# Quantitative Inhabitation for Different Lambda Calculi in a Unifying Framework

Victor Arrial <sup>1</sup> Giulio Guerrieri <sup>2,3</sup> Delia Kesner <sup>1,4</sup>

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<sup>3</sup>Edinburgh Research Centre, Huawei, Edinburgh

<sup>4</sup>Institut Universitaire de France

Marseille - I2M, May 4, 2023

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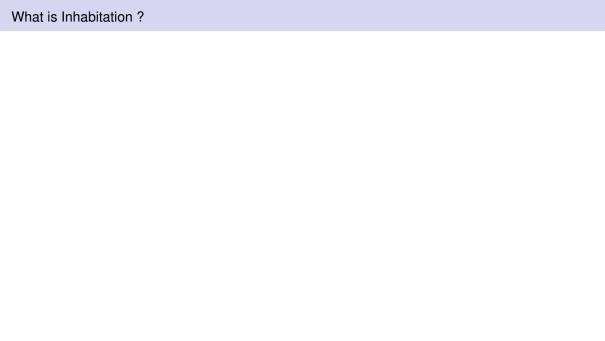
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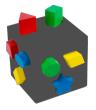
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Typing Problem:

# Typing Problem:

 $\Gamma \vdash t : \sigma$ 



# **Typing Problem:**

 $\Gamma \vdash t : \sigma$ 

Computational: [Mil'78]

**Typers** 

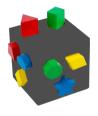


Typing Problem:  $\Gamma \vdash t : \sigma$ 

(2)

Inhabitation Problem (IP):

Computational: [Mil'78]
Typers



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Inhabitation Problem (IP):

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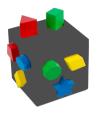
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Inhabitation Problem (IP):  $\Gamma \vdash t : \sigma$ 

Computational: [HuOr'20] Program Synthesis

**Logical**: **[HoMi'94]**Proof Search and Logic Programming



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# Quantitative Inhabitation for Different Lambda Calculi in a Unifying

# **Framework**

# Quantitative Inhabitation for Different Lambda Calculi in a Unifying Framework



#### **Different Models of Computation:**









# Quantitative Inhabitation for Different Lambda Calculi in a Unifying Framework

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#### **Different Models of Computation:**







#### **Unifying Frameworks:**

Call-by-Push-Value [Levy'99]

#### **Different Models of Computation:**







- Call-by-Push-Value [Levy'99]
- Bang Calculus [EG'16]



#### **Different Models of Computation:**







- Call-by-Push-Value [Levy'99]
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$$t, u ::= x \mid \lambda x.t \mid tu$$



#### **Different Models of Computation:**





- Call-by-Push-Value [Levy'99]
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#### **Different Models of Computation:**





#### **Unifying Frameworks:**

- Call-by-Push-Value [Levy'99]
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$$\mid !t$$
$$\mid der(t)$$

Values Computations



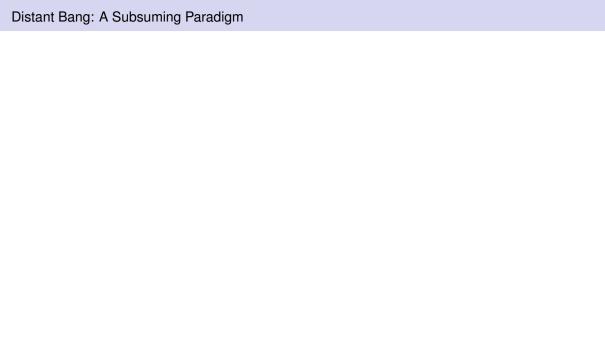
#### **Different Models of Computation:**





- Call-by-Push-Value [Levy'99]
- Distant Bang Calculus [EG'16] [BKRV'20]:













BANG

Static Properties: [BKRV'20]

NAME

t normal form







BANG

Static Properties: [BKRV'20]

NAME

t normal form  $\Leftrightarrow$  t  $\stackrel{N}{t}$  normal form











BANG

Static Properties: [BKRV'20]

NAME

t normal form

 $\Leftrightarrow$   $t^N$  normal form

BANG

**Dynamic Properties: [BKRV'20]** 

NAME





Static Properties: [BKRV'20]

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t normal form  $\Leftrightarrow$  t  $\stackrel{N}{t}$  normal form

BANG

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NAME

BANG

NAME BANG VALUE BANG

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Static Properties: [BKRV'20]



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Static Properties: [BKRV'20]



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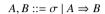


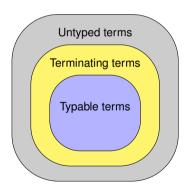
Can we do the same thing with inhabitation?

