

A Speedup Theorem for Asynchronous Computation

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Joint work with:

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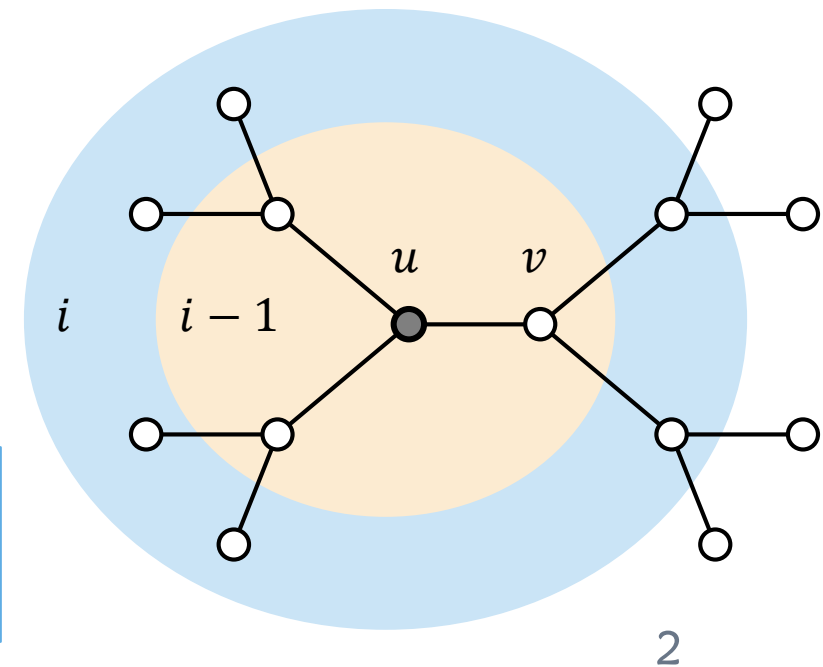
Speedup Theorem (a.k.a. round elimination)

- Recent technique for LOCAL lower bounds
- Typical problems: Maximal Matching, Sinkless Orientation, Coloring
- We want to show that a **problem $P = P_T$** has on **T -round** algorithm
- High-level idea:

Claim 1: i -round algorithm for problem $P_i \Rightarrow$
 $(i - 1)$ -round algorithm for another problem P_{i-1}

Claim 2: No 0 -round algorithm for P_0

Technique: simulate
distance- i view



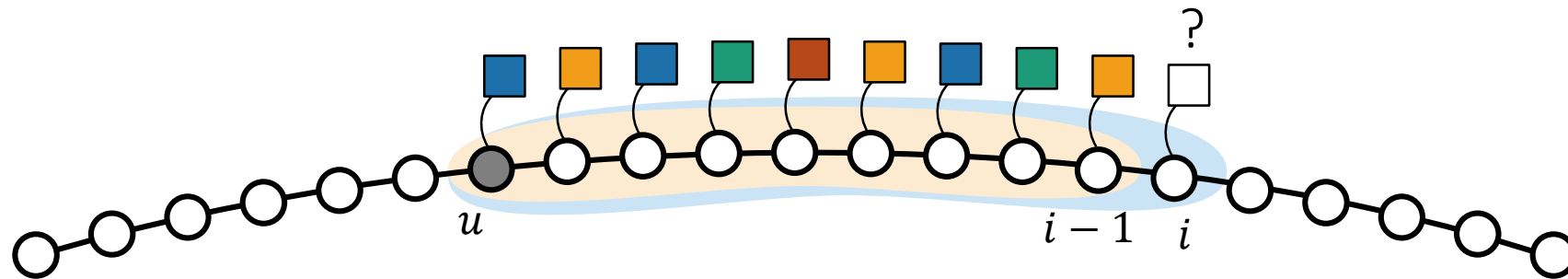
Speedup Theorem – Example

- Linial's lower bound for 3-coloring a ring
- High-level idea:

$$\text{col}_{i-1}(u) = \{\text{col}_i(u) \mid \text{possible color of distance-}i \text{ node}\}$$

Claim 1: i -round algorithm for c -coloring \Rightarrow $(i - 1)$ -round algorithm for 2^c -coloring

Claim 2: No 0-round algorithm for $(n - 1)$ -coloring



Round Elimination in Async. Computation?

Shared memory, with iterated model

- *distance- i* is not defined
- But... we can still ask what can process u see in round i
- High-level idea – the same

Claim 1: *i -round* algorithm for task $\Pi_i \Rightarrow$
 $(i - 1)$ -round algorithm for another task Π_{i-1}

Claim 2: No *0-round* algorithm for P_0

Technique: simulate possible views at round i

Shared Memory Models

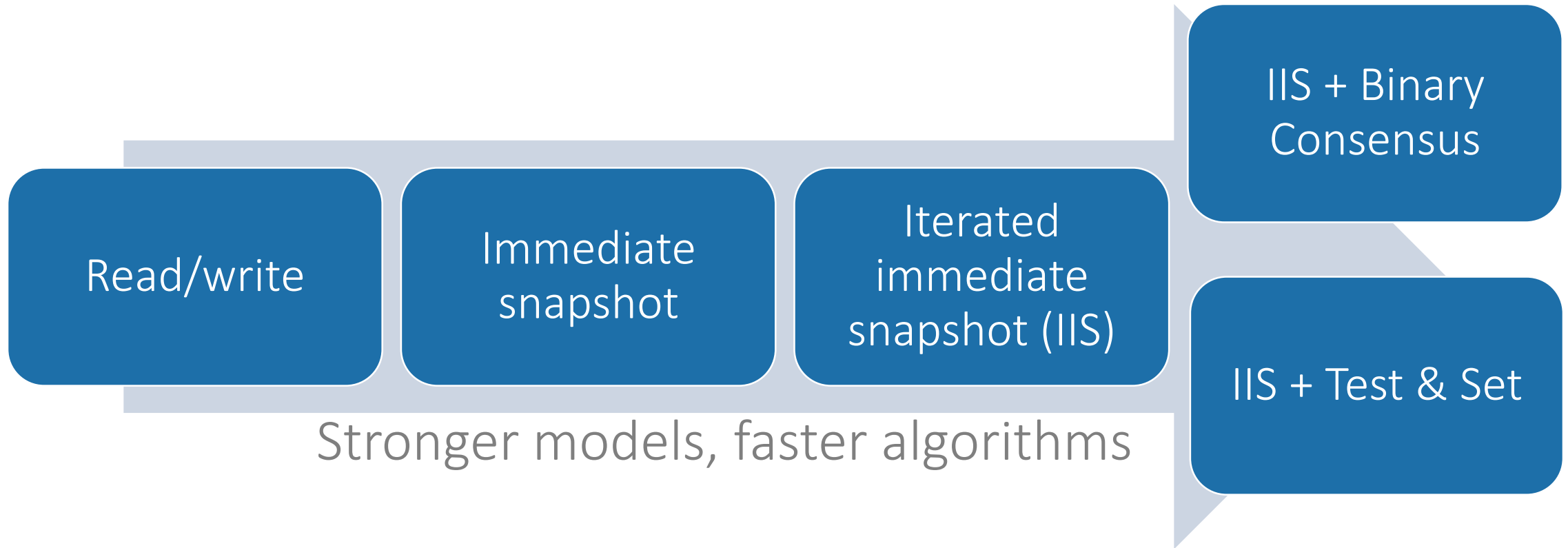
Read/write

Immediate
snapshot

Iterated
immediate
snapshot (IIS)

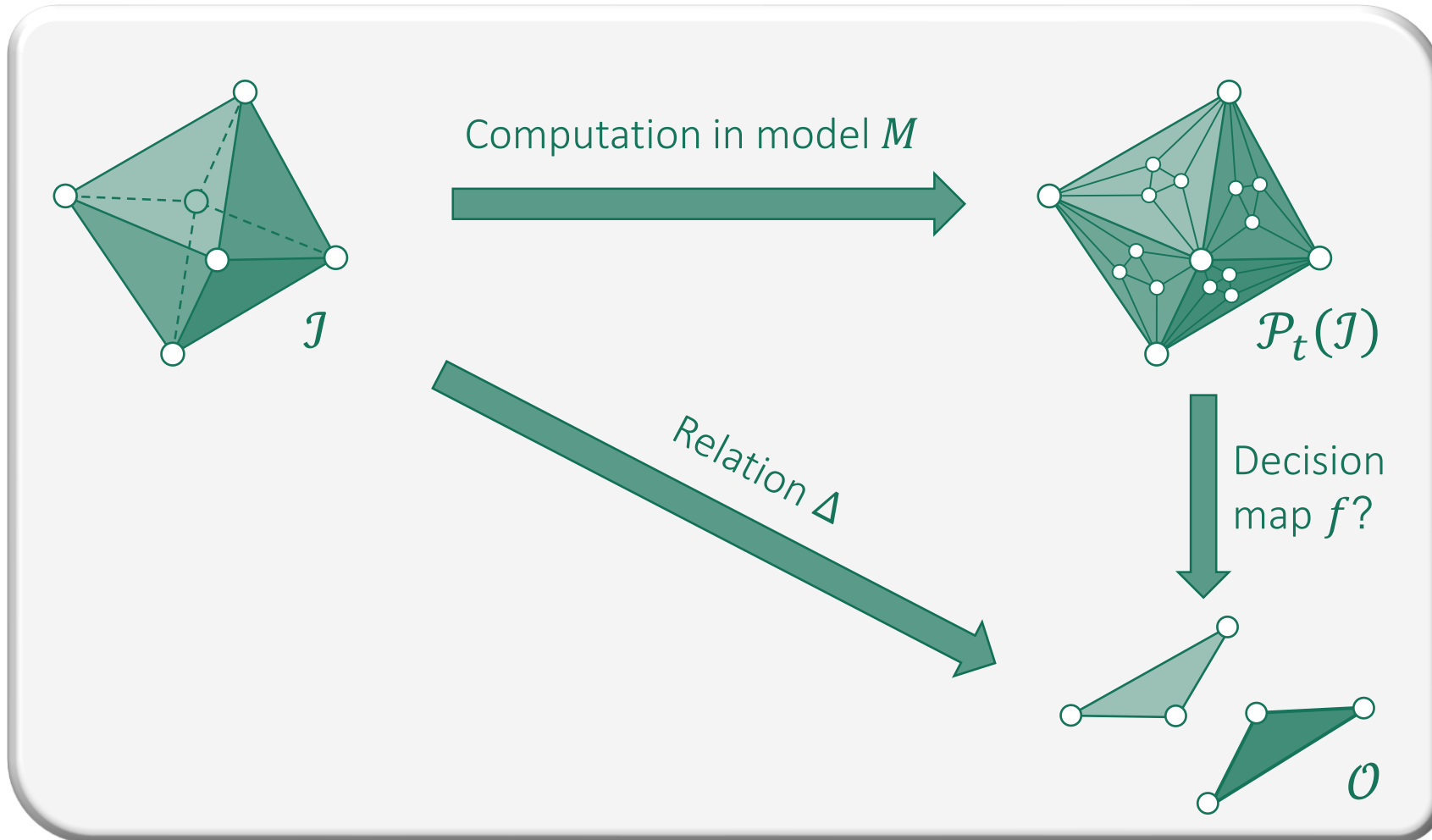
Stronger models, faster algorithms

Shared Memory Models



Tools

Tasks and Protocols



Theorem [HS99]:

