



Unisson

MPRI

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Unisson Problem

Properties:

- **Safety:** For every two neighbors u and v the output clock values satisfy
 - Synchronous: $clock_u = clock_v$
 - Asynchronous: $clock_v = k$ and $clock_u \in \{k - 1, k, k + 1\}$.
- **Liveness:** Each node updates its clock value infinitely often

Outline

- **Synchronous Unisson**
 - Arora, Dolev, Gouda 1991
- **Asynchronous Unisson**
 - Boulinier 2007
 - Emek, Keren 2021

Synchronous Unisson

Anish Arora, Shlomi Dolev, Mohamed G.Gouda

Maintaining digital clocks in step.

IPL 1991

Book: Introduction to Distributed Self-Stabilizing Algorithms, Altisen at all **2019**

Model

- Anonymous undirected graph $G = (V, E)$
- State model
- Synchronous scheduler
- Knowledge:
 - periode m
 - $m \geq \max\{2, 2D - 1\}$ where D is the diameter

Unisson

An execution e satisfies the synchronous unison if the predicate $SU(e)$ holds, where $SU(e)$ is defined by the conjunction of the following three properties:

- in every configuration of e , all the processes have the same clock value,
- e is infinite, and
- in each step of e , each clock is incremented modulo m .

Algorithme

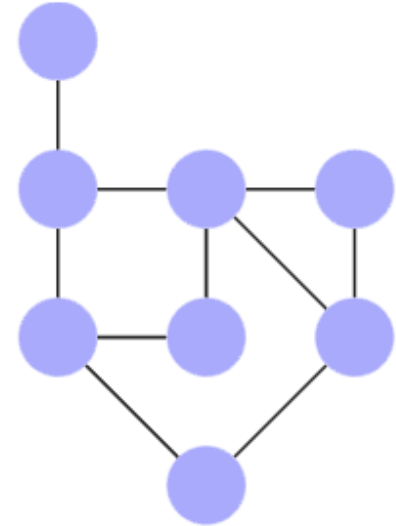
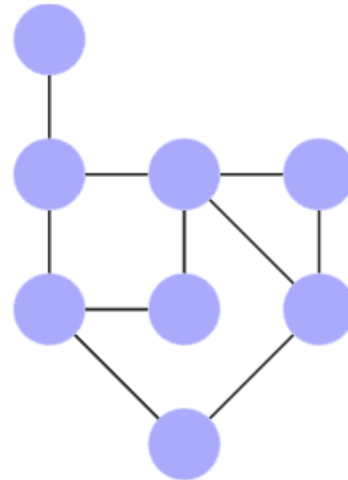
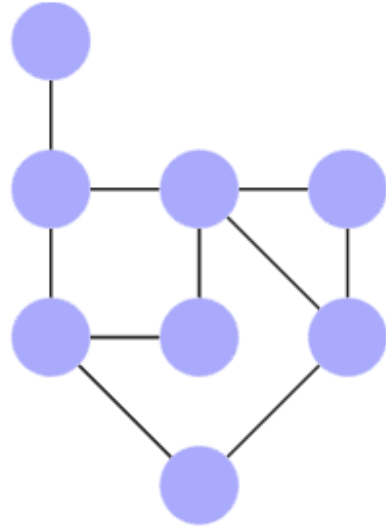
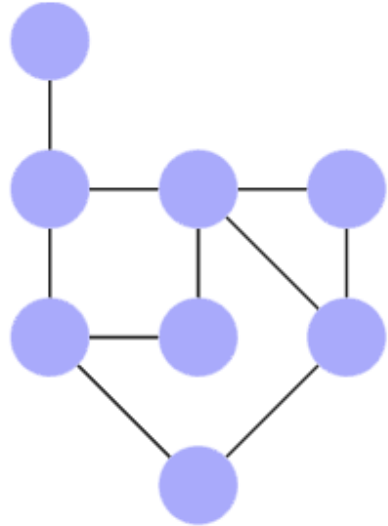
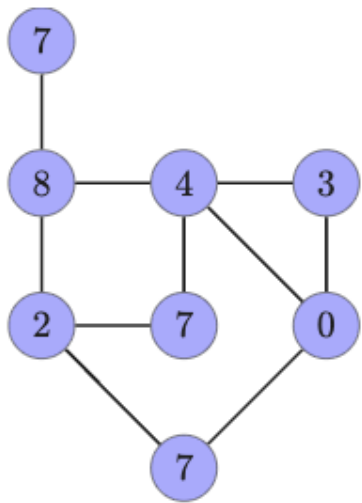
Local variable

$$clock_v \in \{0, \dots, m - 1\}$$

Rule

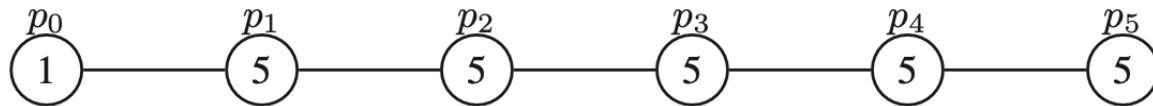
$$R : \longrightarrow clock_v = \min\{clock_u \mid u \in N(v) \cup \{v\}\} + 1 \pmod{m}$$

