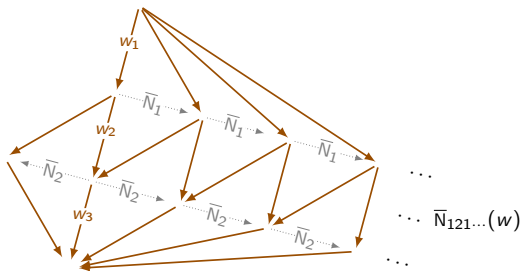
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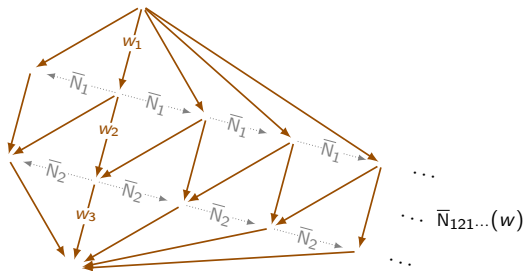
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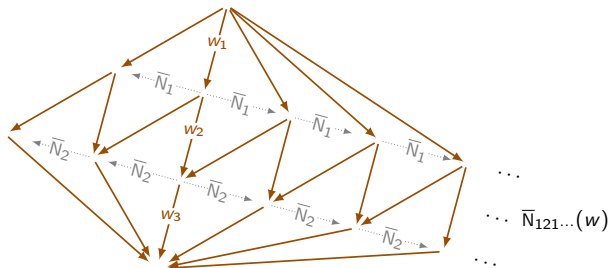
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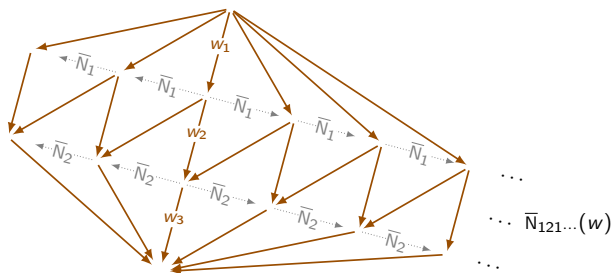
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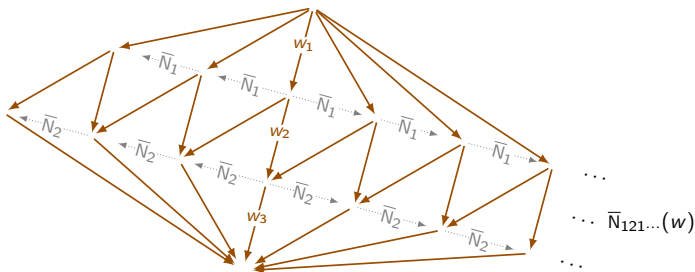
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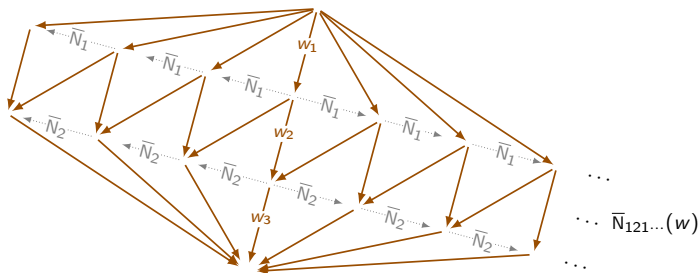
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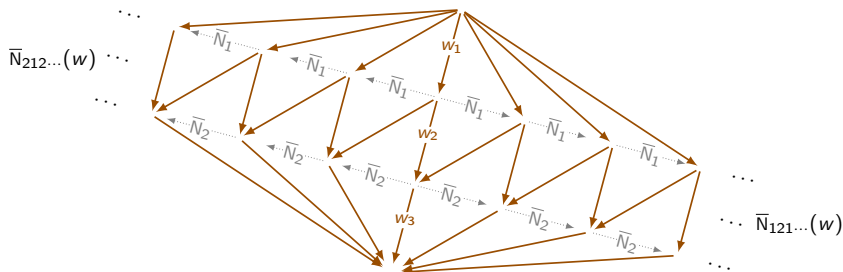
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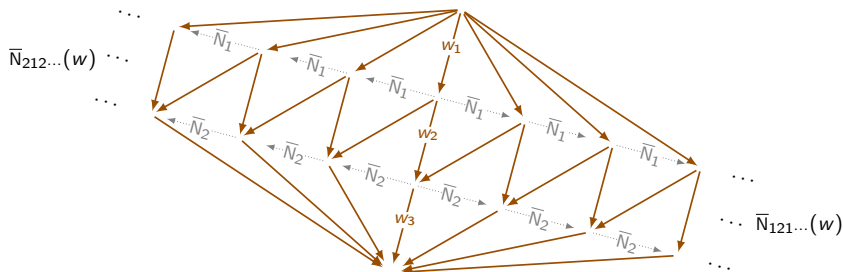
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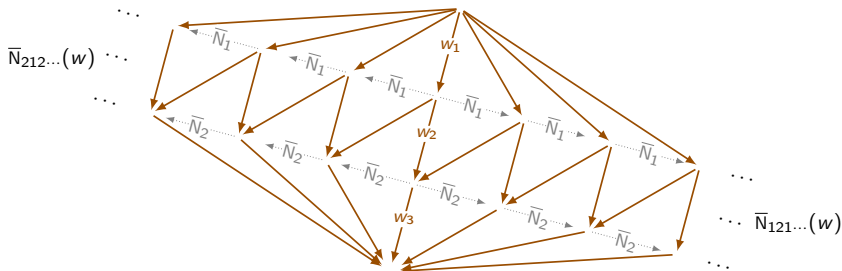
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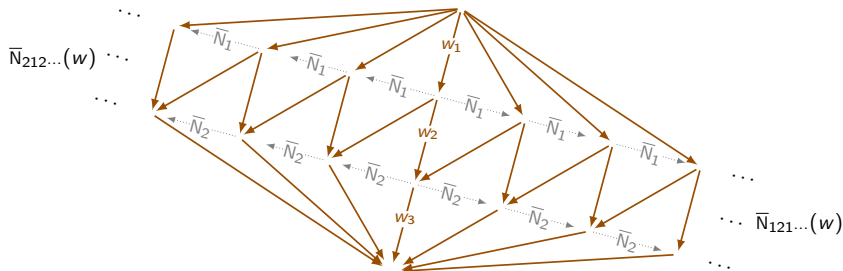