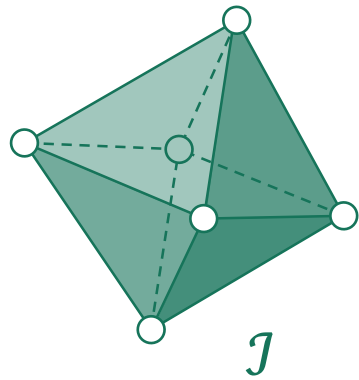
$(\mathcal{J}, \mathcal{O}, \Delta)$ is t -round solvable

\Leftrightarrow

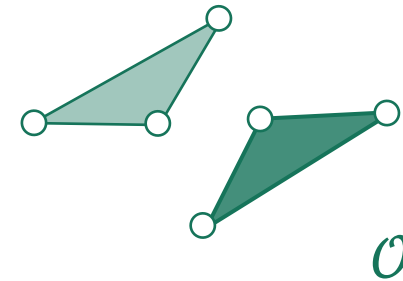
$\exists f: \mathcal{P}_t(\mathcal{J}) \rightarrow \mathcal{O}$
agreeing with Δ

A Task

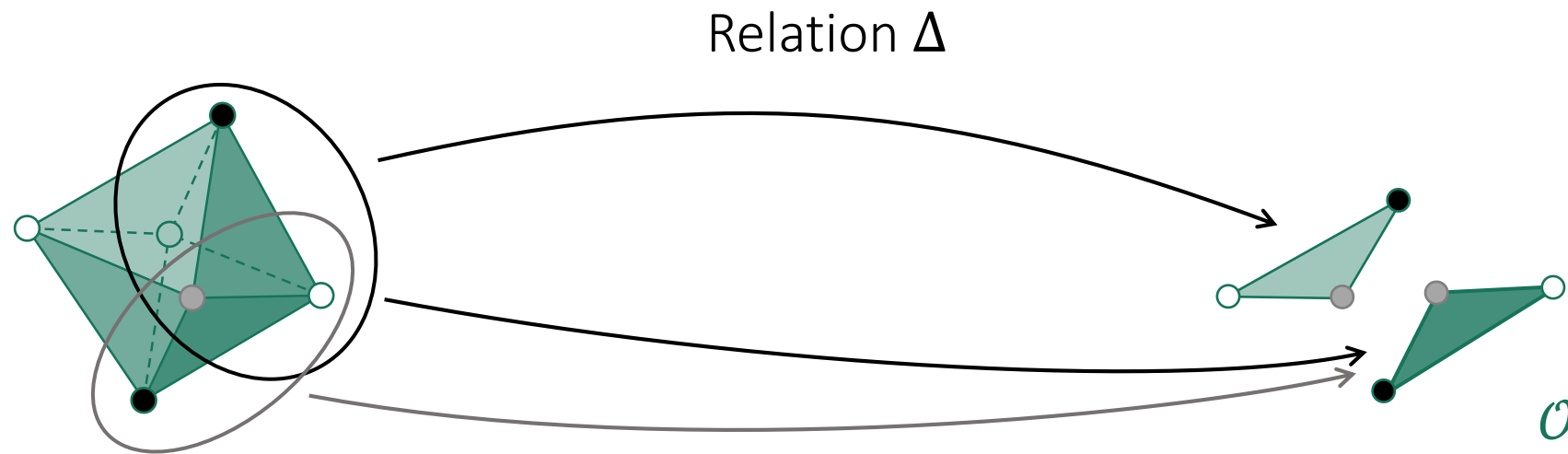
A task $\Pi = (\mathcal{J}, \mathcal{O}, \Delta)$



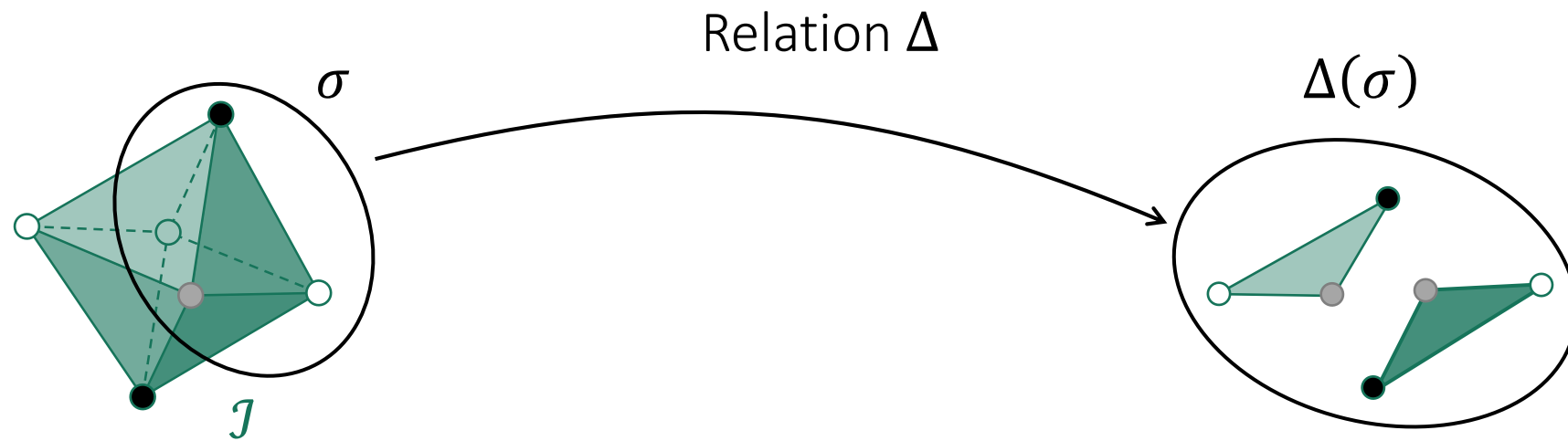
Relation Δ



A Task

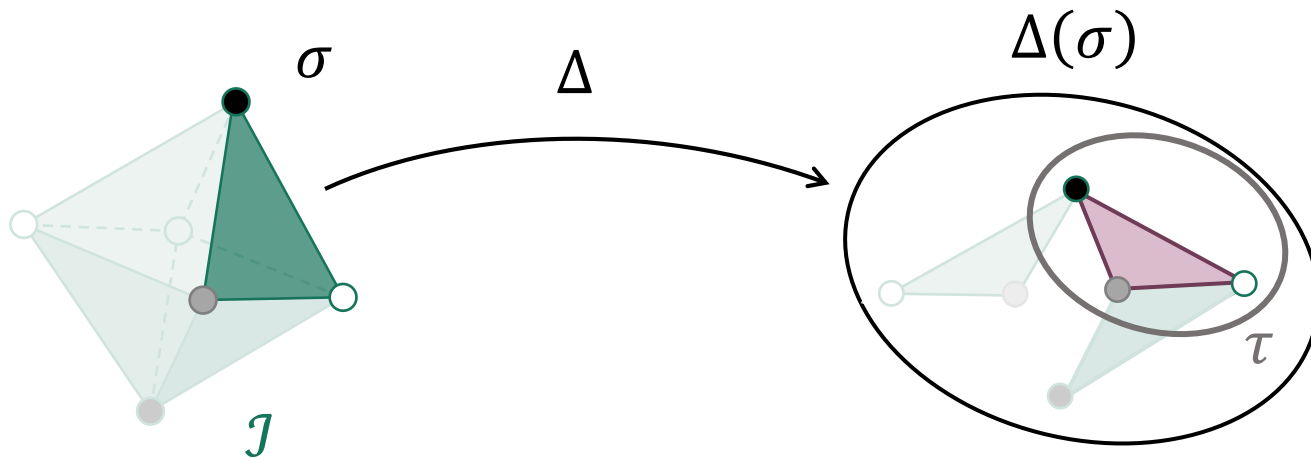


A Task



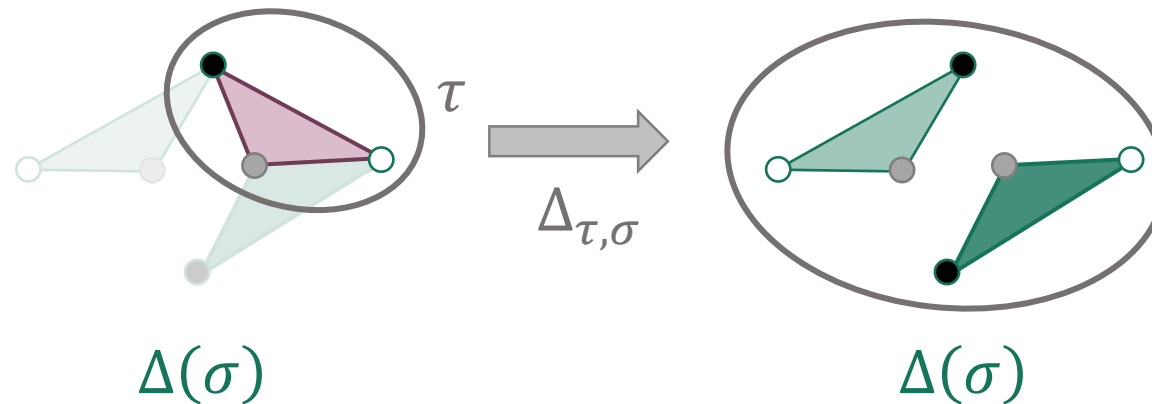
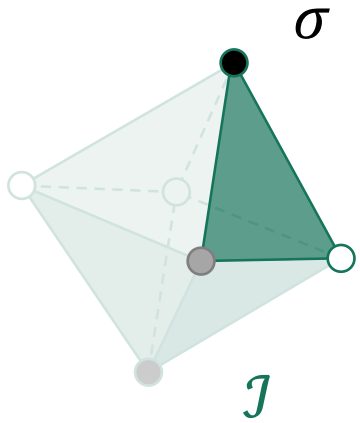
Definition: Local Task