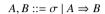
# Quantitative Inhabitation for Different Lambda Calculi in a Unifying Framework

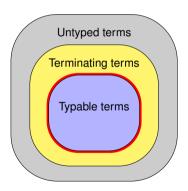
Quantitative Inhabitation for Different Lambda Calculi in a Unifying **Framework** 

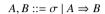
# Simple Types Versus Intersection Types

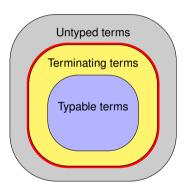




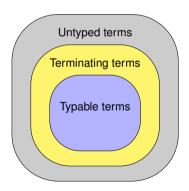




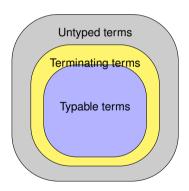




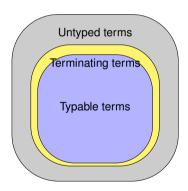
$$A, B ::= \sigma \mid A \Rightarrow B \mid A \cap B$$



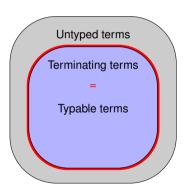
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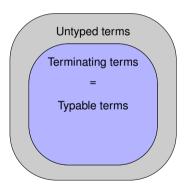
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#### Associativity:

$$A \cap (B \cap C) = (A \cap B) \cap C$$

$$A, B := \sigma \mid A \Rightarrow B \mid A \cap B$$

Untyped terms

Terminating terms

=
Typable terms

Associativity:

$$A \cap (B \cap C) = (A \cap B) \cap C$$

Commutativity:

$$A\cap B=B\cap A$$

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Untyped terms

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Associativity:

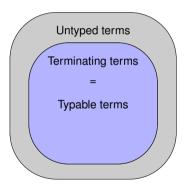
$$A \cap (B \cap C) = (A \cap B) \cap C$$

Commutativity:

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Idempotency?

$$A,B ::= \sigma \mid A \Rightarrow B \mid {\color{red} A \cap B}$$



Associativity:

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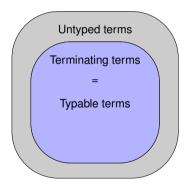
$$A \cap B = B \cap A$$

Idempotency?

Idempotent [CoDe'78],[CoDe'80]

$$A \cap A = A$$

$$A,B ::= \sigma \mid A \Rightarrow B \mid A \cap B$$



Associativity:

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$$A \cap A = A$$

**Qualitative** properties





$$A, B ::= \sigma \mid A \Rightarrow B \mid A \cap B$$

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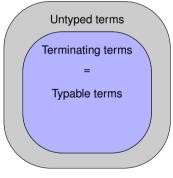
$$A \cap A \neq A$$

Qualitative properties





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Idempotent [CoDe'78],[CoDe'80]

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Qualitative properties





Quantitative properties [dCarv'07]



<b>Typing</b> ? <b>⊢</b> <i>t</i> : ?	Inhabitation $\Gamma \vdash ? : \sigma$

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Simple Types		
Idempotent Types		
Non-Idempotent Types		

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Decidable	
	? <b>+</b> <i>t</i> : ?

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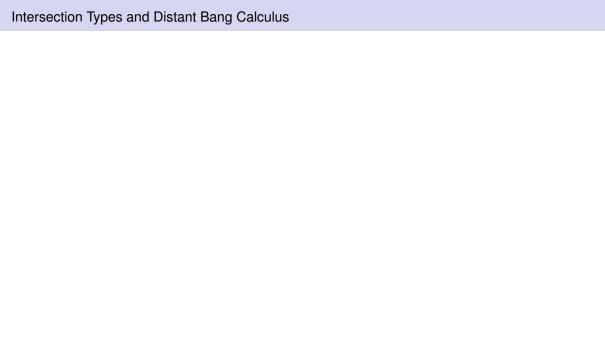
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Three Typing Systems: [BKRV'20]

NAME : N

**VALUE**: V

BANG: B

Three Typing Systems: [BKRV'20]

NAME : N

VALUE : V

 $BANG : \mathcal{B}$ 

Static Properties: [BKRV'20]

NAME

 $\Gamma \vdash_{\mathcal{N}} t : \sigma$ 

#### Three Typing Systems: [BKRV'20]

NAME : N

VALUE : V

BANG : B

Static Properties: [BKRV'20]

NAME

 $\Gamma \vdash_{\mathcal{N}} t : \sigma \iff \Gamma \vdash_{\mathcal{B}} t^{N} : \sigma$ 

BANG

#### Three Typing Systems: [BKRV'20]

NAME : N

VALUE : V

 $BANG : \mathcal{B}$ 

Static Properties: [BKRV'20]

NAME VALUE

### Quantitative Inhabitation for Different Lambda Calculi in a Unifying

**Framework** 



#### First Goal

■ **Decidability** of the (more general) **BANG** Inhabitation Problem (IP).

#### First Goal + More Ambitious Second Goal

- **Decidability** of the (more general) **BANG** Inhabitation Problem (IP).
- Decidability of the NAME and VALUE IP from decidability of the BANG IP.



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More Ambitious Third Goal

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#### More Ambitious Third Goal

Decidability by finding all inhabitants in the BANG IP.