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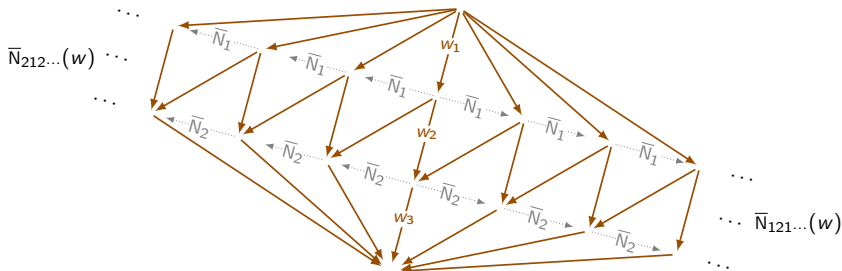
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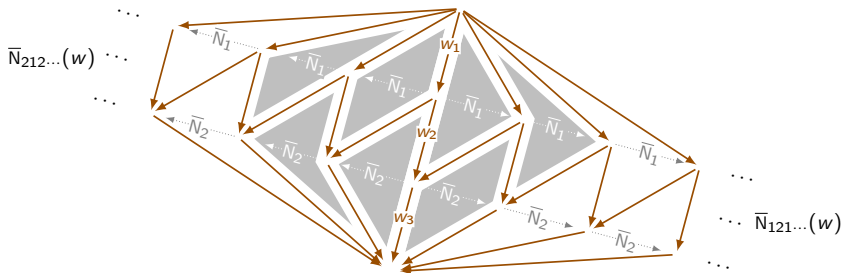


The **breadth** of  $(Q, N)$  is defined as:

$$\left( \max_{w \in Q^3} \min\{ \ell : N(w) = \bar{N}_{\underbrace{212\dots}_{\text{length } \ell}}(w) \}, \max_{w \in Q^3} \min\{ \ell : N(w) = \bar{N}_{\underbrace{121\dots}_{\text{length } \ell}}(w) \} \right).$$