- Given $\sigma \in \mathcal{J}$, $\tau \subseteq V(\Delta(\sigma))$



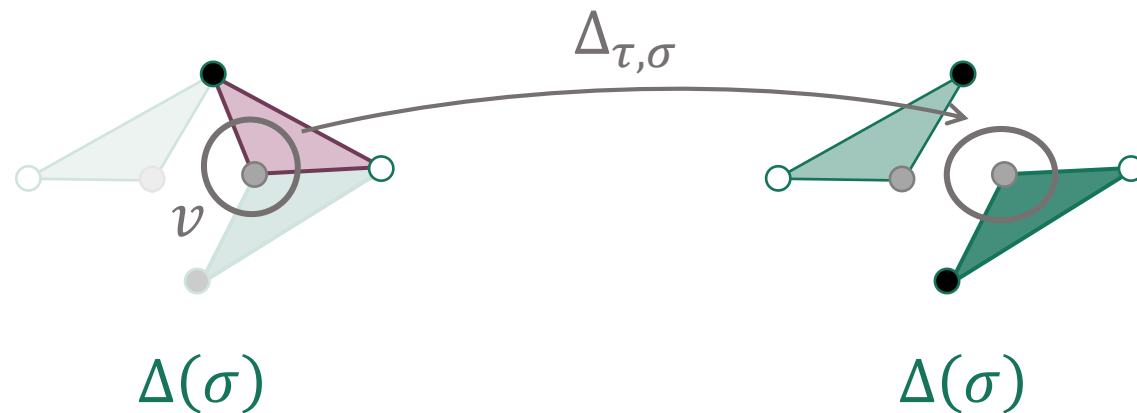
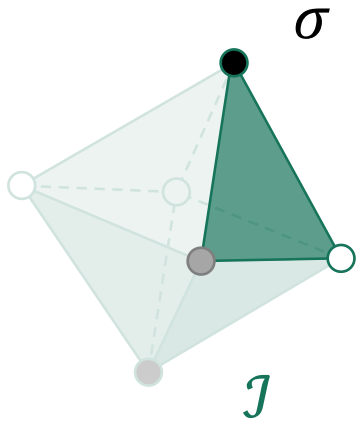
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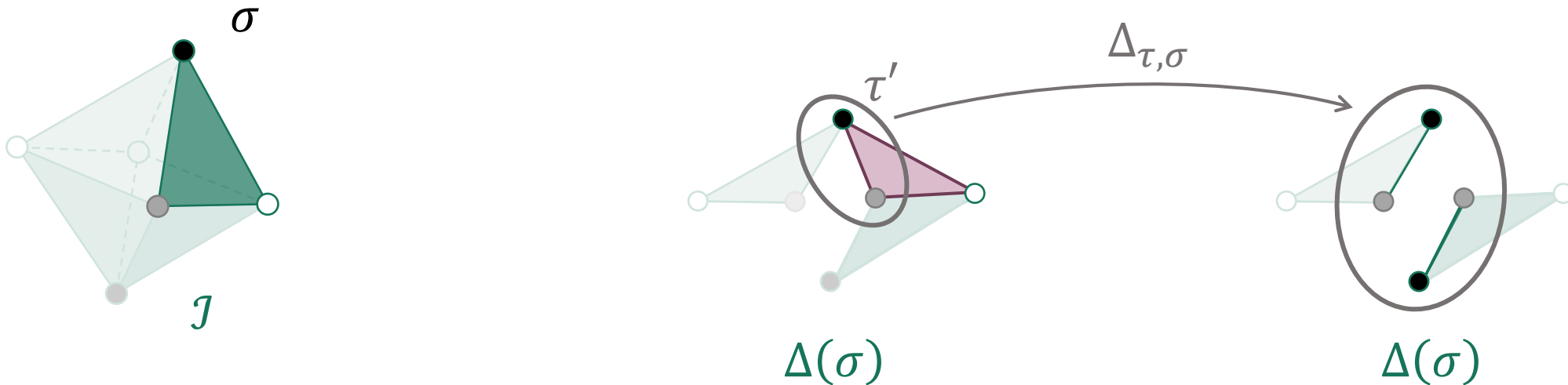
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 - $\forall v \in \tau: \Delta_{\tau, \sigma}(v) = \{v\}$



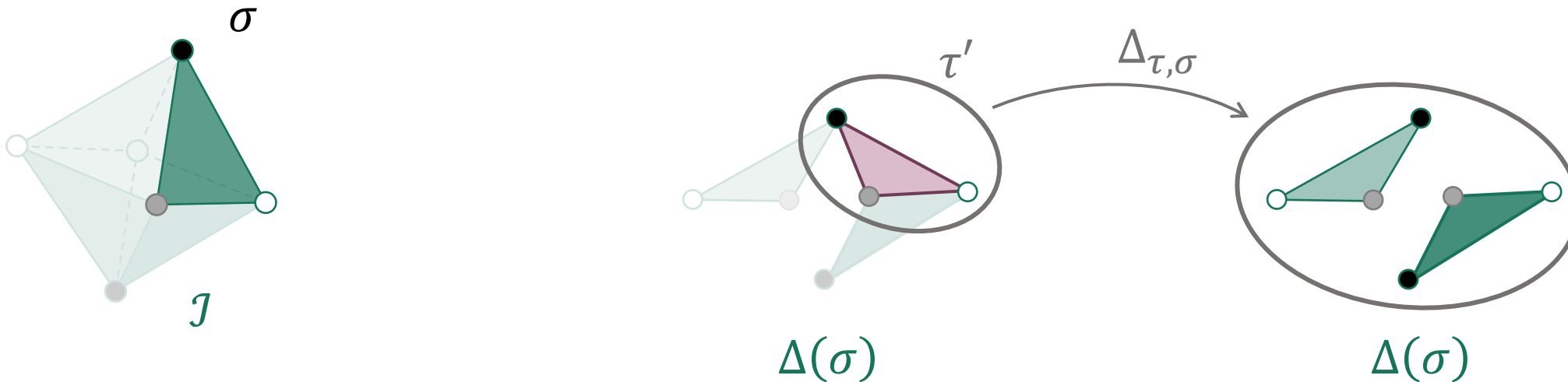
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 - $\forall v \in \tau: \Delta_{\tau, \sigma}(v) = \{v\}$
 - $\forall \tau' \subseteq \tau, |\tau'| > 1: \Delta_{\tau, \sigma}(\tau') = \text{proj}_{\text{id}(\tau')} \Delta(\sigma)$



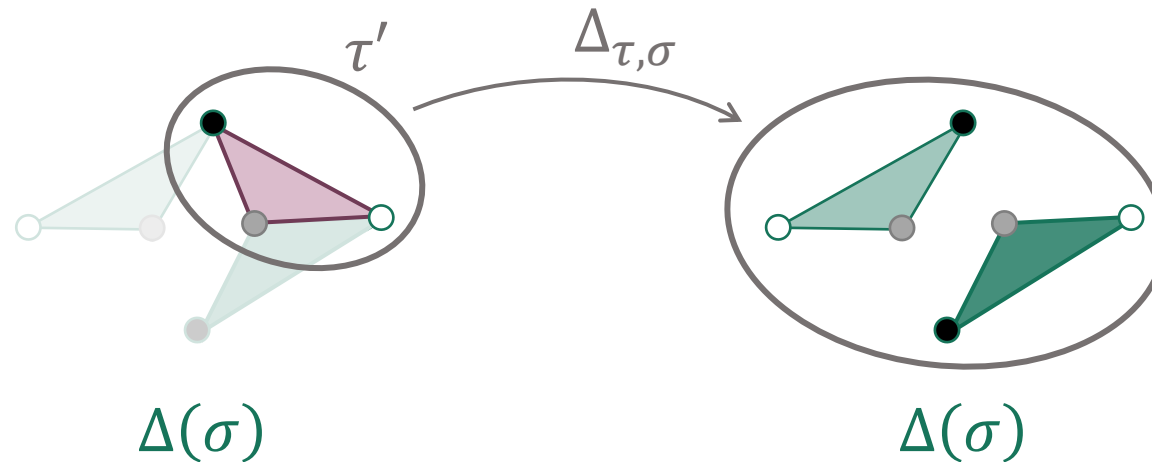
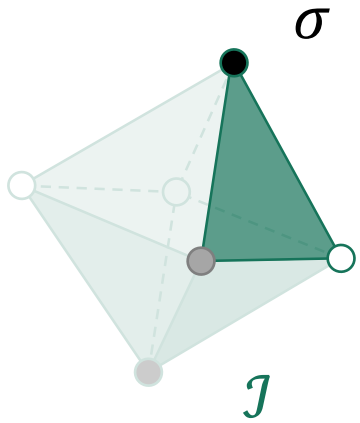
Definition: Local Task

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Definition: Local Task

- Given $\sigma \in \mathcal{J}$, $\tau \subseteq V(\Delta(\sigma))$, define **local task** $\Pi_{\tau,\sigma} = (\tau, \Delta(\sigma), \Delta_{\tau,\sigma})$, where $\Delta_{\tau,\sigma}$:
 - Vertex: itself
 - Not vertex: anywhere



