Dynamic Networks through the Lens of Algebraic Topology

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DUCAT/ESTATE @ Cap Hornu – 17/03



Outline

Modeling Dynamic Networks and Algebraic Topology :

- Pierre's talk follow up
- algebraic methods in distributed computing
 - (shared memory)
 - static networks
 - dynamic networks
 - message adversaries
- (after lunch) reminder
- recent techniques with algebraic topology

- success of algebraic methods in distributed computing
- a model that can *model* (almost) all non-deterministic distributed executions
- but limits to effective generalization
- outline of some recent techniques
 - generalizing the standard chromatic subdivision [G.-Perdereau-2016]
 - full topology [Nowak-Schmid-Winkler-2019]
 - topology of the set of non-oblivious executions by geometrization [G.-Perdereau-2021]

some of the results were already presented at Descartes ...

Conclusion

The Dynamic Network or Message Adversary Model

- V is the set of processes
- dynamic graph = a sequence G₀, G₁, G₂, ..., G_t, ...
 G_t are spanning digraphs (ie over the same set of vertices V)
- dynamic network or message adversary = set of dynamic graphs

A Question of Terminology

- Mobile faults Santoro N., Wiedmayer P. Time is not a healer STACS 89
- *HeardOf Model* Charron-Bost B. and Schiper A. The Heard-Of model: computing in distributed systems with benign faults Dist. Computing 2009
- *Message Adversaries* Afek Y, Gafni E. Asynchrony from Synchrony ICDCN 2013

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- *Time Varying Graphs and Dynamic Networks* Casteigts A., Flocchini P., Quattrociocchi W., Santoro N. Int. J. Parallel Emergent Distributed Syst. 2012

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A Computation Step

The system evolves in synchronous rounds.

 G_0 is the initialization.

In a given round t, a process v

- sends its message m_v to neighbours (sendAll (m_v)),
- it receives messages according to arcs in G_t : m_u is received if uv ∈ A(G_t)
- it computes locally a new state

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- it computes locally a new state
- G_t is called the *instant digraph*

Message adversaries model (almost) everything

notation : infinite words (over an alphabet of graphs)

Examples with a network of two processes

- at each round, everything is possible: $\{\circ \bullet, \circ \leftrightarrow \bullet, \circ \leftrightarrow \bullet, \circ \rightarrow \bullet\}^{\omega}$.
- at each round, only one message can be lost: $\Gamma^{\omega} = \{\circ \leftrightarrow \bullet, \circ \leftarrow \bullet, \circ \rightarrow \bullet\}^{\omega}.$
- at most one of the processes can lose messages: $\{\circ\leftrightarrow\bullet,\circ\leftarrow\bullet\}^{\omega} \cup \{\circ\leftrightarrow\bullet,\circ\rightarrow\bullet\}^{\omega}.$
- at most one of the processes can crash: $C_1 = \{\circ \leftrightarrow \bullet\}^{\omega} \cup \{\circ \leftrightarrow \bullet\}^* (\{\circ \leftarrow \bullet\}^{\omega} \cup \{\circ \rightarrow \bullet\}^{\omega}).$
- The communication system is *fair*: $Fair = \Gamma^{\omega} \setminus \Gamma^*(\{\circ \leftrightarrow \bullet, \circ \leftarrow \bullet\}^{\omega} \cup \{\circ \leftrightarrow \bullet, \circ \rightarrow \bullet\}^{\omega}).$

no notion of faults but can encode faults

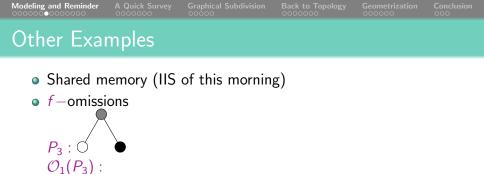


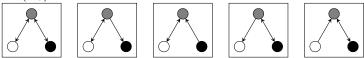
- Shared memory (IIS of this morning)
- f-omissions $P_3: \bigcirc$ $\mathcal{O}_1(P_3):$











- an adversary is said *oblivious* (or *iterated*) if it is Σ^ω for some set Σ
- general dynamic networks
- async. static networks
- synchronous static network

IIS Model (as a dynamic network)

The set Γ_n of graphs with *n* vertices such that

- (loops : always omitted)
- containment: $u \longrightarrow v$ or $v \longrightarrow u$
- immediacy: $u \longrightarrow v$ and $v \longrightarrow w$ implies $u \longrightarrow w$.