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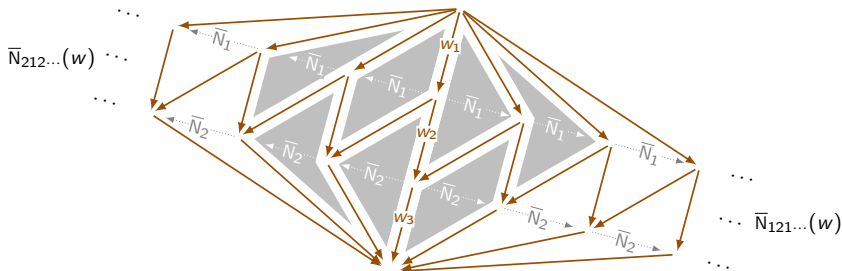
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Lemma [P 2016] *top-*

$$S \cong \langle \mathcal{M}_{S, Q, N} \rangle_+^1 / ?$$

Proposition [P 2016] *bottom-approximation*

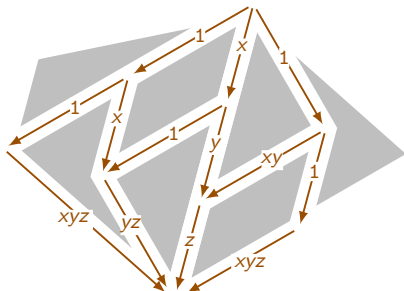
$$\langle \mathcal{M}_{S, Q, N} \rangle_+^1 \cong S / ? \iff (Q, N) \text{ satisfies } (\blacklozenge)$$

Every **finite monoid**  $\mathcal{J}$  is an automatic monoid:

- ▷ let  $(\mathcal{J}, N)$  verify  $N(xy) = 1(xy)$  for every  $(x, y) \in \mathcal{J}^2$ ;

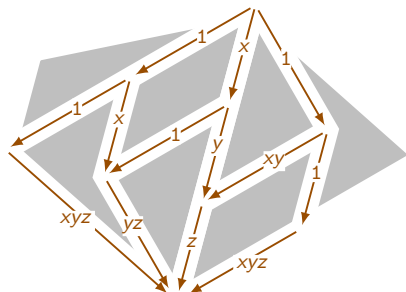
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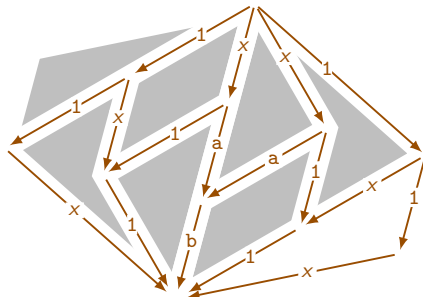
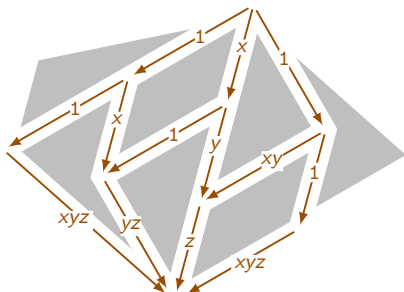


The **bicyclic monoid**  $\mathbf{B} = \langle a, b : ab = 1 \rangle_+^1$  is not an automaton monoid:

- ▷ let  $(\{a, b, 1\}, N)$  with  $N(ab) = 1$ ,  $N(x1) = 1x$ , and  $N(xy) = xy$ ;

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- ▷ its breadth is  $(3, 4)$ , contradicting Condition (◆).

The **plactic monoid** of rank  $n$  is

$$\mathbf{P}_n = \left\langle 1 < \cdots < n : \begin{array}{ll} zxy = xzy & \text{for } x \leq y < z \\ yxz = yzx & \text{for } x < y \leq z \end{array} \right\rangle_+^1.$$

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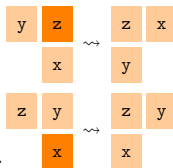
Cain Gray Malheiro 2014