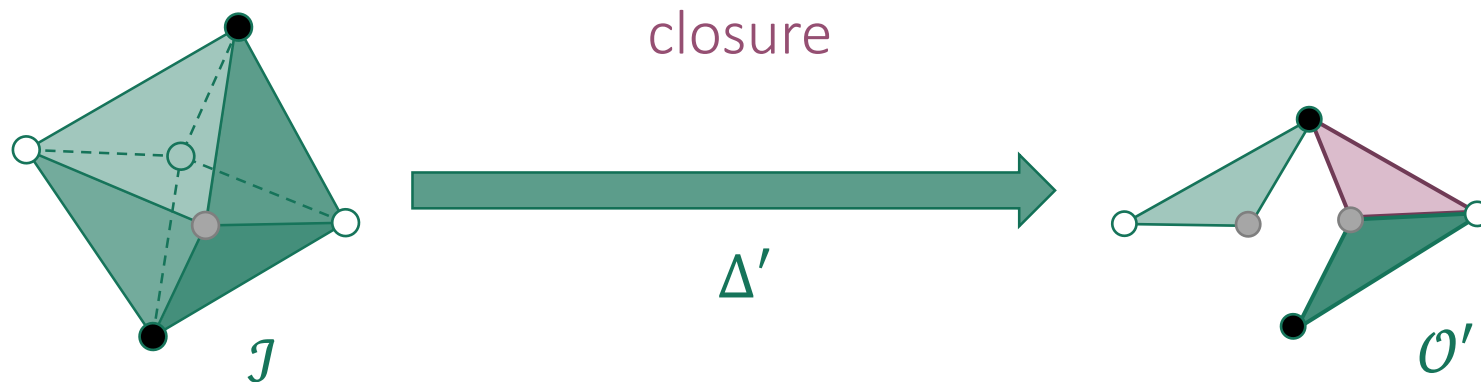
Definition: Closure Task

- The core of the technique: defining Π_{i-1}
- Given a task $\Pi = (\mathcal{J}, \mathcal{O}, \Delta)$ and a model M



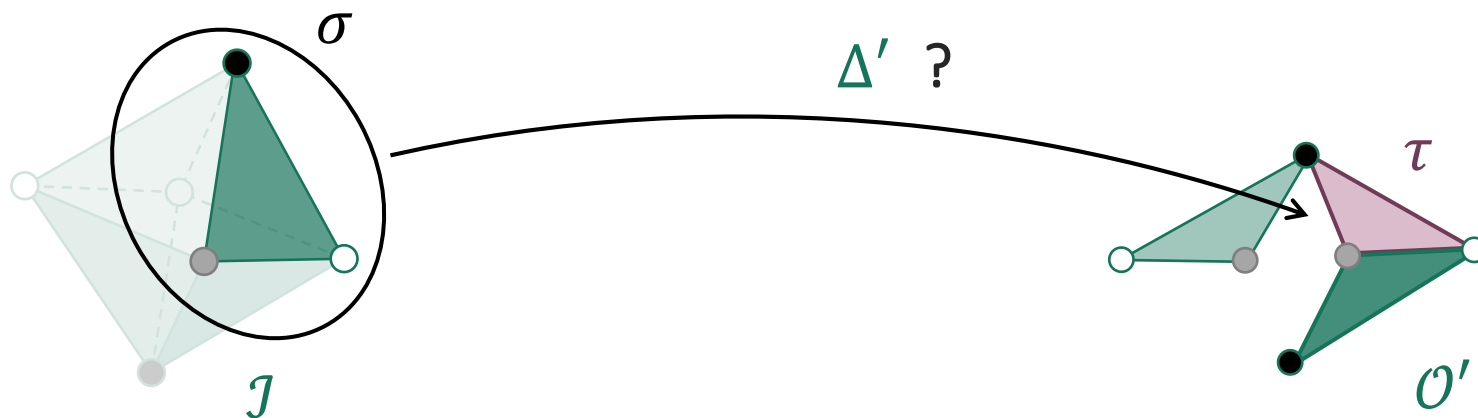
Definition: Closure Task

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- Given a task $\Pi = (\mathcal{J}, \mathcal{O}, \Delta)$ and a model M we define a closure task $\text{cl}_M(\Pi) = (\mathcal{J}, \mathcal{O}', \Delta')$



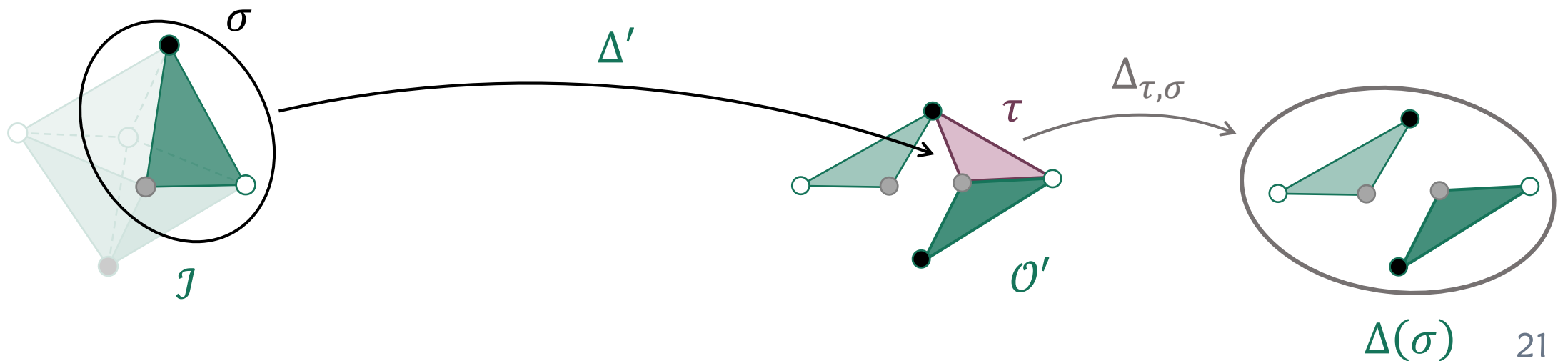
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 - $\forall \sigma \in \mathcal{J}, \tau \subseteq V(\Delta(\sigma)): \tau \in \Delta'(\sigma) ?$



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 - $\forall \sigma \in \mathcal{J}, \tau \subseteq V(\Delta(\sigma)): \tau \in \Delta'(\sigma) \iff$ the local task $\Pi_{\tau, \sigma}$ is 1-round solvable in M

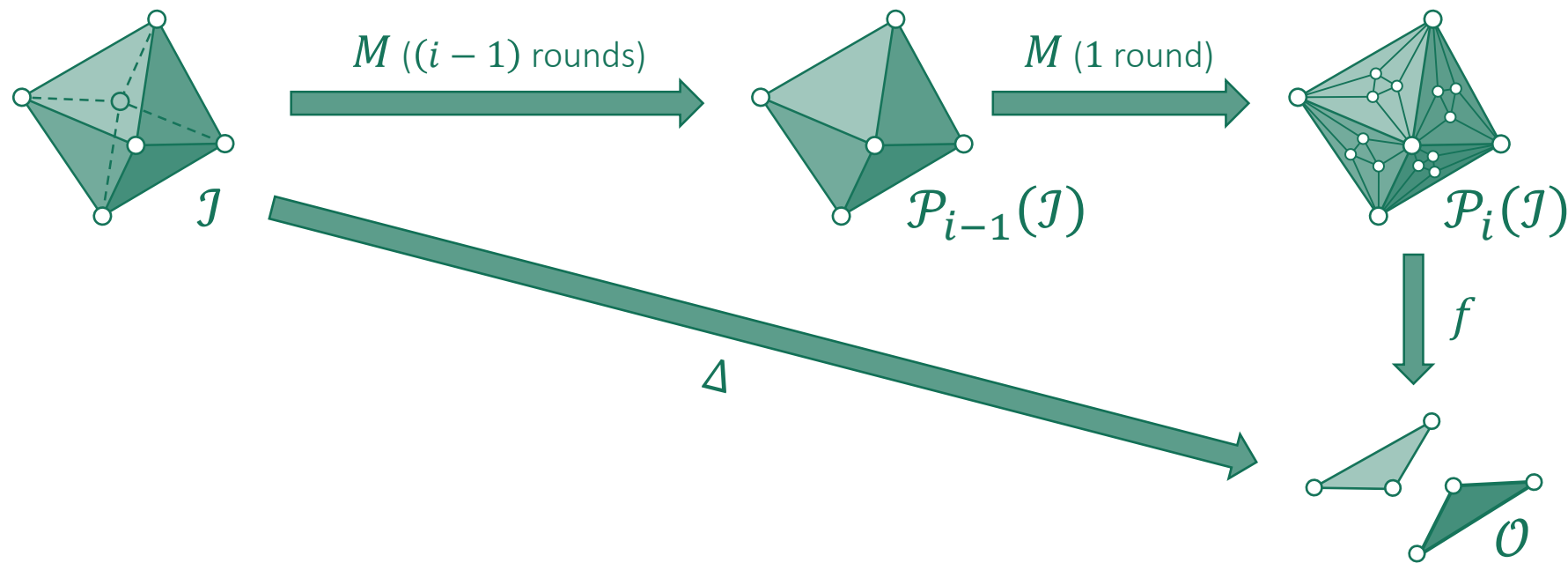


Main Theorem

Theorem: i -round algorithm for task Π in $M \Rightarrow$
 $(i - 1)$ -round algorithm for $\text{cl}_M(\Pi)$ in M

