# A game-theoretic interpretation of Boolean operators in Strategic Reasoning

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#### System



(ouest-france.fr)



#### Requirements



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#### Requirements

#### • Parking maneuver

#### System



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- Parking maneuver
- Anti-collision guarantee

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- Traffic protocols

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- Parking maneuver
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Models are games









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 $\pi = p_1 p_2 \ldots$  is a play



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 is a play

# Wining conditions for a coalition Coalition wins if the play $\pi \in$ Win with Win $\subseteq$ Plays



 $\pi = p_1 p_2 \ldots$  is a play

#### Wining conditions for a coalition

Coalition wins if the play  $\pi \in \mathsf{Win}$  with  $\mathsf{Win} \subseteq \mathsf{Plays}$ 

Formalization of requirement in Strategy logic

### Anti-collision guarantee

$$\begin{array}{lll} \Phi_{ACG} = & \forall strat_{car} \ \exists strat_{shuttle} \ (car, strat_{car})(shuttle, strat_{shuttle}) \\ & \Box(\operatorname{crash}(car, shuttle) \rightarrow \neg \operatorname{at\_fault}(shuttle)) \end{array}$$

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#### One goal formula

Formula of the form  $Qstrat_1 Qstrat_2 \dots b\psi$  with  $\psi$  a temporal formula

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$$\begin{array}{ll} \Phi_{TP} = & \forall strat_{car} \exists strat_{shuttle} \ (car, strat_{car})(shuttle, strat_{shuttle}) \\ & \Box(\texttt{cross}(car, shuttle) \rightarrow (\texttt{prio}(shuttle) \leftrightarrow \texttt{pass}(shuttle))) \end{array}$$

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We want only one *strat*<sub>shuttle</sub> !

#### Both at once

 $\forall strat_{car_1} \forall strat_{car_2} \exists strat_{shuttle} \\ (car, strat_{car_1})(shuttle, strat_{shuttle}) \psi_{ACG} \land (car, strat_{car_2})(shuttle, strat_{shuttle}) \psi_{TP}$ 

 $\begin{array}{l} & \text{Problem !} \\ \forall \ \textit{strat}_{\textit{car}_1} \ \forall \ \textit{strat}_{\textit{car}_2} \ \exists \ \textit{strat}_{\textit{shuttle}}, \end{array}$ 

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Definition: strategy in a game

strat : Hist  $\rightarrow Ac$ 

where Hist is the set of histories and Ac the set of actions

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Definition: strategy in a game

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Solution !  $\forall^{R} strat_{car_{1}} \forall^{R} strat_{car_{2}} \exists^{R} strat_{shuttle},$ 

Definition: strategy in a game strat : Hist  $\rightarrow$  Ac where Hist is the set of histories and Ac the set of actions



- History deterministic automata:
  - T. Colcombet. The theory of stabilisation monoids and regular cost functions. ICALP 2009.
  - ► U. Boker, K. Lehtinen. When a little nondeterminism goes a long way: An introduction to history-determinism. ACM SIGLOG News 2023.

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- Timeline semantics:
  - P. Gardy, N. Markey, P. Bouyer. Dependences in Strategy Logic. TCS 2020.
#### Idea

Given  $\Phi \in \operatorname{SL}$  and G a CGS, build

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 $\label{eq:Given} \begin{array}{l} \mathsf{Given} \ \Phi \in \mathrm{SL} \ \text{and} \ \mathsf{G} \ \mathsf{a} \ \mathsf{CGS}, \ \mathsf{build} \\ \bullet \ \mathsf{CGS}_{\mathrm{GTS}}(\mathsf{G}, \Phi) \ \mathsf{a} \ \mathsf{new} \ \mathsf{CGS} \end{array}$ 

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#### Realizable semantics

$$\mathsf{G}\models_{\boldsymbol{R}} \Phi \text{ iff } \mathsf{CGS}_{\mathrm{GTS}}(\mathsf{G}, \Phi)\models \Phi_{\mathrm{GTS}}(\Phi)$$

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#### Realizable semantics

$$\mathsf{G}\models_{\boldsymbol{R}} \Phi \text{ iff } \mathsf{CGS}_{\mathrm{GTS}}(\mathsf{G}, \Phi)\models \Phi_{\mathrm{GTS}}(\Phi)$$

Because realizable strategy suffice for one goal formula [Mogavero, F., Murano, A., Perelli, G., & Vardi, M. Y. (2014). Reasoning about strategies: On the model-checking problem. ]



#### Original game G



#### Original formula $\Phi$

$$D = \begin{array}{c} \forall strat_{car_{1}} \forall strat_{car_{2}} \exists strat_{shuttle} \\ \flat_{ACG} \psi_{ACG} \land \flat_{TP} \psi_{TP} \end{array}$$

with

C

 $\begin{array}{ll} \flat_{ACG} = & (car, strat_{car_1})(shuttle, strat_{shuttle}) \\ \flat_{TP} = & (car, strat_{car_2})(shuttle, strat_{shuttle}) \end{array}$ 

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# Building the game $\mathsf{CGS}_{\mathrm{GTS}}(\mathsf{G}, \Phi)$