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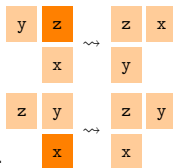
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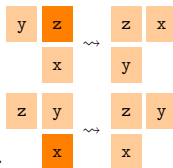
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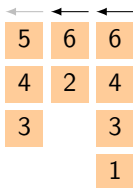
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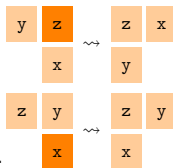
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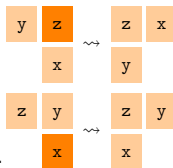
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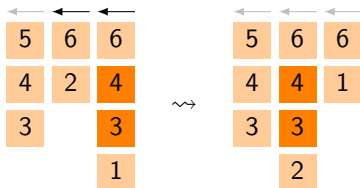
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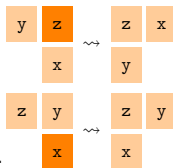
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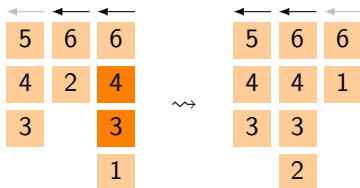
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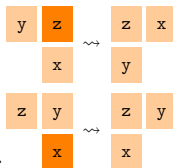
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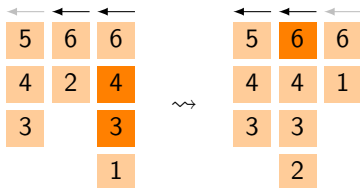
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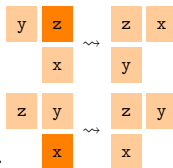
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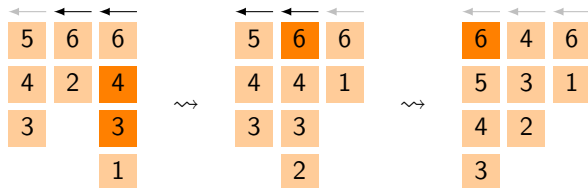
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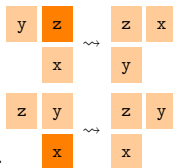




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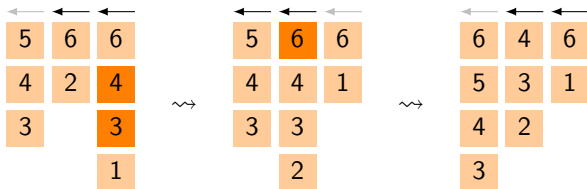
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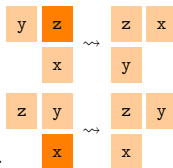
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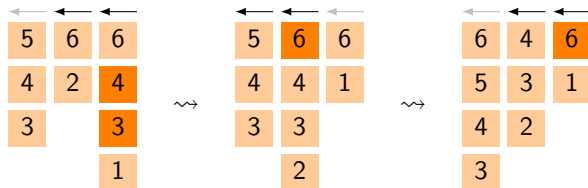
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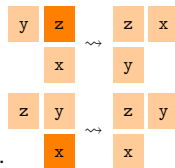
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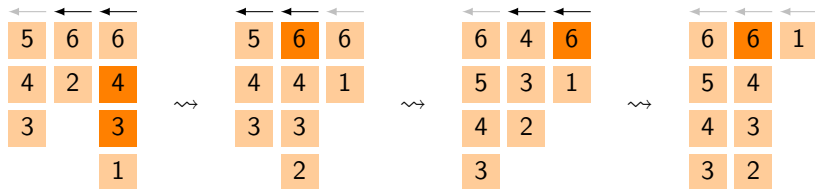
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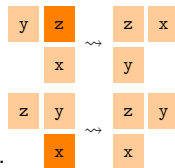
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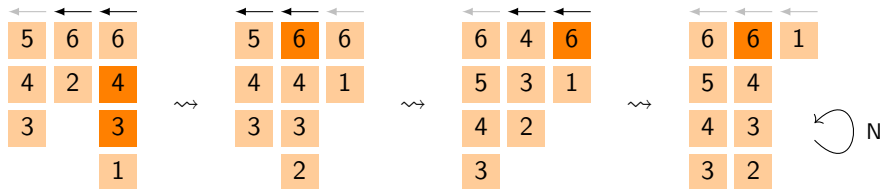
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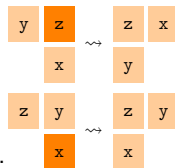
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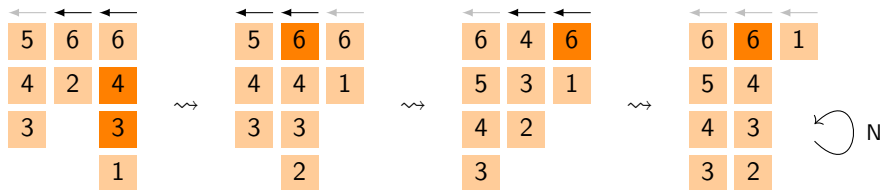
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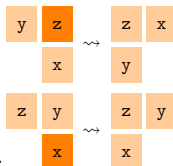
P 2016