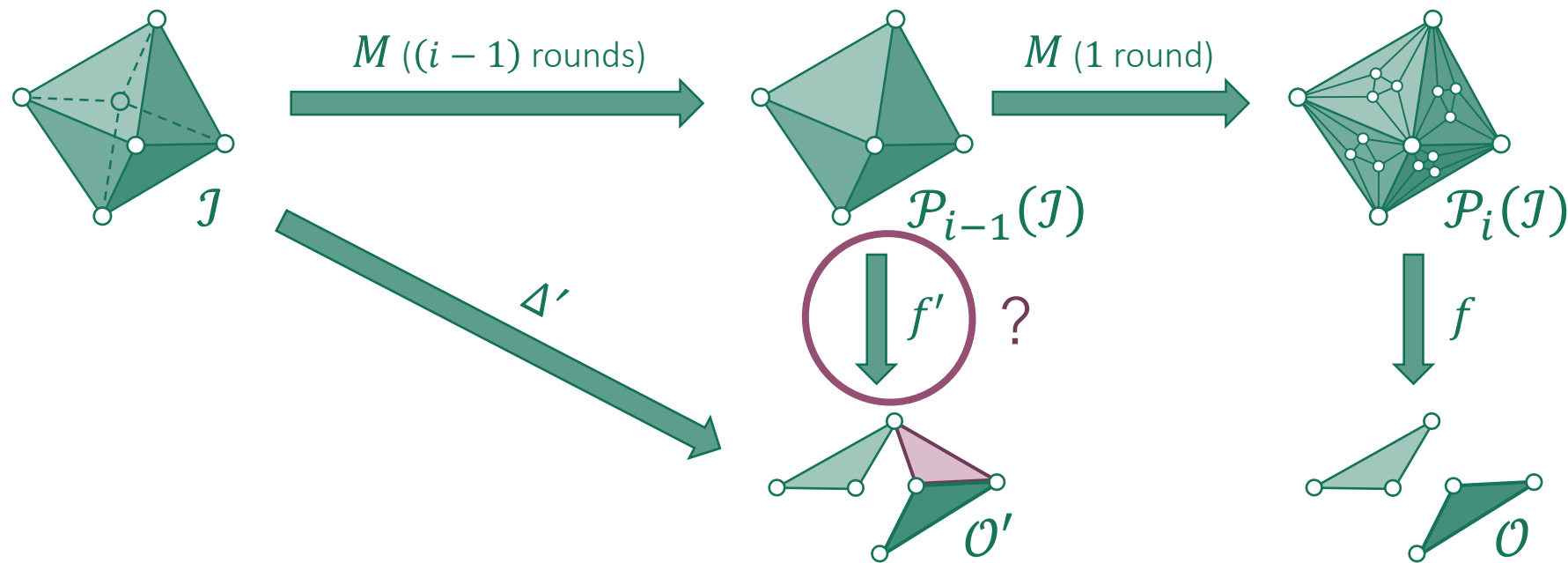
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Main Theorem

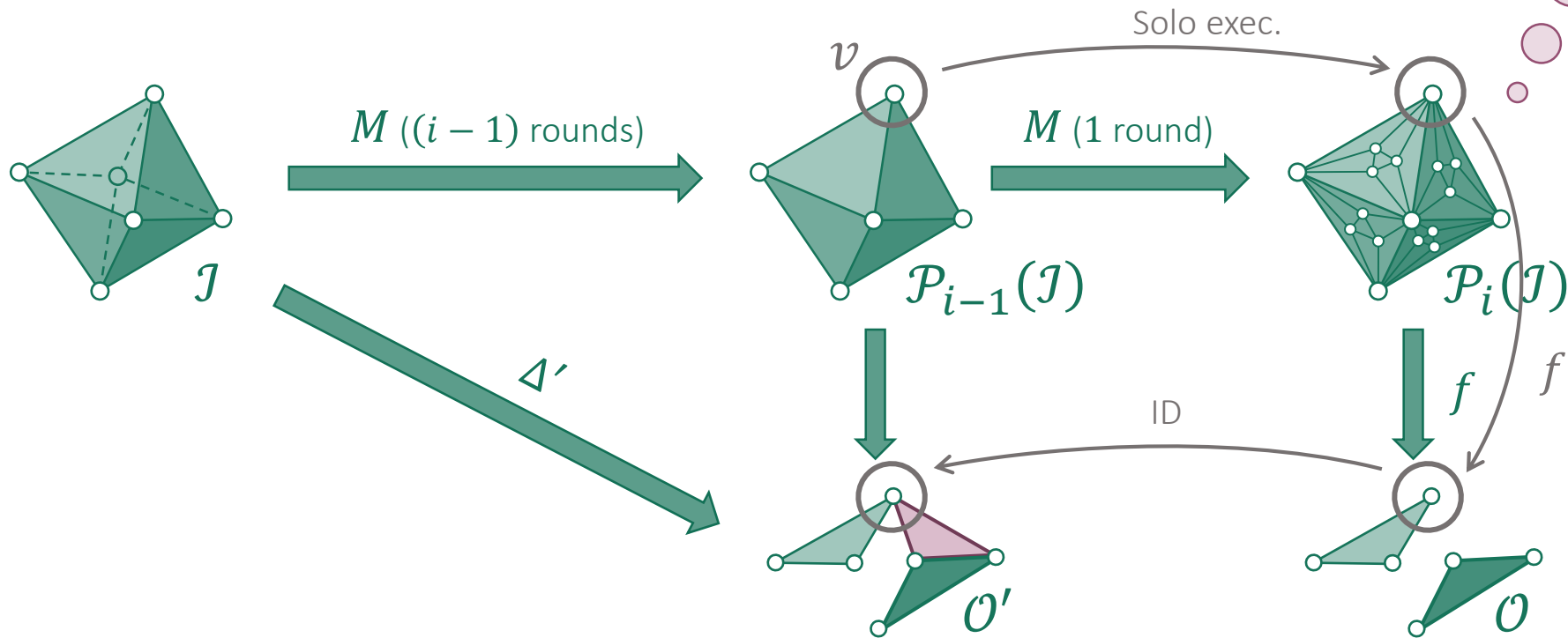
Theorem: i -round algorithm for task Π in $M \Rightarrow$
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Main Theorem

Theorem: i -round algorithm for task Π in $M \implies$
 $(i - 1)$ -round algorithm for $\text{cl}_M(\Pi)$ in M

Left to prove:
 This f' agrees with Δ'
 Exercise



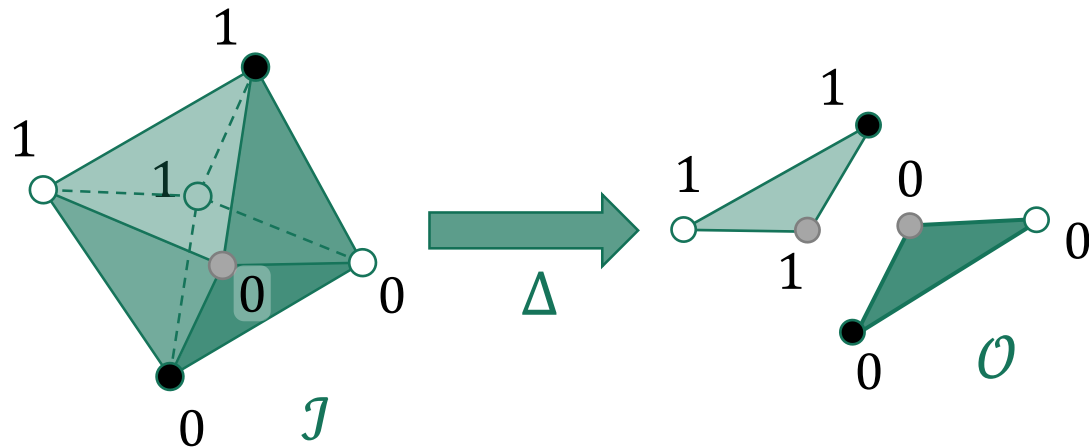
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Applications

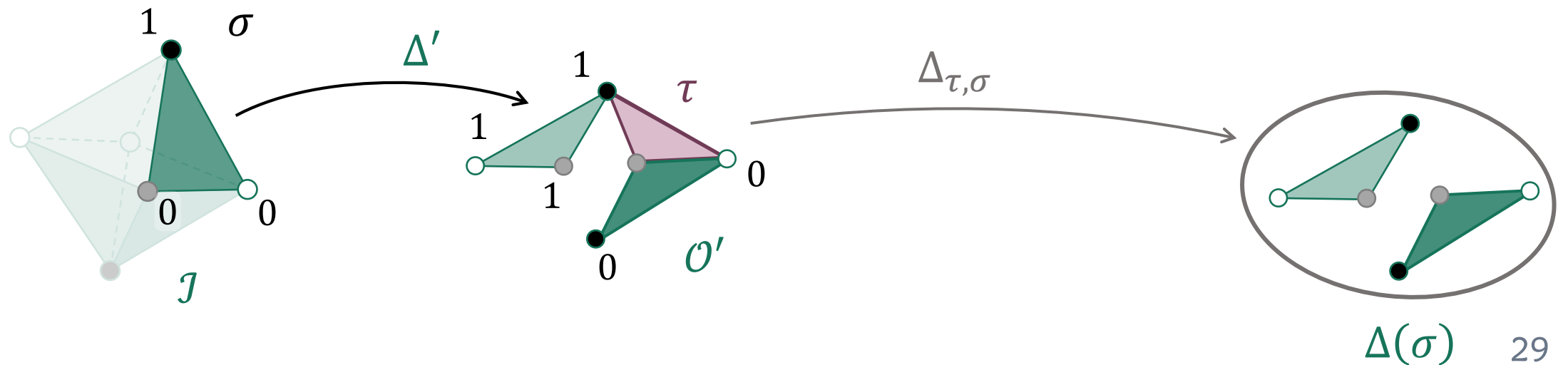
Impossibility of Consensus

- M = wait free iterated immediate snapshot
- $\Pi = (\mathcal{J}, \mathcal{O}, \Delta) = \text{Consensus}$
- $\text{cl}_M(\Pi) = ?$