They are the graphs of **pre-total orders**.

 $IIS(n) = \Gamma_n^{\omega}$

Idea: $u \longrightarrow v$ means v has read the value written by u (in the immediate memory).

IIS Model (as a dynamic network)

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They are the graphs of **pre-total orders**.

 $IIS(n) = \Gamma_n^{\omega}$

Idea: $u \longrightarrow v$ means v has read the value written by u (in the immediate memory). Initially proposed as a memory model, now can also be considered as a message model.

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Topology : Simplicial Complex Modeling

identifier -> color state -> label

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Topology : Simplicial Complex Modeling

- identifier -> color state -> label
- local state \equiv vertex;

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Topology : Simplicial Complex Modeling

- identifier -> color state -> label
- local state \equiv vertex;
- 2 global \equiv simplex;



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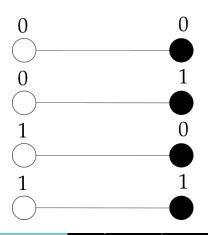
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Topology : Simplicial Complex Modeling

identifier -> color state -> label

- Iocal state \equiv vertex;
- 2 global \equiv simplex;
- many global states
 complexe simplicial;



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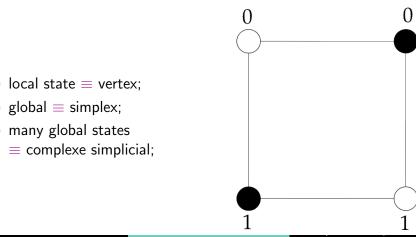
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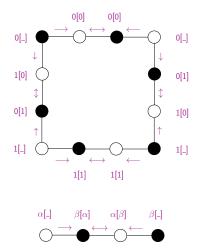
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Topology : Operational View



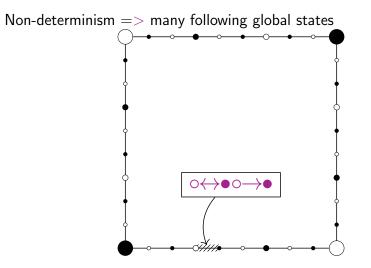
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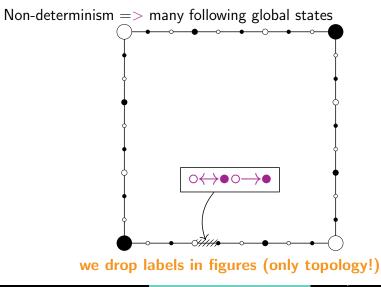
Topology : Distributed Computations



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Topology : Distributed Computations



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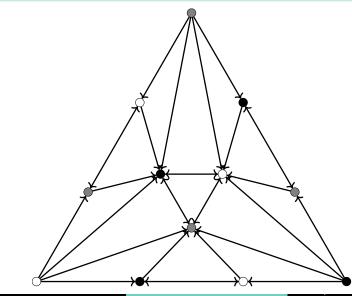
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Standard Chromatic Subdivision



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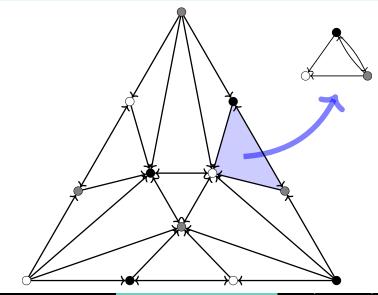
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Standard Chromatic Subdivision



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Topology : Executions

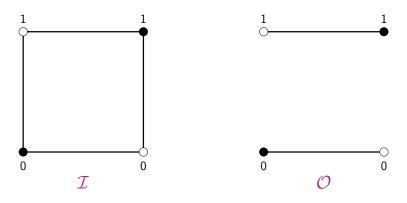
An execution gives a sequence of "simplicial complexes" that is algorithmically defined.