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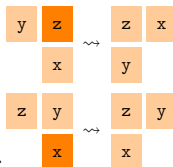
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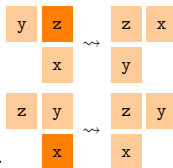
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Cain Gray Malheiro 2016

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Cain Gray Malheiro 2016

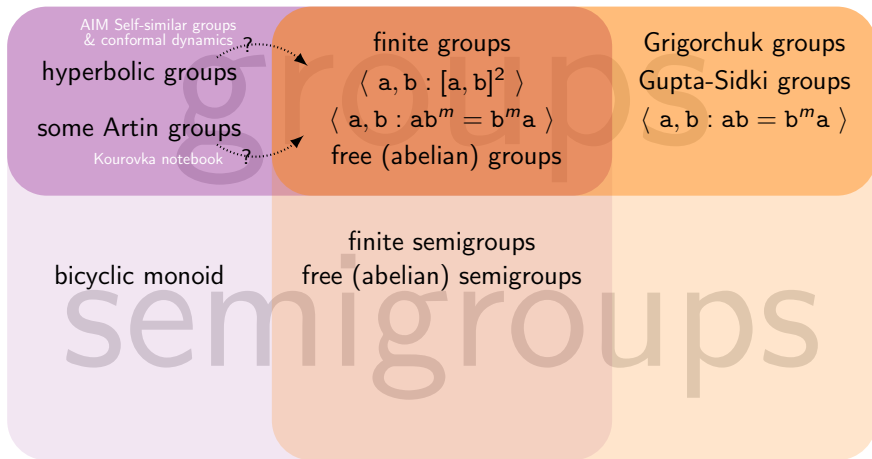
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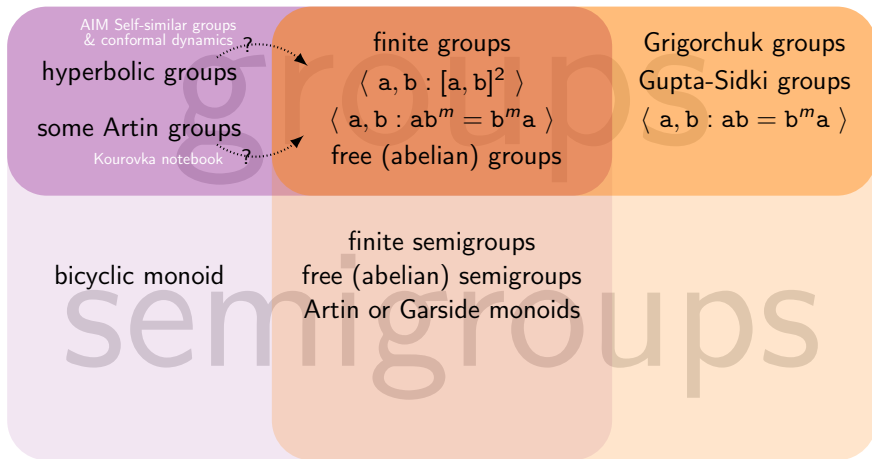


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AIM Self-similar groups  
& conformal dynamics

hyperbolic groups

some Artin groups

Kourovka notebook

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$\langle a, b : ab^m = b^m a \rangle$