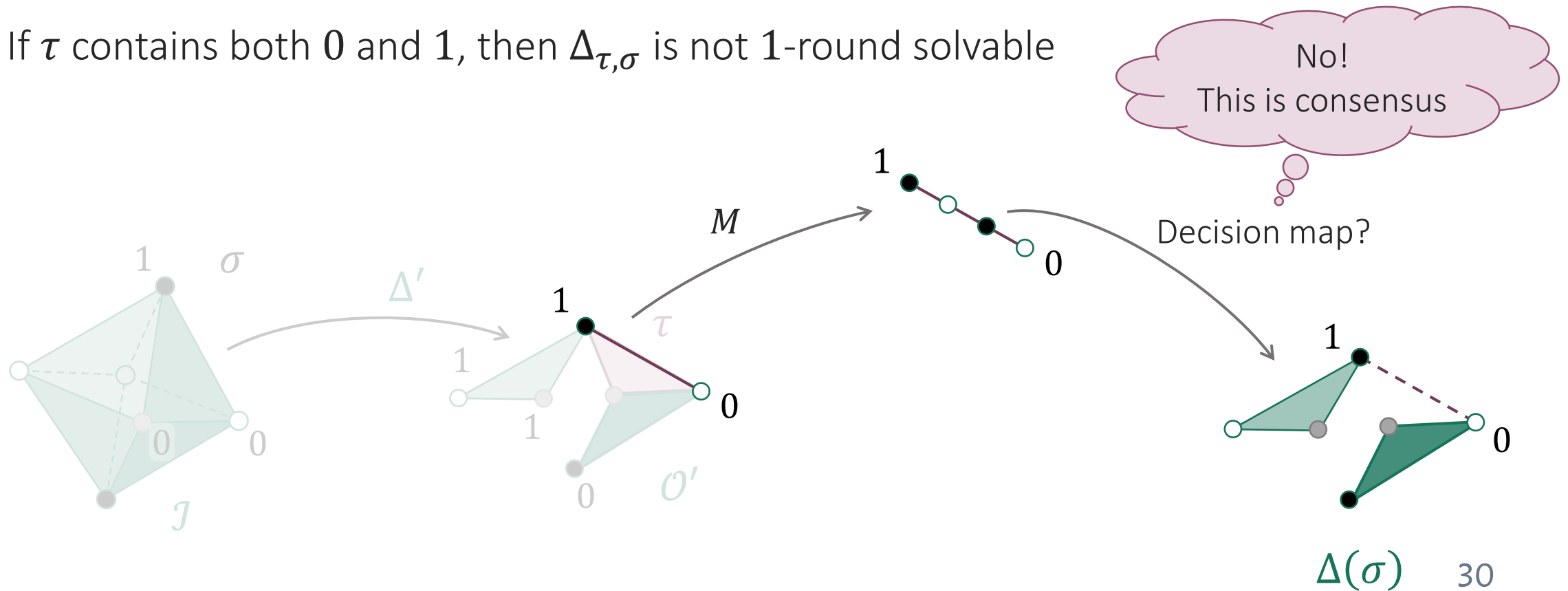
Impossibility of Consensus

- $\tau \in \Delta'(\sigma) \iff \Pi_{\tau,\sigma}$ is 1-round solvable in M
- If τ contains both 0 and 1, then $\Delta_{\tau,\sigma}$ is not 1-round solvable



Impossibility of Consensus

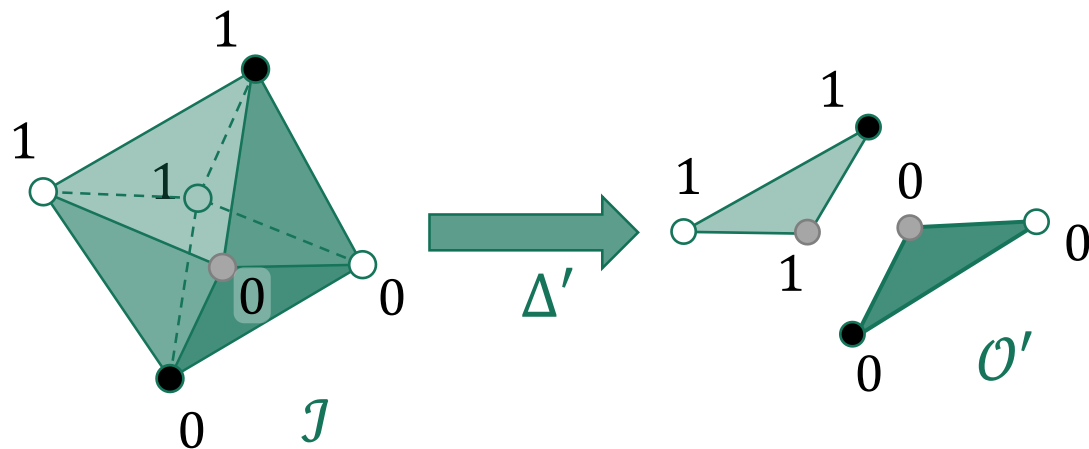
- $\tau \in \Delta'(\sigma) \iff \Pi_{\tau,\sigma}$ is 1-round solvable in M
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Impossibility of Consensus

- $\text{cl}_M(\Pi) = (\mathcal{J}, \mathcal{O}', \Delta')$ has the same simplices as $\Pi = (\mathcal{J}, \mathcal{O}, \Delta)$
- So for consensus $\text{cl}_M(\Pi) = \Pi$

Claim 1: i -round algorithm for consensus \implies
 $(i - 1)$ -round algorithm for consensus

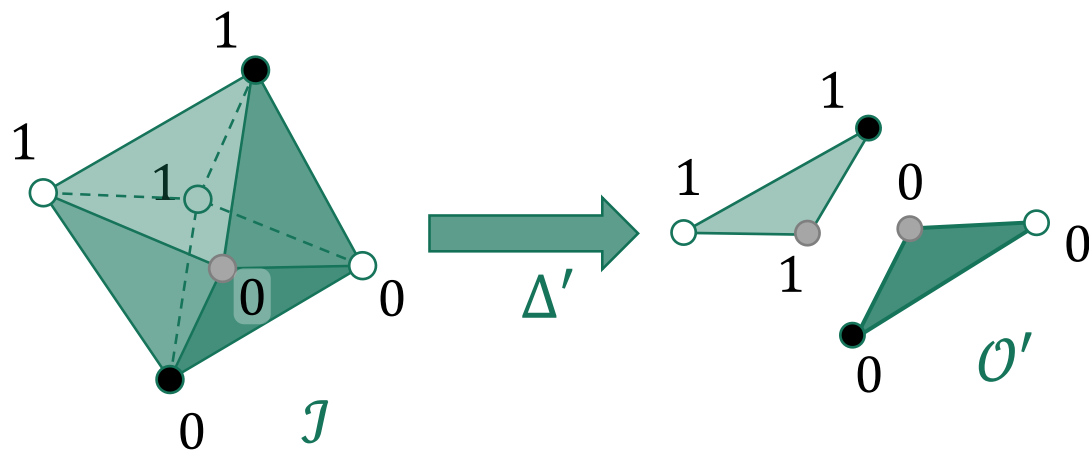


Impossibility of Consensus

Claim 1: i -round algorithm for consensus \Rightarrow $(i - 1)$ -round algorithm for consensus

Claim 2: No 0-round algorithm for consensus

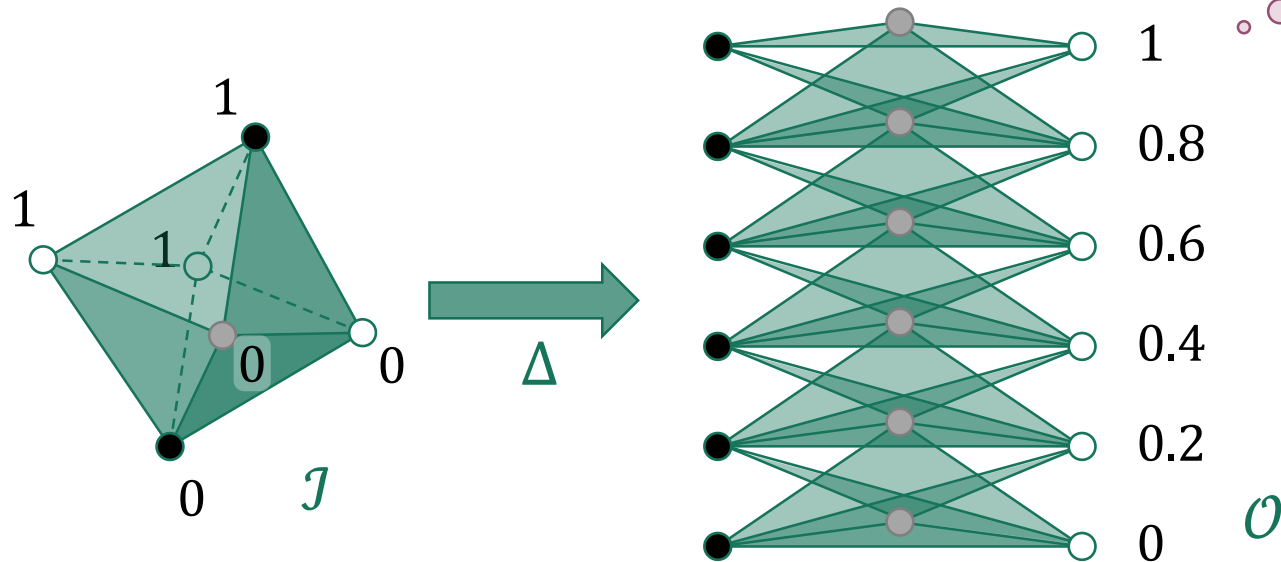
Conclusion: Impossibility of consensus in iterated immediate snapshot model