Example



Example of Worst Case execution

$$D = 5, m = 2D - 1 = 9,$$



	p_0	p_1	p_2	p_3	p_4	p_5
γ_0	1	5	5	5	5	5
γ_1	2	2	6	6	6	6
γ_2	3	3	3	7	7	7
γ_3	4	4	4	4	8	8
γ_4	5	5	5	5	5	0
γ_5	6	6	6	6	1	1
γ_6	7	7	7	2	2	2
γ_7	8	8	3	3	3	3
γ_8	0	4	4	4	4	4
γ_9	1	1	5	5	5	5
γ_{10}	2	2	2	6	6	6
γ_{11}	3	3	3	3	7	7
γ_{12}	4	4	4	4	4	8
γ_{13}	5	5	5	5	5	5

Revisited Correctness

Legal configuration

$$\text{Legal}_U(\gamma) \equiv \forall u, v \in V \times V | \text{clock}_v(\gamma) = \text{clock}_u(\gamma)$$

Tools

- $m^+(\gamma) = \max\{clock_v(\gamma) \mid \forall v \in V\}$
- $m^-(\gamma) = \min\{clock_v(\gamma) \mid \forall v \in V\}$
- Let us consider a configuration γ such that $Legal_u(\gamma) = false$
 - we have $m^+ \neq m^-$
 - Let denoted by $d^+(\gamma)$ For all v in V the maximum distance between a node v with $clock_v = m^+$ and the closest node u with $clock_u = m^-$
 - Remark that $d^+(\gamma) \leq D - 1$ when the graph is a chain
 - Let denote by $m^s(\gamma) = m - m^+(\gamma)$
 - Let denote by $m^e(\gamma) = n - m_\gamma^+ - m_\gamma^-$

Reset clock

Lemma 1: if $d^+(\gamma) > m^s(\gamma)$ then at least one node v turn is clock to 0 in configuration $\gamma_{(m^s(\gamma)+\gamma_0)}$.

Potential function

Let $\psi : \Gamma \times V \rightarrow \mathbb{N}$ be the function defined by:

$$\psi(\gamma, v) = \begin{cases} 0 & \text{if } \mathit{clock}_v(\gamma) = m^-(\gamma) \\ n^{m^e} & \text{if } d^+(\gamma) > m^s(\gamma) \wedge \mathit{clock}_v(\gamma) \neq m^-(\gamma) \\ 1 & \text{if } d^+(\gamma) \leq m^s(\gamma) \wedge \mathit{clock}_v(\gamma) \neq m^-(\gamma) \end{cases}$$

Let $\Psi : \Gamma \rightarrow \mathbb{N}$ be the potential function defined by:

$$\Psi(\gamma) = \sum_{v \in V} \beta(\gamma)$$

Let denoted by Γ_C the set of legal configurations such that

$$\Gamma_C = \{\gamma \in \Gamma \mid \Psi(\gamma) = 0\}$$

Closure and Correctness

Theorem 1: $true \triangleright \Gamma_C$ and Γ_c is closed

Theorem 2: The system converges in at most $3D - 2$ steps

Example of Worst Case execution in a chain

$$D = 5, m = 2D - 1 = 9, 3D - 2 = 13 \text{ steps}$$

	p_0	p_1	p_2	p_3	p_4	p_5
γ_0	1	5	5	5	5	5
γ_1	2	2	6	6	6	6
γ_2	3	3	3	7	7	7
γ_3	4	4	4	4	8	8
γ_4	5	5	5	5	5	0
γ_5	6	6	6	6	1	1
γ_6	7	7	7	2	2	2
γ_7	8	8	3	3	3	3
γ_8	0	4	4	4	4	4
γ_9	1	1	5	5	5	5
γ_{10}	2	2	2	6	6	6
γ_{11}	3	3	3	3	7	7
γ_{12}	4	4	4	4	4	8
γ_{13}	5	5	5	5	5	5