=> protocol complex ${\cal P}$

the protocol complex when the algorithm is the *full information* protocol.



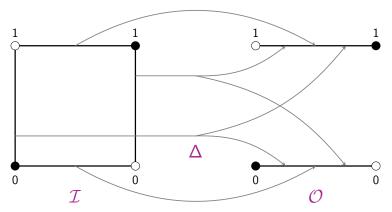
- \mathcal{I} : set of inputs, \mathcal{O} : set of outputs
- Δ : relation between \mathcal{I} and \mathcal{O}



Binary consensus for 2 processes



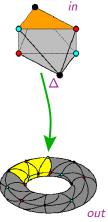
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Binary consensus for 2 processes

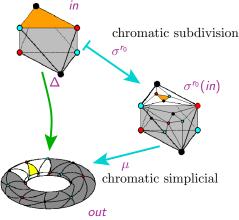
Herlihy Shavit Distributed Computability Theorem

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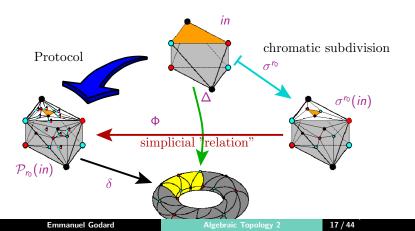
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Survey of Old and Recent Results 1

See Distributed Computing Through Combinatorial Topology (Herlihy, Kozlov, Rajsbaum)

- distributed tasks are topologically constrained
- applications :
 - consensus: connexity
 - set-agreement : simple connexity
 - colored tasks : renaming bounds
 - "graph" tasks : DUCAT

Partial Survey of Old and Recent Results 2

Consensus	 oblivious adversaries F^ω [Coulouma-GPeters-2015] arbitrary adversaries :
	▶ n = 2 [Fevat-G2011], [GPerdereau-2020]
	any n [Nowak-Schmid-Winckler-2019]
	 know-all adversaries [CFPRRT-2021]
k-set agreem	ent IIS : [Saks-Zaharoglou-2000]
	f-omissions : [GPerdereau-2016]
	 know-all adversaries [CFPRRT-2019]
tasks	 IIS : [Herlihy-Shavit-1999], [Borowsky-Gafni-1993]
	• affine models : [Kuznetsov-Rieutord-etal-2016,2018]

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Partial Summary

Tasks\Models	sub-IIS	IIS	general graphs
consensus	GP20(n=2)		NSW19 CFPRRT21
k-set agreement		SZ2000	GP16 CFPRRT19
general tasks	KR16/18	BG93 HS99	???

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Known Limits for the Topological Approach

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Known Limits for the Topological Approach

The protocol complex is too complex

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Known Limits for the Topological Approach

- The protocol complex is too complex
- **2** focus on the IIS model = standard/chromatic subdivision

Conclusion

Known Limits for the Topological Approach

- The protocol complex is too complex
- **(2)** focus on the IIS model = standard/chromatic subdivision
- computability equivalences but complexity ??

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IIS : When it Works Nicely

Iterated Immediate Snapshot (IIS)

IIS model is central see Pierre and Hugues' talks, also Kozlov 2013 "regular" message adversaries oblivious / iterated

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Direction for Generalization

- arbitrary underlying graphs
- arbitrary languages (not only oblivious)
- more direct characterizations

Generalizing : Graphical Subdivision $\zeta(G)$

Goal: define a subdivision for arbitrary (underlying) graphs requirements :

- extension of the standard chromatic subdivision
- ie this will be $\zeta(K_n)$

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Definition by Recurrence for "G"

$$\zeta(G,\sigma) \stackrel{\text{\tiny def}}{=} \begin{cases} \emptyset & \text{if } V(G) = \emptyset \\ \sigma & \text{if } E(G) = \emptyset \\ \bigcup_{\tau \subsetneq \sigma} \operatorname{join}(\zeta(G_{|\tau},\tau),\mu_{\sigma}(\sigma \backslash \tau)) & \text{otherwise} \end{cases}$$