No matter in how many rounds

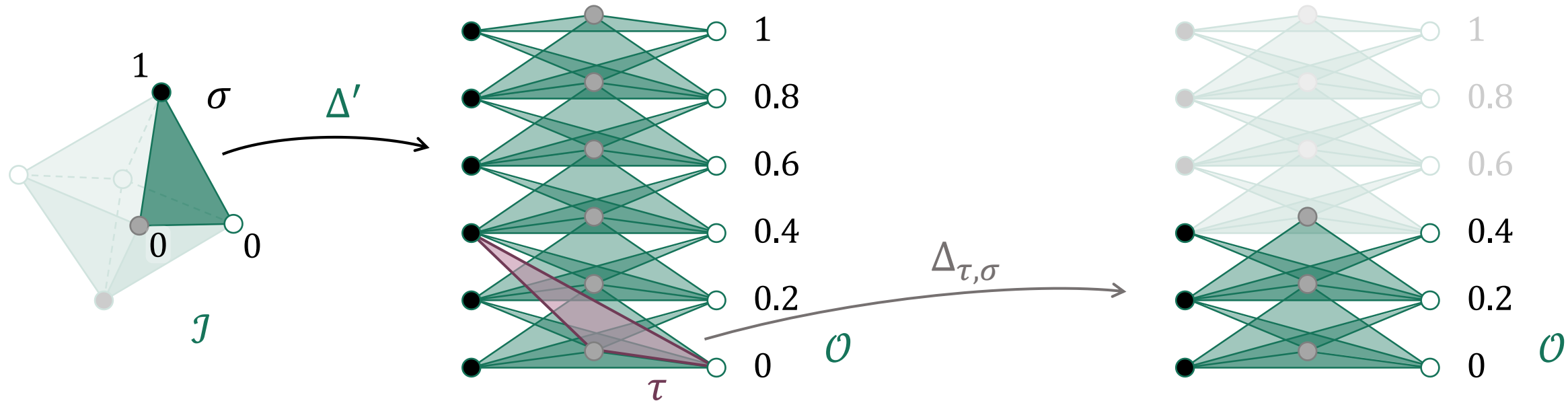
Approximate Agreement

- M = wait free iterated immediate snapshot
- $\Pi_\epsilon = (\mathcal{J}, \mathcal{O}, \Delta) = \epsilon$ -agreement
- $\text{cl}_M(\Pi_\epsilon) = ?$



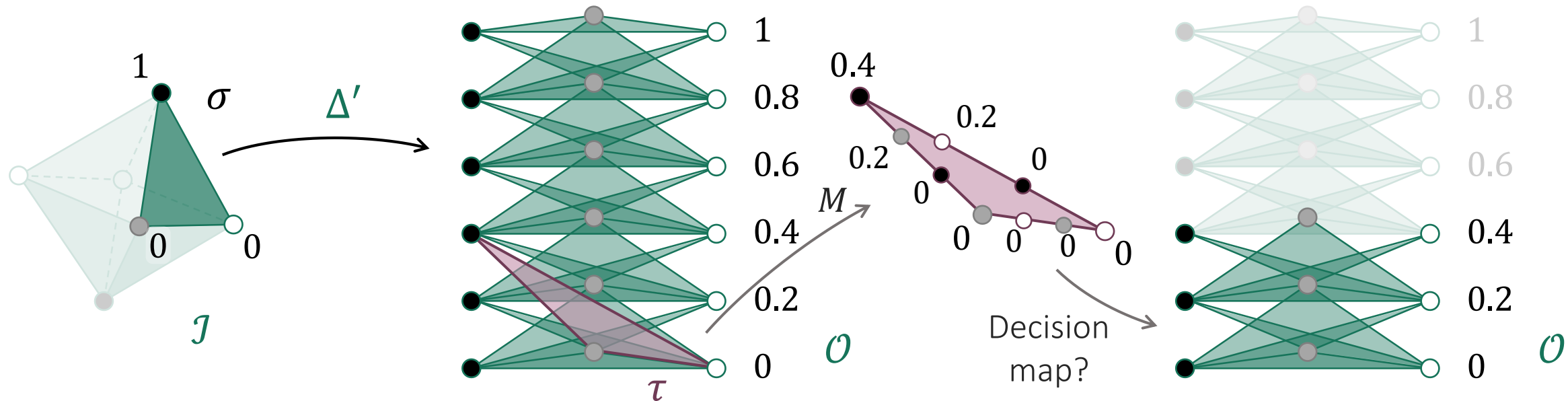
Approximate Agreement

- $\tau \in \Delta'(\sigma) \iff \Pi_{\tau,\sigma}$ is 1-round solvable in M



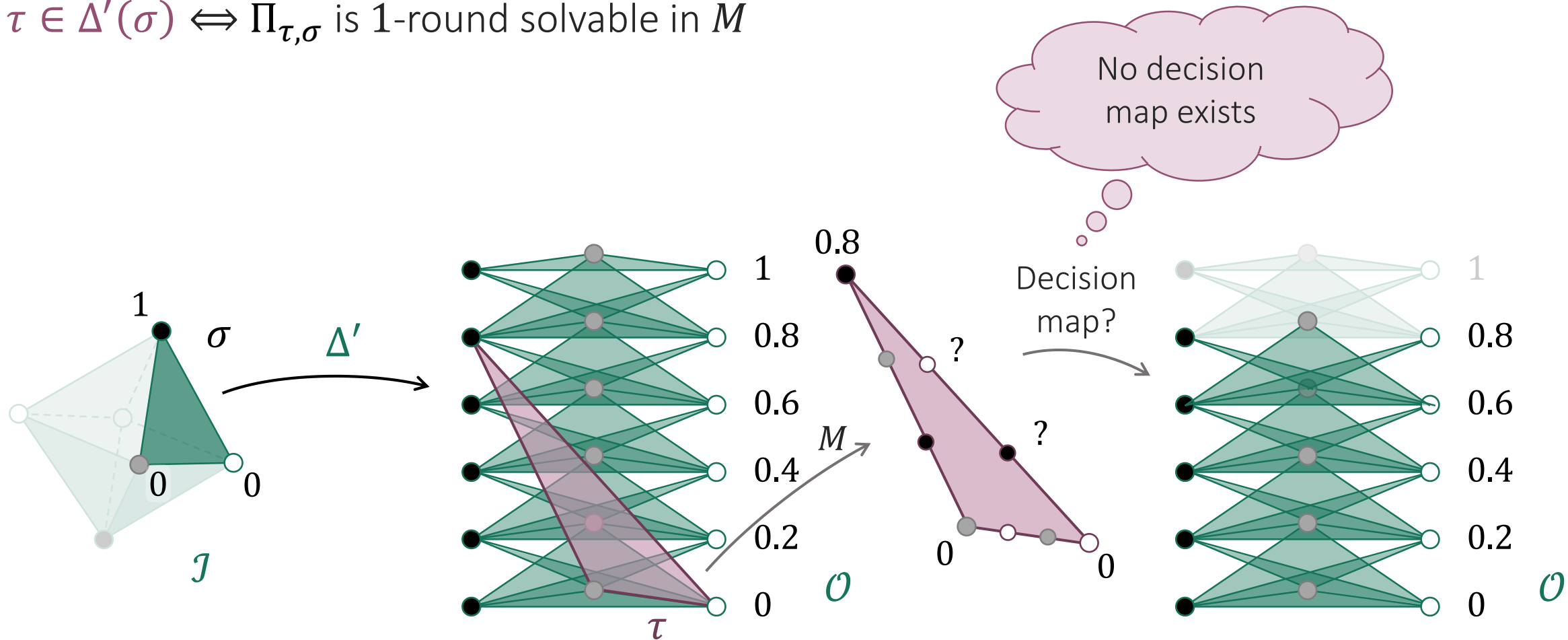
Approximate Agreement

- $\tau \in \Delta'(\sigma) \iff \Pi_{\tau, \sigma}$ is 1-round solvable in M



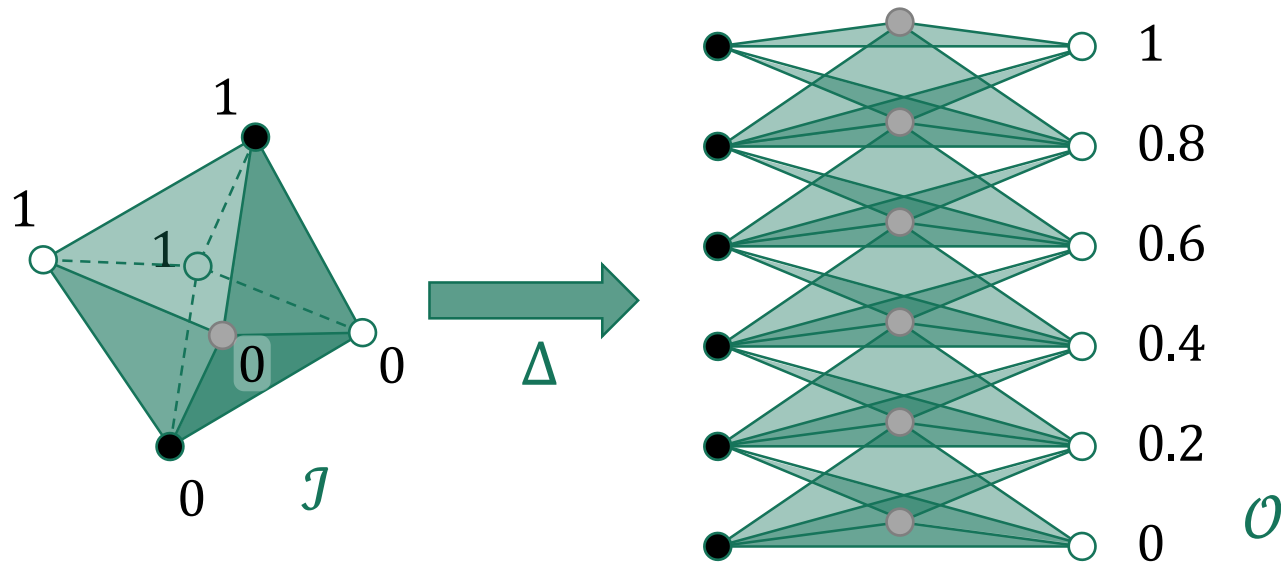
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Approximate Agreement