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 $b_{ACG} = (car, strat_{car_1})(shuttle, strat_{shuttle})$  $b_{TP} = (car, strat_{car_2})(shuttle, strat_{shuttle})$ 

strat<sub>car1</sub> strat<sub>cary</sub> strat<sub>shuttle</sub>





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# Building the game $\mathsf{CGS}_{\mathrm{GTS}}(\mathsf{G}, \Phi)$



strat <sub>car1</sub>	$\mapsto$	right
strat <sub>car2</sub>	$\mapsto$	left
strat <sub>shuttle</sub>	$\mapsto$	left





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strat <sub>car1</sub>	$\mapsto$	right
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•ACG		
shuttle	$\mapsto$	left
car	$\mapsto$	right



strat <sub>car1</sub>	$\mapsto$	right
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♭ <sub>ACG</sub> shuttle car	$\stackrel{\rightarrow}{\mapsto}$	left right
♭ <sub>TP</sub> shuttle car	$\stackrel{\rightarrow}{\rightarrow}$	left left

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#### Original formula Φ

d

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$$\mathcal{D} = \begin{array}{c} \forall strat_{car_{1}} \; \forall strat_{car_{2}} \; \exists strat_{shuttle} \\ \flat_{ACG} \psi_{ACG} \land \flat_{TP} \psi_{TP} \end{array}$$

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▶ <sub>ACG</sub>		
shuttle	$\mapsto$	left
car	$\mapsto$	right
$b_{TP}$		
shuttle	$\mapsto$	left
car	$\mapsto$	left

#### Original game G *shuttle* $\mapsto$ right left car $\mapsto$ $p_1$ **p**3 $p_2$ left shuttle right left $\mapsto$ right right left car $\mapsto$

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$$\begin{array}{ccc} \flat_{ACG} \\ shuttle & \mapsto & \texttt{left} \\ car & \mapsto & \texttt{right} \\ \\ \flat_{TP} \\ shuttle & \mapsto & \texttt{left} \\ car & \mapsto & \texttt{left} \end{array}$$

đ



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	<b>p</b> 2
$\mapsto$	left
$\mapsto$	right
	-
$\mapsto$	left
$\mapsto$	left
	$\stackrel{1}{\rightarrow}$ $\stackrel{1}{\rightarrow}$ $\stackrel{1}{\rightarrow}$

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d



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ACG		$p_2$
shuttle	$\mapsto$	left
car	$\mapsto$	right
b <sub>TP</sub>		<b>p</b> 2
shuttle	$\mapsto$	left
car	$\mapsto$	left

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#### Original game G Original formula $\Phi$ *shuttle* $\mapsto$ right left $\forall strat_{car_1} \forall strat_{car_2} \exists strat_{shuttle} \\ \flat_{ACG} \psi_{ACG} \land \flat_{TP} \psi_{TP}$ *car* $\mapsto$ left right $\Phi =$ with $p_1$ $p_2$ $p_3$ $b_{ACG} = (car, strat_{car_1})(shuttle, strat_{shuttle})$ right $b_{TP} = (car, strat_{car_2})(shuttle, strat_{shuttle})$ shuttle $\mapsto$ left right left car $\mapsto$ strat<sub>car1</sub> right $\mapsto$ $strat_{car_2} \mapsto left$ ACG strat<sub>shuttle</sub> right $\mapsto$ shuttle $\mapsto$ right car $\mapsto$ $p_2$ PACG b<sub>TP</sub>

 $p_3$ 

right













### The $\Phi_{\rm GTS}(\Phi)$ formula

 $\label{eq:Given} \mathsf{Given} \ \Phi = \ \forall \textit{strat}_{\textit{car}_1} \ \forall \textit{strat}_{\textit{car}_2} \ \exists \textit{strat}_{\textit{shuttle}} \ \flat_{\textit{ACG}} \psi_{\textit{ACG}} \land \flat_{\textit{TP}} \psi_{\textit{TP}} \ ,$ 

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We define 
$$\Phi_{\text{GTS}}(\Phi) = \begin{array}{c} \forall strat_{car_1} \forall strat_{car_2} \exists strat_{shuttle} \forall strat_{AND} \flat_{id} \\ (\Box \flat_{ACG} \rightarrow \psi_{ACG}) \land (\Box \flat_{TP} \rightarrow \psi_{TP}) \end{array}$$

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#### Theorem

For every CGS G and  ${\rm SL}[{\rm C}/{\rm DG}]$  formula  $\Phi,$  we have

$$CGS_{GTS}(G, \Phi) \models \Phi_{GTS}(\Phi) \text{ iff } G \models_{\mathcal{T}} \Phi$$

where  $\models_{\mathcal{T}}$  is defined in [P. Gardy, N. Markey, P. Bouyer. Dependences in Strategy Logic.]

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To be published in FSTTCS24

### Conclusion

Game theoretic semantics

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#### Game theoretic semantics

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#### future work

- Extend the result for bigger fragments (with both "and" and "or")
- Compare with the standard semantics

Thank you for listening!