γ	p_0	p_1	p_2	p_3	p_4	p_5		m^+	m^-	m^e	m^s	d^+	$m^s < d^+$	$\Psi(\gamma)$
γ_0	1	5	5	5	5	5		5	1	2	4	5	oui	$5 \times 6^2 = 180$
γ_1	2	2	6	6	6	6		6	2	2	3	4	oui	$4 \times 6^2 = 144$
γ_2	3	3	3	7	7	7		7	3	2	2	3	oui	$3 \times 6^2 = 108$
γ_3	4	4	4	4	8	8		8	4	2	1	2	oui	$2 \times 6^2 = 72$
γ_4	5	5	5	5	5	0		5	0	1	4	5	oui	$5 \times 6 = 30$
γ_5	6	6	6	6	1	1		6	1	1	3	4	oui	$4 \times 6 = 24$
γ_6	7	7	7	2	2	2		7	2	1	2	3	oui	$3 \times 6 = 18$
γ_7	8	8	3	3	3	3		8	3	1	1	2	oui	$2 \times 6 = 12$
γ_8	0	4	4	4	4	4		4	0		5	5	non	5
γ_9	1	1	5	5	5	5		5	1		4	4	non	4
γ_{10}	2	2	2	6	6	6		6	2		3	3	non	3
γ_{11}	3	3	3	3	7	7		7	3		2	2	non	2
γ_{11}	4	4	4	4	4	8		8	4		1	1	non	1
γ_{11}	5	5	5	5	5	5		5	5		0	0	non	0

Asynchronous Unisson

Naive algorithm

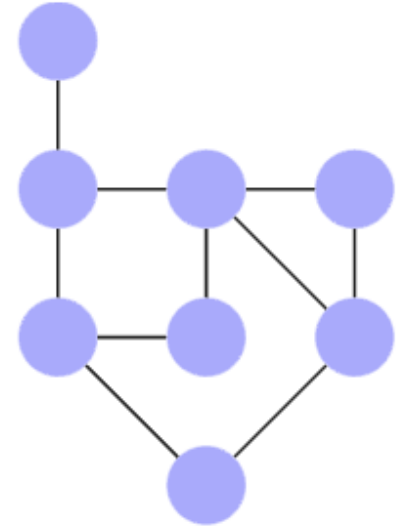
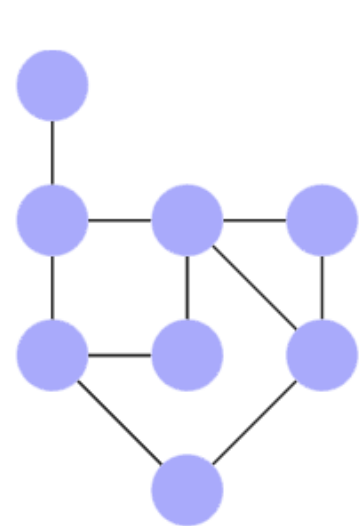
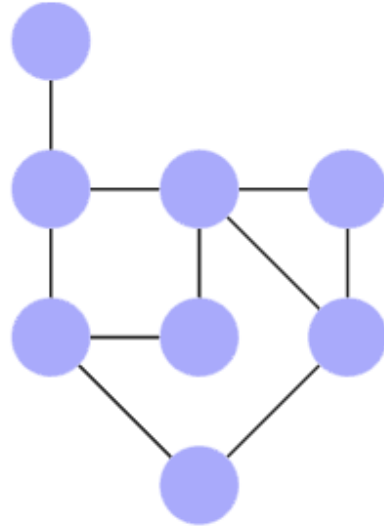
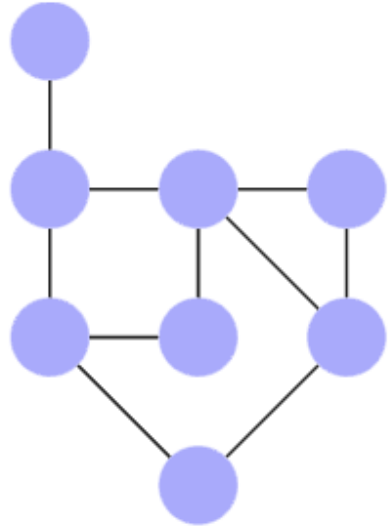
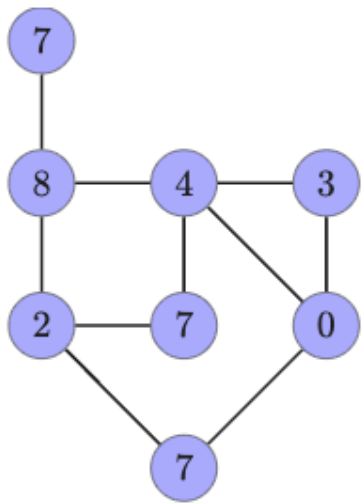
Unbounded clock defined over \mathbb{Z}