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Grigorchuk groups

Gupta-Sidki groups

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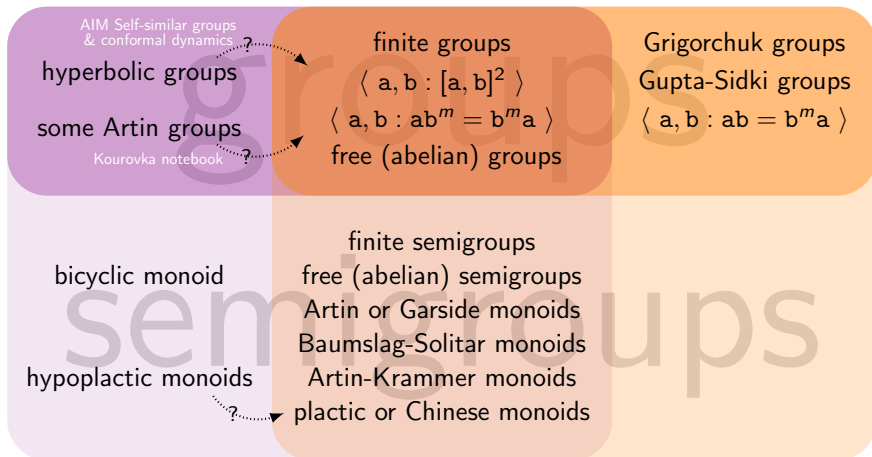
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Artin-Krammer monoids

plactic or Chinese monoids

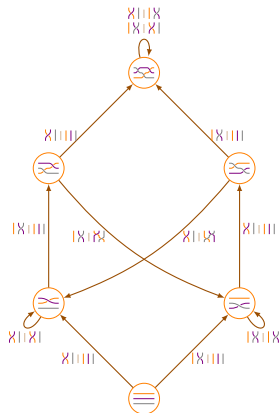
# automatic

# automaton



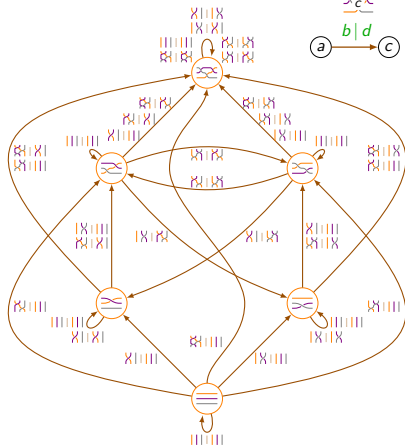
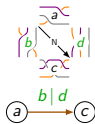
# automatic

$$\mathbf{B}_{3+}^1 = \langle \text{---}, \text{---} : \text{---} \text{---} \text{---} = \text{---} \text{---} \text{---} \rangle_+^1$$



Thurston transducer

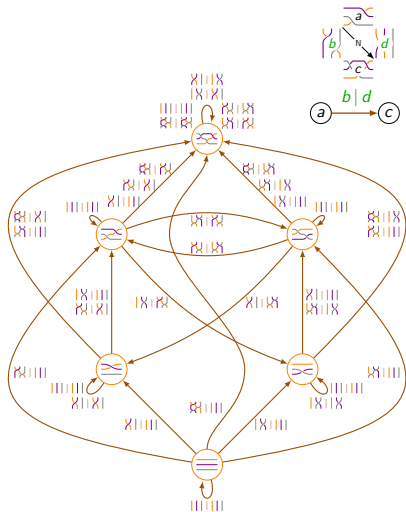
$$B_{3+}^1 = \langle \text{diagram 1}, \text{diagram 2} : \text{diagram 3} \text{ diagram 4} \text{ diagram 5} = \text{diagram 6} \text{ diagram 7} \text{ diagram 8} \rangle_+^1$$



(completed)  
Thurston transducer

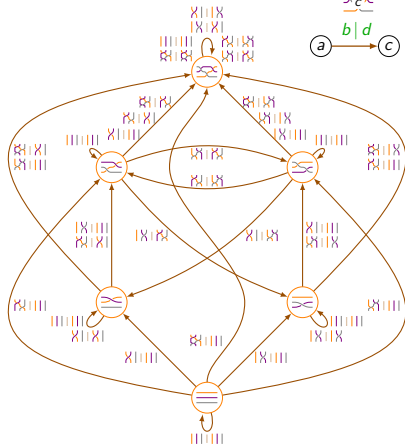
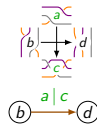
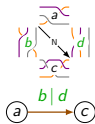


$$\mathbf{B}_{3+}^1 = \langle \text{diagram 1}, \text{diagram 2} : \text{diagram 3} = \text{diagram 4} \rangle_+^1$$