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### Coming Back to Inhabitation

#### First Goal + More Ambitious Second Goal

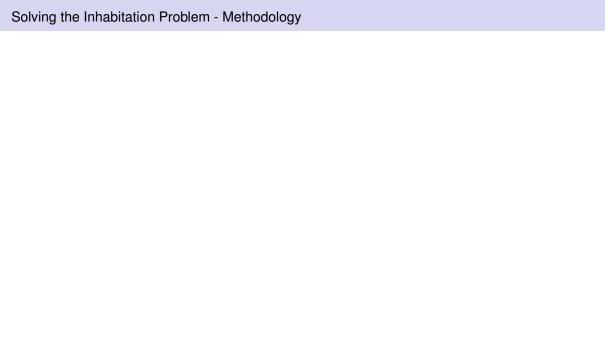
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#### More Ambitious Third Goal

- Decidability by finding all inhabitants in the BANG IP.
- Decidability of the NAME and VALUE IP by finding all inhabitants from those of the BANG IP.
- Using generic properties so that other encodable models of computation can use these results.







Instead of **just one** solution:

 $\Gamma \vdash \mathbf{t} : \sigma$ 

We want to compute **all** solutions:

$$\mathsf{Sol}(\Gamma,\sigma) \; := \; \{\, \mathbf{t} \mid \Gamma \vdash \mathbf{t} : \sigma \,\}$$



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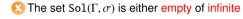
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### Problem



BANG



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### Problem





We compute a **finite** generator:

Basis $(\Gamma, \sigma)$ 

Which is **correct** and **complete**:

$$\operatorname{span}(\operatorname{Basis}(\Gamma,\sigma)) \ = \ \operatorname{Sol}(\Gamma,\sigma)$$



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#### Theorem

 $\P$  For any typing  $(\Gamma, \sigma)$ , Basis $_{\mathcal{B}}(\Gamma, \sigma)$  exists, is finite, correct and complete.

BANG



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BANG



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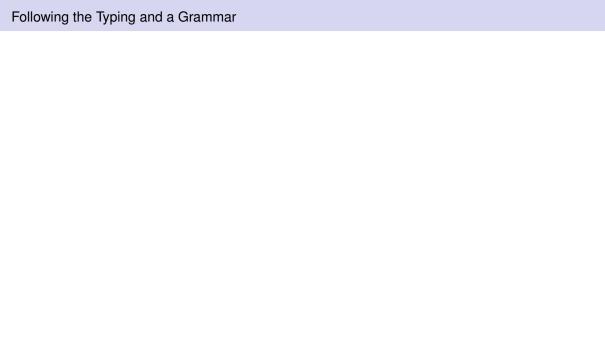
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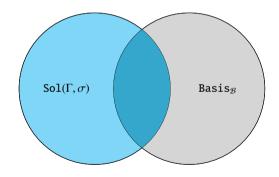
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- Grammar rules

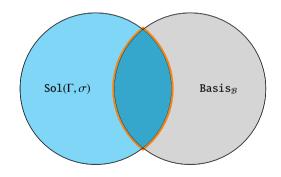


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Follows two sets of rules:

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$$\frac{g \mapsto \operatorname{Var} \mid}{x \Vdash_g H^{\operatorname{Xi}[\sigma]}(\emptyset; \sigma)^{\operatorname{VAR}}} = \frac{g \mapsto \operatorname{Der}(g') \mid}{\operatorname{der}(a) \Vdash_g H^{\operatorname{Xi}[\tau]}(\Gamma; [\sigma])} \underset{\Gamma = \Gamma_a + \Gamma_b}{\operatorname{De}} = \frac{g \mapsto \operatorname{Sub}(g_a, g_b)}{\operatorname{In}(\Gamma; \sigma)} = \frac{g \mapsto \operatorname{Sub}(g_a, g_b)}{\operatorname{In}(\Gamma; \sigma)}$$

```
g \mapsto \mathsf{App}(g_a, g_b)
             \Gamma = \Gamma_a + \Gamma_b
                                                              a \Vdash_{g_a} H^{x:[\tau]}(\Gamma_a; \mathcal{M} \Rightarrow \sigma) \quad b \Vdash_{g_b} N(\Gamma_b; \mathcal{M})
\mathcal{M} \Rightarrow \sigma \Vdash S(\tau, \diamond \Rightarrow \sigma)
                                                              ab \Vdash_{a} H^{x:[\tau]}(\Gamma;\sigma)
```

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g \mapsto \mathsf{App}(g_a, g_b)
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                                                                         a \Vdash_{g_a} H^{x:[\tau]}(\Gamma_a; \mathcal{M} \Rightarrow \sigma) \quad b \Vdash_{g_b} N(\Gamma_b; \mathcal{M})
\mathcal{M} \Rightarrow \sigma \Vdash S(\tau, \diamond \Rightarrow \sigma)
                                                                      ab \Vdash_q H^{x:[\tau]}(\Gamma;\sigma)
                     n \in [0, \mathsf{sz}(\rho)], \ M \Vdash S(\rho, | \diamondsuit_1, \dots, \diamondsuit_n|) | a \Vdash_{a_n} H^{*_{n+1}}(\Gamma_a, u; M; \sigma) \mid B \Vdash_{a_n} H^{*_{n+1}}(\Gamma_b; M)
```