Naive

$$R : \forall u \in N(v) | \text{clock}_v \leq \text{clock}_u \longrightarrow \text{clock}_v = \text{clock}_v + 1$$

Theorem 3: Naive algorithm resolves the asynchronous unisson problem
[Boulinier 2007]

Example



Unbounded vs bounded

Asynchronous Unisson

A Thin Self-Stabilizing Asynchronous Unison Algorithm with
Applications to Fault Tolerant Biological Networks

Yuval Emek Eyal Keren

PODC'21

Result

Deterministic asynchronous self-stabilizing unisson

- Stabilization time $O(D^3)$ rounds
- State Space: $O(D)$ States $\rightarrow O(\log_2 D)$ bits per nodes.

Model

- Undirected graph $G = (V, E)$
- State model
- Scheduler Distributed fair

Local variables:

- Each node $v \in V$ has a clock from a cyclic group $k \in K, |K| \geq 3$.

State of the node

- We denote by $S_v(t)$ the state of the node v at time t

Able state

- A node v maintains an **able** state if v detects no fault
 - $S_v(t) \in \bar{T}$
 - $\bar{T} = \{\ell \mid \ell \in \mathbb{Z}, 1 \leq |\ell| \leq d\}$
 - $d = \Theta(D)$

Faulty state

- A node v moves to a **faulty** state if v detects at least one fault
 - $S_v(t) \in \hat{T}$
 - $\hat{T} = \{\hat{\ell} \mid \ell \in \mathbb{Z}, 2 \leq |\ell| \leq d\}$
 - $d = \Theta(D)$

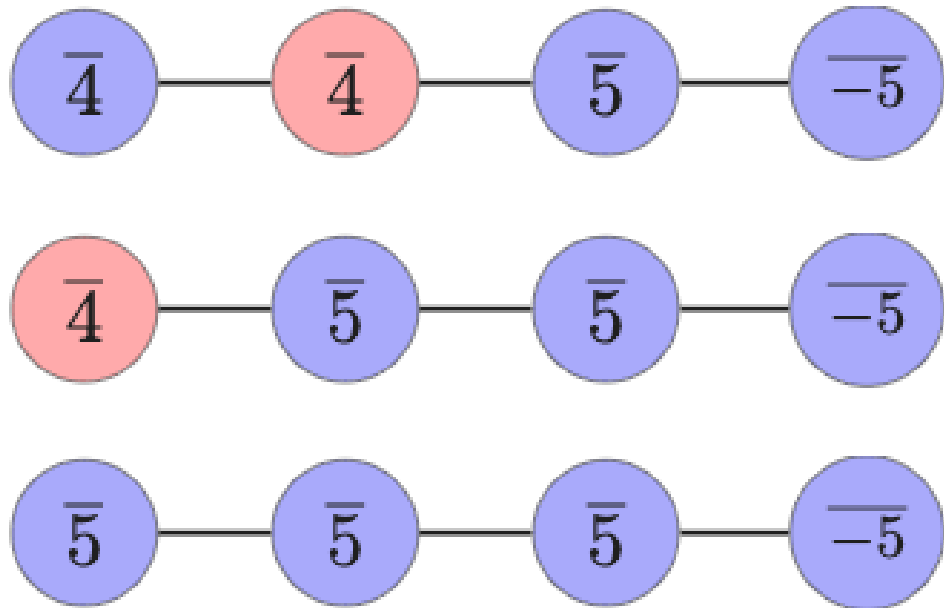
Remark: A node in $\bar{\ell}$ or $\hat{\ell}$ has a level ℓ

Definitions

- Edge $e = (u, v)$ is **protected** if u and v have adjacent levels.
- Node v is **protected** if all its incident edges are protected.
- Node v is **good** if it is protected and does not observe any faulty states.