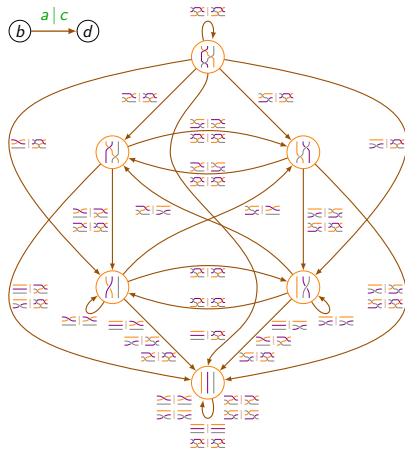


(completed)  
Thurston transducer

$$B_{3+}^1 = \langle \text{diagram 1}, \text{diagram 2} : \text{diagram 3} \text{diagram 4} \text{diagram 5} = \text{diagram 6} \text{diagram 7} \text{diagram 8} \rangle_+^1$$

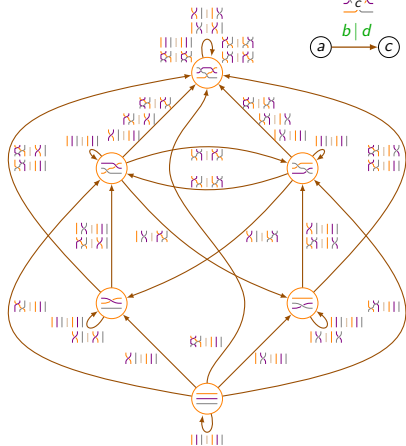
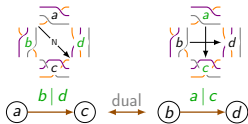


(completed)  
Thurston transducer

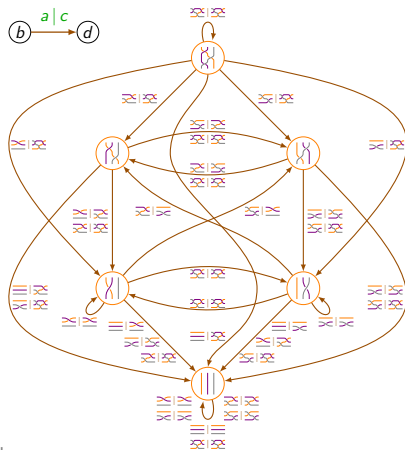


Mealy automaton

$$B_{3+}^1 = \langle \text{diagram 1}, \text{diagram 2} : \text{diagram 3} \text{diagram 4} \text{diagram 5} = \text{diagram 6} \text{diagram 7} \text{diagram 8} \rangle_+^1$$

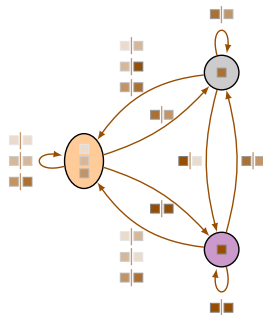
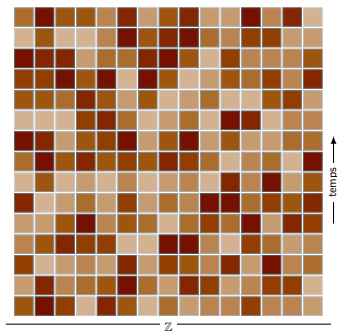


(completed)  
Thurston transducer



Mealy automaton

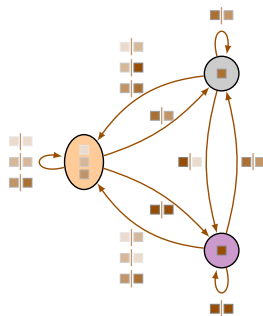
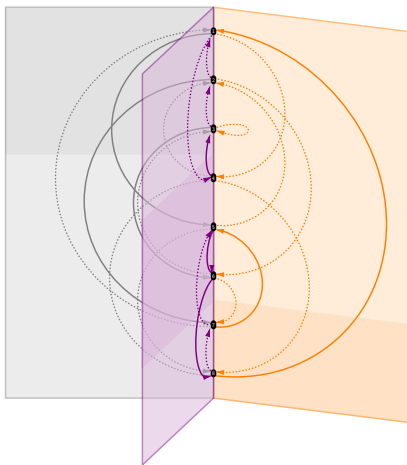
dual



adapter au nouvel alphabet  $\{1, \dots, 8\}$

### Question

Is the finiteness problem for reset automaton groups decidable?



adapter au nouvel alphabet  $\{1, \dots, 8\}$

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