```
\Gamma = \Gamma_a + \Gamma_b
                                                   a \Vdash_{a_0} H^{x:[\tau]}(\Gamma_a; \mathcal{M} \Rightarrow \sigma) \quad b \Vdash_{a_b} N(\Gamma_b; \mathcal{M})
                                                 ab \Vdash_{\sigma} H^{x:[\tau]}(\Gamma;\sigma)
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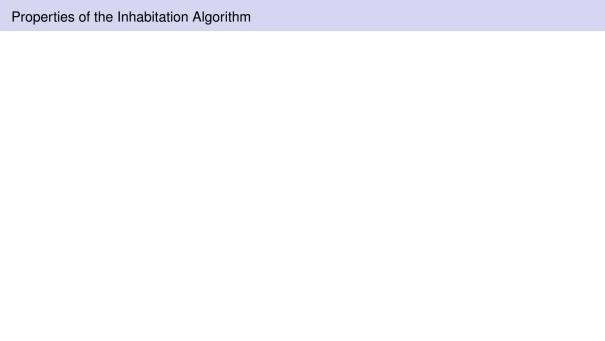
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g \mapsto \mathsf{App}(g_a, g_b)
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                                                               ab \Vdash_{\boldsymbol{q}} H^{x:[\tau]}(\Gamma;\sigma)
           n \in [0, \mathsf{sz}(\rho)], \ M \Vdash S(\rho, [\lozenge_1, \ldots, \lozenge_n]) | a \Vdash_{q_a} H^{\wedge_{1^{k_1}}}(\Gamma_a, y : M; \sigma) \quad b \Vdash_{q_b} H^{\sim_{1^{k_1}}}(\Gamma_b; M)
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                     n \in [0, \mathsf{sz}(\rho)], \ M \Vdash S(\rho, | \diamondsuit_1, \dots, \diamondsuit_n|) | a \Vdash_{a_n} H^{*_{n+1}}(\Gamma_a, u; M; \sigma) \mid B \Vdash_{a_n} H^{*_{n+1}}(\Gamma_b; M)
```

$$\frac{g \mapsto \operatorname{Var} \mid}{x \Vdash_g H^{\operatorname{Xi}[\sigma]}(\emptyset; \sigma)^{\operatorname{VAR}}} = \frac{g \mapsto \operatorname{Der}(g') \mid}{\operatorname{der}(a) \Vdash_g H^{\operatorname{Xi}[\tau]}(\Gamma; [\sigma])} \underset{\Gamma = \Gamma_a + \Gamma_b}{\operatorname{De}} = \frac{g \mapsto \operatorname{Sub}(g_a, g_b)}{\operatorname{In}(\Gamma; \sigma)} = \frac{g \mapsto \operatorname{Sub}(g_a, g_b)}{\operatorname{In}(\Gamma; \sigma)}$$

### The Full Algorithm and its Implementation





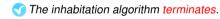
### Non-deterministic algorithm



### Non-deterministic algorithm



### Theorem



### Non-deterministic algorithm



#### Theorem

- The inhabitation algorithm terminates.
- $\bigcirc$  The algorithm is sound and complete (i.e. it exactly computes  $\mathtt{Basis}_{\mathcal{B}}(\Gamma, \sigma)$ ).

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### More Ambitious Third Goal

Oecidability by finding all inhabitants in the BANG IP.