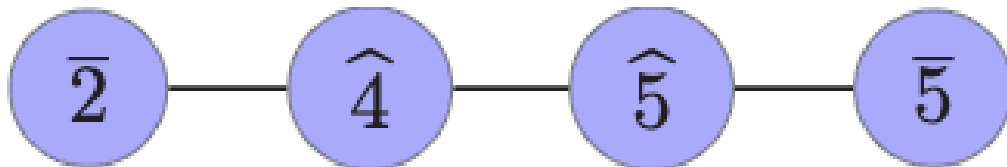
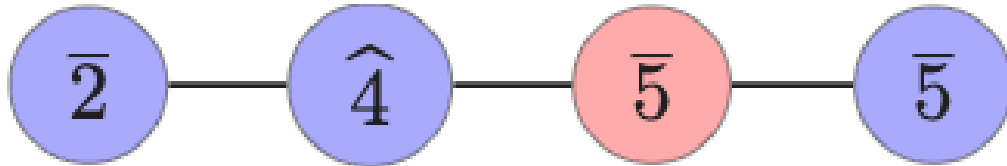
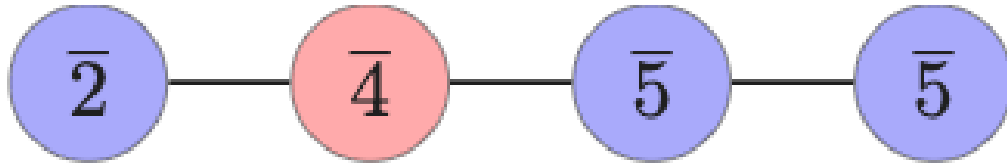
Able Able transition (AA)

$$R_{AA} : \text{Good}(v) \wedge \forall u \in N(v) : \text{clock}_u \in \{\bar{l}, \overline{l+1}\} \longrightarrow \text{clock}_v = \overline{l+1}$$



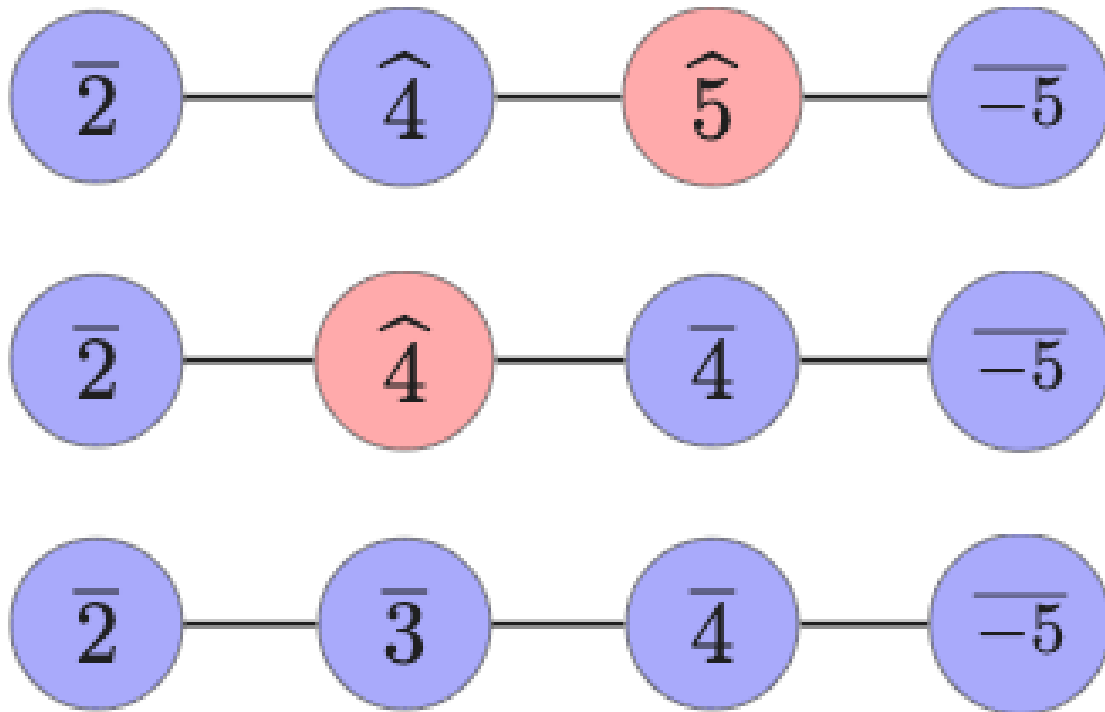
ADIE Faulty transition (AF)

$$R_{AF} : \neg Protected(v) \wedge \forall u \in N(v) : clock_u \in \{\bar{\ell}, \overline{\ell+1}\} \longrightarrow clock_v = \hat{\ell}$$



Faulty Able transition (FA)

$$R_{AF} : \forall u \in N(v) : clock_u < \ell \wedge clock_v = \hat{\ell} \longrightarrow clock_v = \overline{\ell - 1}$$



Transition Diagram