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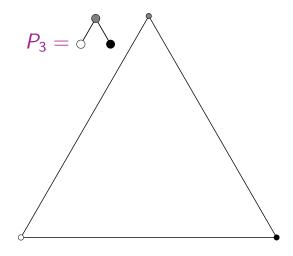
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Construction for Graphical Subdivision of " P_3 "



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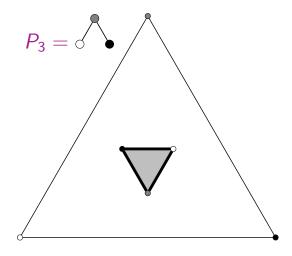
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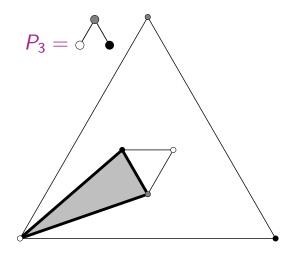
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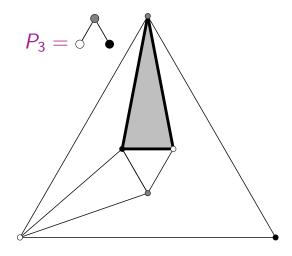
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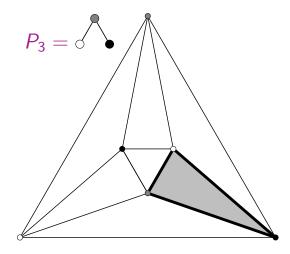
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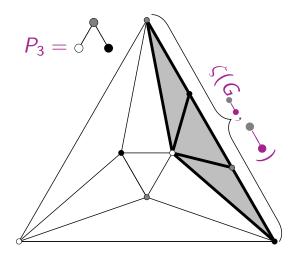
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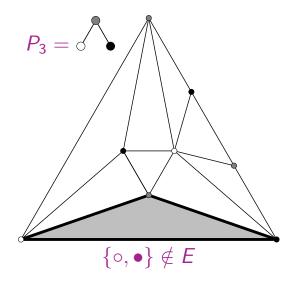
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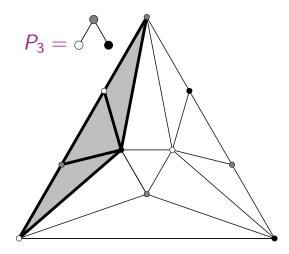
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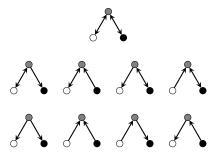


Corresponding Message Adversary

The standard correpsondance defines a special set of instant graphs: $\gamma({\cal G})$

n = |G|. D a subgraph of G, $\varphi_G(D)$ is defined by $uv \in A(\varphi_G(D))$ if $uv \in E(G)$,

 $\gamma(G) = \varphi_G(IIS_n).$



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Application : Set-agreement

Proposition

It is impossible to solve set-agreement on $\gamma(P_3)^{\omega}$.

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Proof: By Sperner Lemma

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NB ne fonctionne que pour l'impossibilité

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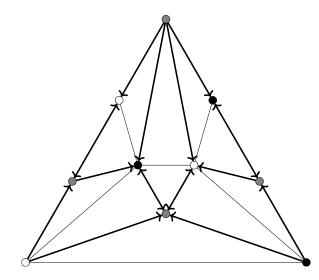
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Actually Topological "Diagrams"



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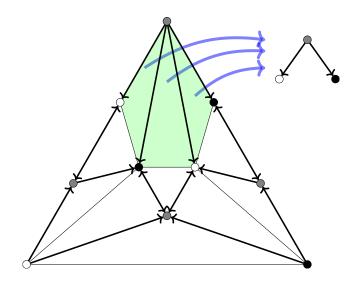
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Actually Topological "Diagrams"



Conclusion

Power and Limits of Algebraic Tools

- elementary steps of modelization $D \longleftrightarrow S$
- $\bullet => \mathsf{fully general}$
- how to handle in a simple way when generalizing
 - graphical subdivisions
 - geometrization

Perspectives

- diagrams => new applications of possibly more than one simplex per instant graphs
- non oblivious message adversaries and generalizing the induced "topology" => "removing"/"compacting" unnecessary executions

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Questions ?

Thanks for your attention.