### Non-deterministic algorithm

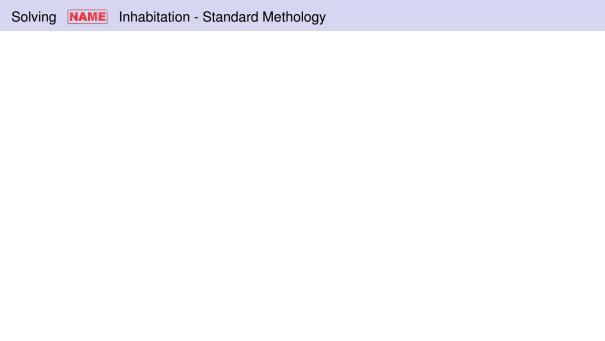


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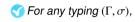
Solving NAME Inhabitation - Standard Methology

### Theorem ([BKR'14])

Basis<sub>N</sub> $(\Gamma, \sigma)$  exists, is finite, correct and complete.  $\bigcirc$  For any typing  $(\Gamma, \sigma)$ ,

NAME

### Theorem ([BKR'14])



 $\P$  For any typing  $(\Gamma, \sigma)$ , Basis<sub>N</sub> $(\Gamma, \sigma)$  exists, is finite, correct and complete.

NAME

Built an algorithm computing Basis<sub>N</sub> $(\Gamma, \sigma)$ : [BKR'14]

$$\frac{\mathbf{a} \Vdash \mathbf{T}(\Gamma + \mathbf{x} : \mathbf{A}, \tau) \qquad \mathbf{x} \notin \mathsf{dom}(\Gamma)}{\lambda \mathbf{x}. \mathbf{a} \Vdash \mathbf{T}(\Gamma, \mathbf{A} \to \tau)} \text{ (Abs)}$$

$$\frac{(\mathbf{a}_i \Vdash \mathbf{T}(\Gamma_i, \sigma_i))_{i \in I} \qquad \uparrow_{i \in I} \mathbf{a}_i}{\bigvee_{i \in I} \mathbf{T}(\mathbf{I}_i, [\sigma_i]_{i \in I})} \text{ (Union)}$$

$$\frac{\Gamma = \Gamma_1 + \Gamma_2 \qquad \mathbf{a} \Vdash \mathbf{H}^{\mathbf{x}:[A_1 \to \dots A_n \to B \to \tau]}(\Gamma_1, \mathbf{B} \to \tau) \qquad \mathbf{b} \Vdash \mathbf{TI}(\Gamma_2, \mathbf{B}) \qquad n \geq 0}{\mathbf{a} \mathbf{b} \Vdash \mathbf{H}^{\mathbf{x}:[A_1 \to \dots A_n \to B \to \tau]}(\Gamma, \tau)} \text{ (Head_0)}$$

$$\frac{\mathbf{a} \Vdash \mathbf{H}^{\mathbf{x}:[A_1 \to \dots A_n \to \tau]}(\Gamma, \tau)}{\mathbf{a} \Vdash \mathbf{T}(\Gamma, \mathbf{x}) \mapsto \mathbf{a}} \text{ (Head_0)}$$



Solving NAME Inhabitation : through BANG Inhabitation

The Basis is preserved by the embedding:



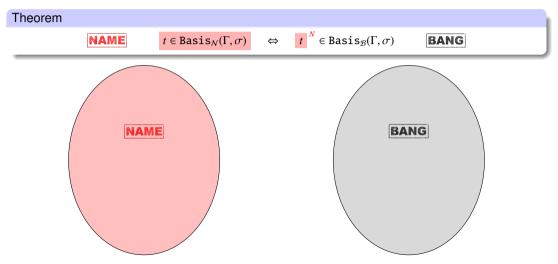
NAME

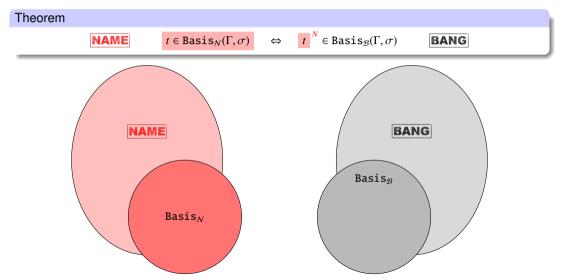
 $t \in \mathtt{Basis}_{\mathcal{N}}(\Gamma, \sigma)$ 

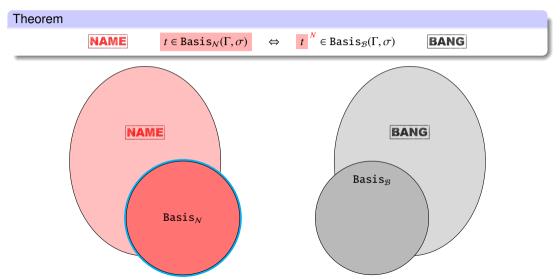
Solving NAME Inhabitation : through BANG Inhabitation

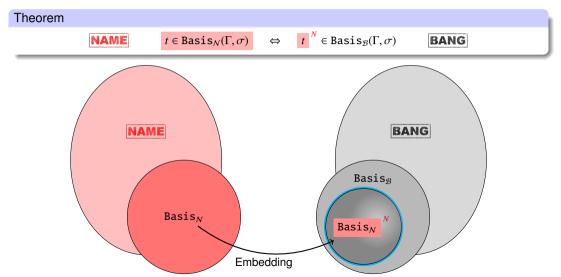
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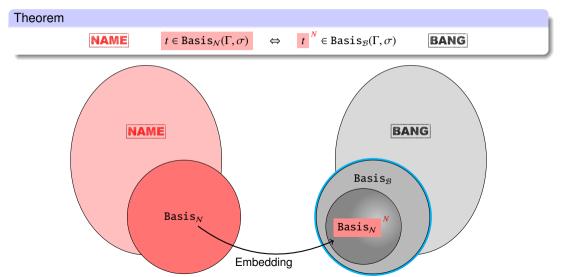


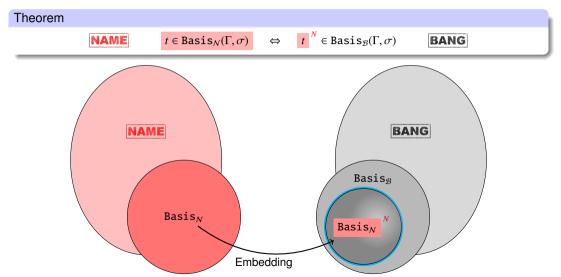


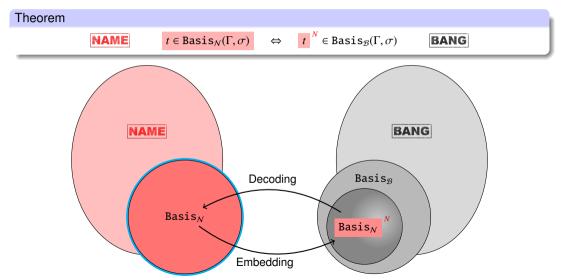


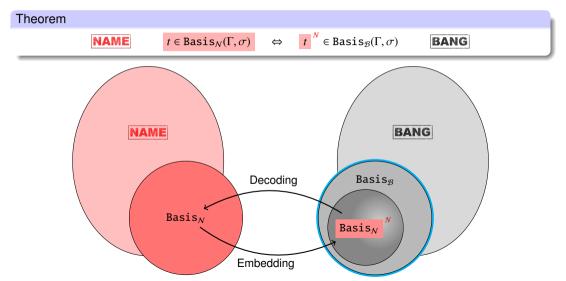