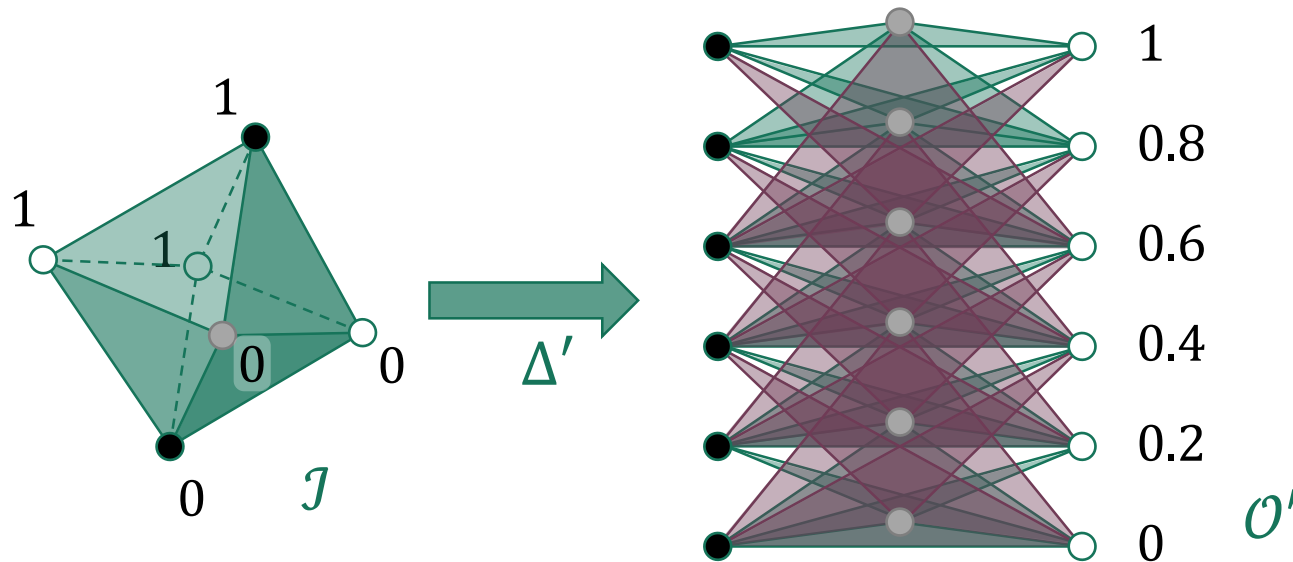
- $cl_M(\Pi_\epsilon) = ?$
 - Simplices of δ -agreement are in Δ' , but only for small δ
 - We show: $cl_M(\Pi_\epsilon) = 2\epsilon$ -agreement



Approximate Agreement

- $cl_M(\Pi_\epsilon) = cl_M(\Pi_{2\epsilon})$

Claim 1: i -round algorithm ϵ -agreement \Rightarrow
 $(i - 1)$ -round algorithm for 2ϵ -agreement



Approximate Agreement

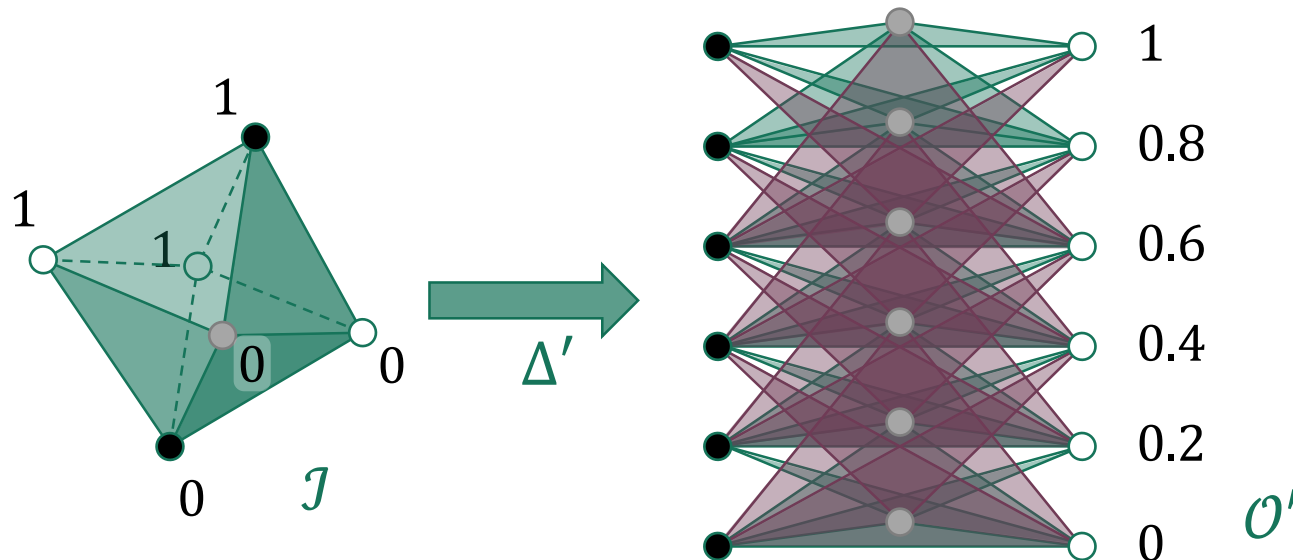
Claim 1: i -round algorithm ϵ -agreement \Rightarrow
 $(i - 1)$ -round algorithm for 2ϵ -agreement

Claim 2: No 0 -round alg. for δ -agreement, $\delta < 1$

If ϵ -agreement solvable in t rounds,
 2ϵ -agreement solvable in $t - 1$ rounds

...

$2^t \epsilon$ -agreement solvable in 0 rounds

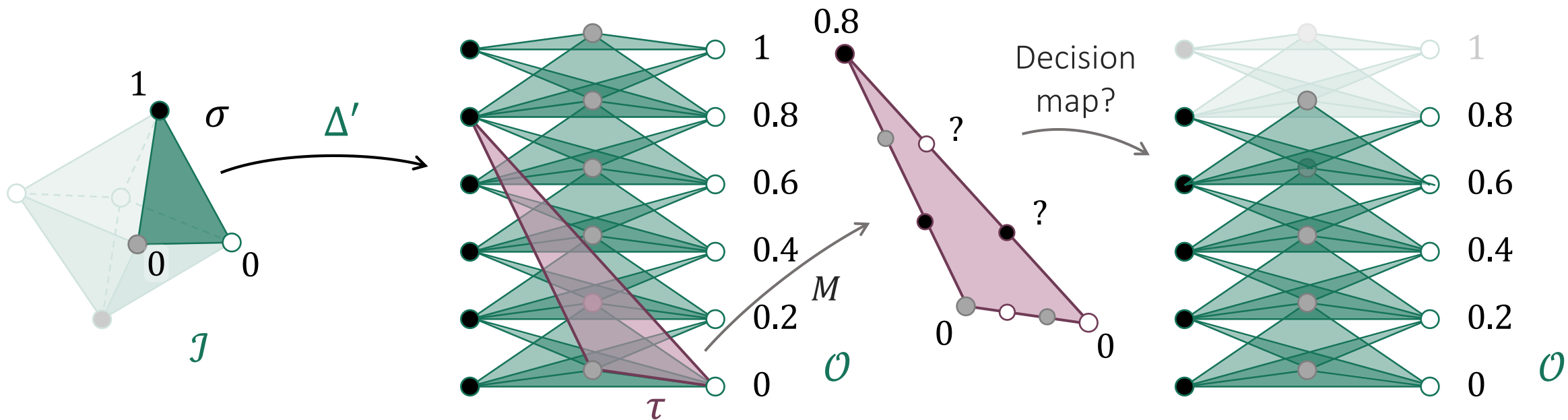


Conclusion:
 ϵ -agreement requires
 $\log_2 1/\epsilon$ rounds

With $n \geq 3$
 processes

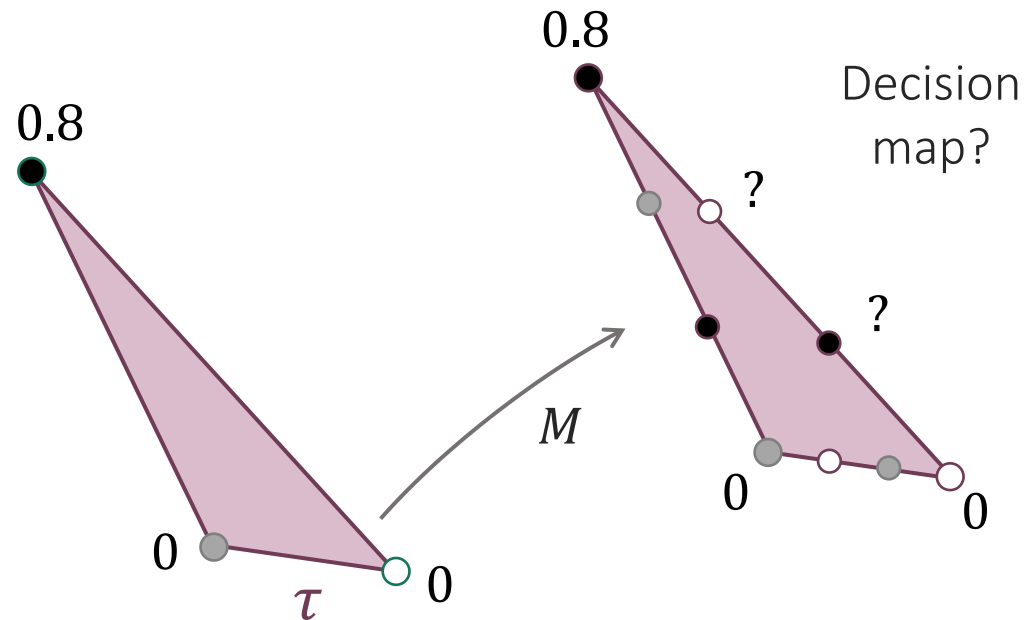
The Power of Simplicity

- Core of the proofs: What happens in a single round?



The Power of Simplicity

- Core of the proofs: What happens in a single round?
- Makes the proofs *easy to extend*



One Technique to Prove them All

Impossibility of consensus

Model
IIS
IIS + T&S

Consensus time lower bounds

Model	Time for $n = 2$	Time for $n \geq 3$
IIS	$\log_3 \epsilon$	$\log_2 \epsilon$
IIS + T&S	$\log_3 \epsilon$	$\log_2 \epsilon$
IIS + Bin. Consensus		$\min(\log_2 1/\epsilon, \log n - 1)$