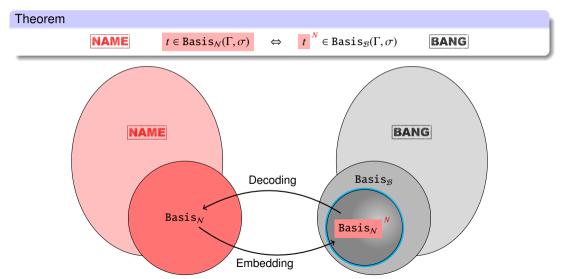


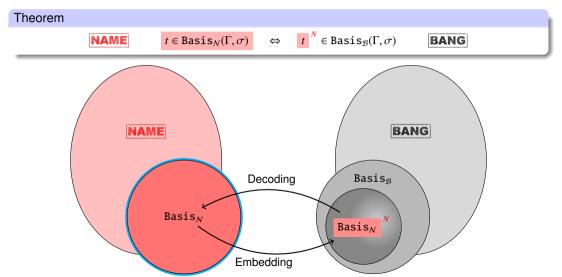


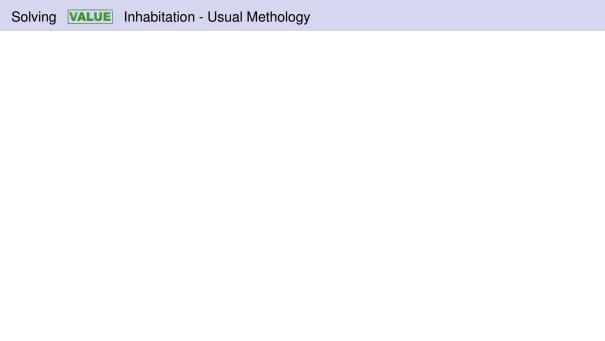












Solving **VALUE** Inhabitation - Usual Methology

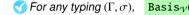
# Theorem



 $\bigcirc$  For any typing  $(\Gamma, \sigma)$ , Basis $_{\mathcal{V}}(\Gamma, \sigma)$  exists, is finite, correct and complete. **VALUE** 

Solving **VALUE** Inhabitation - Usual Methology

# Theorem



Basis $_{\mathcal{V}}(\Gamma, \sigma)$  exists, is finite, correct and complete.

VALUE

Built an algorithm computing  $\operatorname{Basis}_{\mathcal{V}}(\Gamma,\sigma)$  :

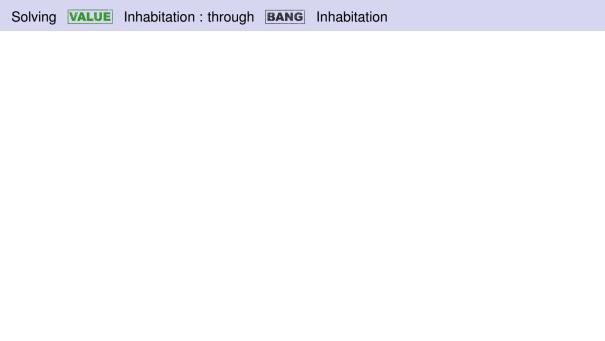


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```
\frac{\left|\begin{array}{c|c} I \neq \emptyset \\ x \Vdash H^{N(\sigma)}(\theta;\sigma) \end{array}\right|^{VAR-FUN}}{x \Vdash N(\Gamma; [\sigma]_{\{\sigma\}})} = \frac{1}{x \vdash N(\emptyset; [\sigma]_{\{\sigma\}})} VAR-VAL \qquad \frac{\left|\begin{array}{c|c} I \neq \emptyset \\ \bot_{V} \Vdash N(\emptyset; [\sigma]_{\{\sigma\}}) \end{array}\right|^{VAR-FUN}}{x \vdash N(\emptyset; [\sigma]_{\{\sigma\}})} = \frac{1}{x \vdash N(\emptyset; [\sigma]_{\{\sigma\}})} VAR-VAL \qquad \frac{1}{x \vdash N(\emptyset; [\sigma
                                                                                                                           \begin{bmatrix} \mathcal{M} \Rightarrow \sigma \end{bmatrix} \Vdash S(\tau, [\diamondsuit \Rightarrow \sigma]) \quad \middle| \quad a_1 \Vdash H_0^{\pi(\tau)}(\Gamma_1; [\mathcal{M} \Rightarrow \sigma]) \quad a_2 \Vdash N(\Gamma_2; \mathcal{M}) \\ & \qquad \qquad \downarrow \\ \\ & \qquad \qquad \downarrow 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                a_1a_2 \Vdash H^{x:[\tau]}_{\star}(\Gamma; \sigma)
                                                                                                                   \begin{array}{c|c} \Gamma = \Gamma' + x : \{ \Gamma \} \\ \sigma \Vdash S(\Gamma, \diamond) & a \Vdash H_{\Gamma}^{\infty[\Gamma]}(\Gamma'; \sigma) \\ \hline a \Vdash N(\Gamma; \sigma) & a \Vdash N(\Gamma; \sigma) \end{array} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} \\ \times \frac{I \neq \emptyset}{a \Vdash N(\Gamma; M; \sigma)} 
                                                                                                                                                                                                                            \Gamma = \Gamma_0 + \Gamma_0 + z : [\rho], \quad \text{fix } u \notin \text{dom}(\Gamma) \cup \{x\}
                                                                                                                                                                                                                                                                                               = \frac{\Gamma_a + \Gamma_b + z : [\rho]}{n \in [0, sz(\rho)], \ M \Vdash S(\rho, [\diamondsuit_1, \dots, \diamondsuit_n])} \quad a \Vdash H_0^{\infty[\tau]}(\Gamma_a, y : \mathcal{M}; \sigma) \quad b \Vdash H_A^{\infty[\rho]}(\Gamma_b; \mathcal{M}) 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               a[y \mid b] \Vdash H_{\alpha}^{x:[\tau]}(\Gamma; \sigma)
                                                                                                                  \Gamma = \Gamma_0 + \Gamma_0, fix u \notin dom(\Gamma) \cup \{x\}
n \in [1, sz(\tau)], [\rho_i]_{i \in [1, n]} \Vdash S(\tau, [\diamond_1, \dots, \diamond_n])
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                a \Vdash H_{\mathcal{Q}}^{\mathcal{Y}:\left[\rho_{i}\right]}\left(\Gamma_{a}, y:\left[\rho_{i}\right]_{i \in \left[\!\left[1,n\right]\!\right] \setminus i}; \sigma\right) \quad b \Vdash H_{A}^{\mathbf{x}:\left[\tau\right]}\left(\Gamma_{b};\left[\rho_{i}\right]_{i \in \left[\!\left[1,n\right]\!\right]}\right)_{\mathsf{ESCHO}}
                                                                                                                                                                                                                                                     i \in [1, n], \sigma \Vdash S(o_i, \diamondsuit)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        a[y \mid b] \Vdash H_o^{x:[\tau]}(\Gamma; \sigma)
                                                                                                                                                                                                                                                                                                                                                                                                                                                         \Gamma = \Gamma_a + \Gamma_b + z : [\tau], \quad \text{fix } y \notin \text{dom}(\Gamma)
                                                                                                                                                                                                                                                                                                                                                                                                                                                 \Gamma = \Gamma_a + \Gamma_b + z : [\tau], \quad \text{fix } y \notin \text{dom}(1)
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\Gamma_{S \in N} = \{0, \text{sz}(\tau)\}, \quad S \vdash \{0, \text{sz}(\tau)\}, 
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 a[u \mid b] \Vdash N(\Gamma; \sigma)
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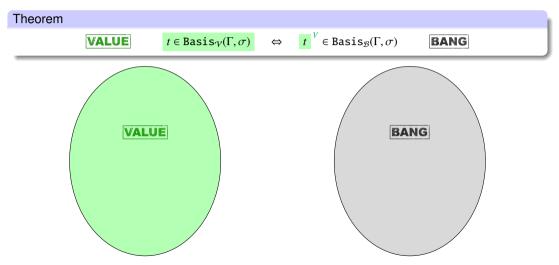
The Basis is preserved by the embedding:

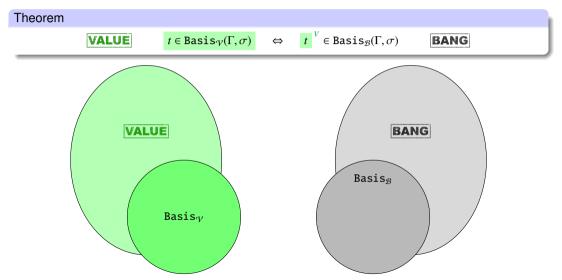


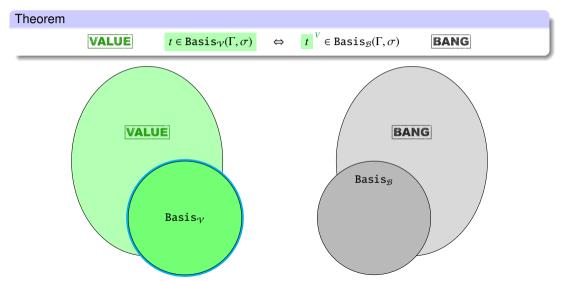
**VALUE** 

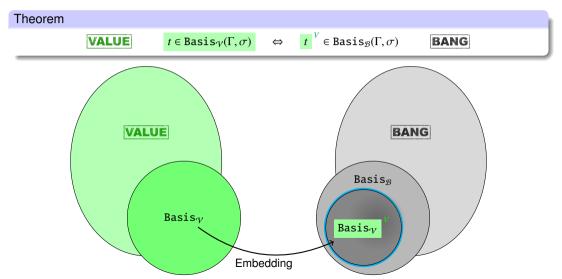
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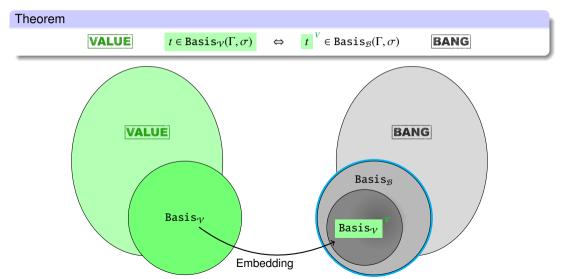


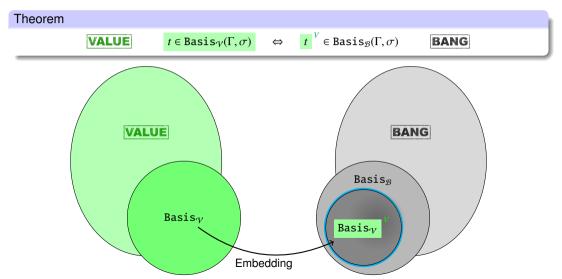


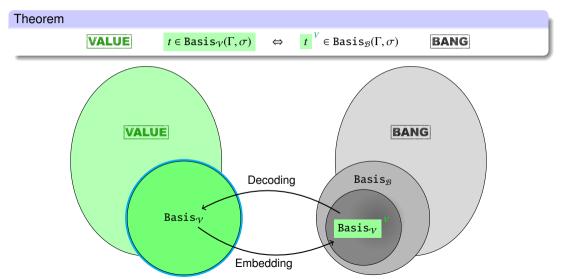


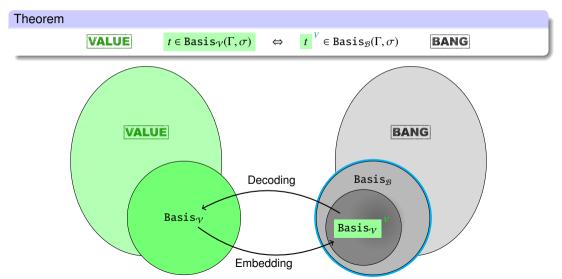


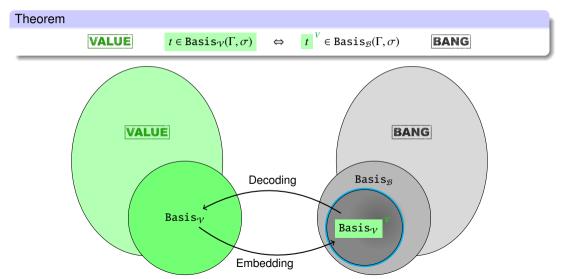


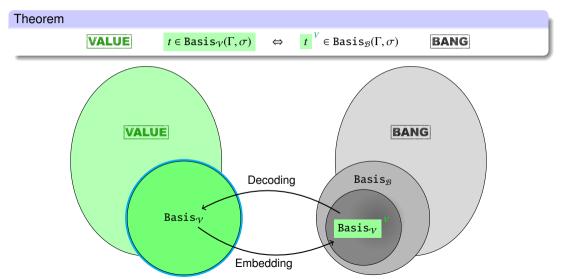














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# Conclusion

# Summary:

Solving the generalized inhabitation problem

■ A several-for-one deal: BANG NAME VALUE OTHERS

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# Thanks for your attention!