

A Complexity Approach to Tree Algebras: the Polynomial Case

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joint work with Thomas Colcombet

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Infinitely sorted tree algebras

Let Σ be a ranked alphabet and \mathcal{V} be a countably infinite set of variables. The **free tree algebra** has as carrier sets the $(T_X)_{X \subseteq \mathcal{V} \text{ finite}}$.

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$$\begin{array}{c} a \\ / \ \backslash \\ x \ \ x \end{array} \in T_{\{x,y\}} \quad \begin{array}{c} a \\ / \ \backslash \\ x \ \ y \end{array} \in T_{\{x,y\}}$$

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Definition (Finite Tree algebras)

A **finite tree algebra** \mathcal{A} consists of an infinite series of finite carrier sets A_X indexed by finite sets of variables X , together with operations:

Constants. $a(x_0, \dots, x_{n-1})^{\mathcal{A}} \in A_{\{x_0, \dots, x_{n-1}\}}$ for all $a \in \Sigma_n$ and variables x_i ,

Substitution. $\cdot_x^{\mathcal{A}}: A_X \times A_Y \rightarrow A_{X \setminus \{x\} \cup Y}$ for all finite X, Y and variable x ,

Renaming. $\sigma^{\mathcal{A}}: A_X \rightarrow A_Y$ for all maps $\sigma: X \rightarrow Y$.

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Identities? $a(x, y) \cdot_y b \quad a(x, z) \cdot_z b$

We also define morphisms, congruences...

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Given a finite tree algebra \mathcal{A} , there is a unique morphism from the free algebra to \mathcal{A} . It is called the **evaluation morphism of \mathcal{A}** .

Languages and the size of the algebra

Definition (Language recognized by an algebra)

A language L of finite trees over Σ is **recognized** by a finite algebra \mathcal{A} if there is a set $P \subseteq A_\emptyset$ such that $L = \alpha^{-1}(P)$ in which α is the evaluation morphism of \mathcal{A} .

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Example $L =$ trees with a b on the leftmost branch

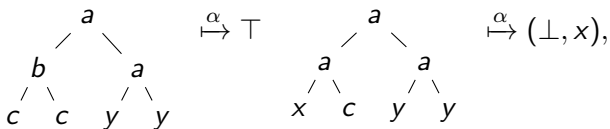
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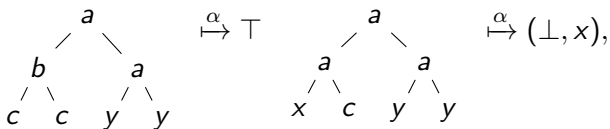
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$$|A_X| = 2 + 2|X| \text{ is linear in } |X|.$$

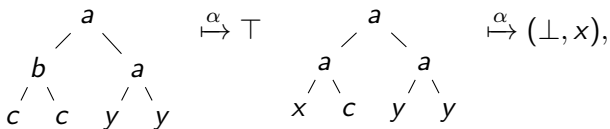
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$$A_X = \{\top, \perp\} \uplus (\{\top, \perp\} \times X) \quad |A_X| = 2 + 2|X| \text{ is linear in } |X|.$$

This algebra has **linear complexity**.

Complexity

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The objective is to identify new classes of languages and to gain a better understanding of tree algebras.

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$L =$ trees whose leftmost branch ends with $a(c, c)$, where
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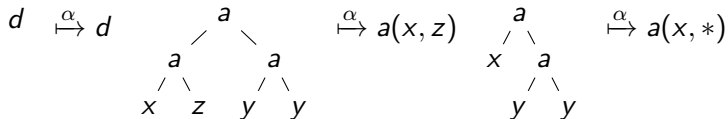
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Orbits: $c, d, a(x, y), a(x, x), a(x, c), a(c, x), a(x, *), a(*, x), a(c, c), a(*, *)$

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This algebra has **quadratic complexity** and **bounded orbit complexity**.

Orbit complexity

Let $|A_X/\mathbf{Sym}(X)|$ be the number of orbits of A_X under the action of $\mathbf{Sym}(X)$ induced by renamings.

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Another bounded hierarchy of classes

All regular languages are recognized by algebras of doubly-exponential orbit complexity.

What complexity means

Complexity is a tool to quantify what the algebra remembers about the variables:

Bounded complexity

The algebra does not remember anything about the variables.

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For a regular language of finite trees, the following properties are equivalent:

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- Being recognized by a finite tree algebra of **polynomial complexity**.
- Being recognized by a finite tree algebra of **bounded orbit complexity**.
- Being **described** by a **coding automaton**.

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- X (resp. f) is called equivariant if it is supported by the empty set.

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- $f: X \rightarrow Y$ is supported by $S \subseteq \mathcal{V}$ if $f(\sigma(x)) = \sigma(f(x))$, for all $x \in X$, $\sigma \in \mathbf{Sym}(\mathcal{V} \setminus S)$.
- X (resp. f) is called equivariant if it is supported by the empty set.

A **deterministic orbit-finite nominal automaton** is given by

- an orbit-finite nominal set A (the alphabet),
- an orbit-finite nominal set Q (the states),
- equivariant subsets $\{q_0\}$ and F of Q (the initial state and the final states),
- and an equivariant transition function $\delta: Q \times A \rightarrow Q$.

Nominal automata

Let $\mathbf{Sym}(\mathcal{V})$ act upon sets X and Y .

- X is called orbit-finite if the group action has finitely many orbits.
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Example: a deterministic register automaton can be seen as a deterministic orbit-finite nominal automaton.

Nominal automata example

$L =$ data words with at least three different datas

Nominal automata example

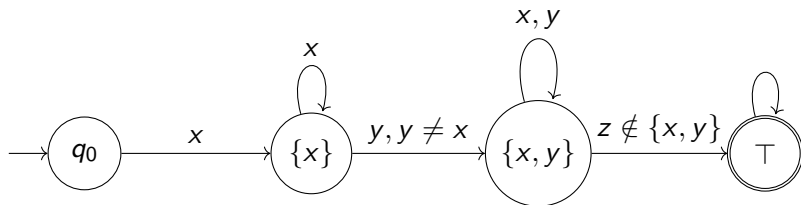
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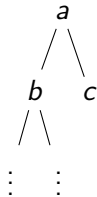
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Coding of trees

How to build the following tree ?



Coding of trees

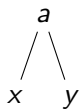
How to build the following tree ?

x

[x]

Coding of trees

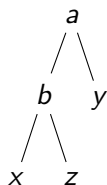
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$[x]$
 $[\cdot_x a(x, y)]$

Coding of trees

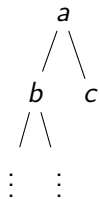
How to build the following tree ?



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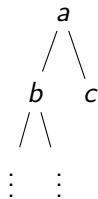
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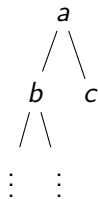
$$C_{\mathcal{V}} = \{[x] \mid x \in \mathcal{V}\}$$

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The alphabet $C_{\mathcal{V}} \cup C_{\mathcal{V}, \Sigma}$ is called the **coding alphabet**. It is a nominal orbit-finite alphabet.

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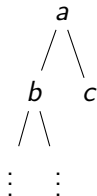
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Coding languages describing tree languages

A language L of codings **describes** a language $K \subseteq T_{\emptyset}$ of trees if, for every coding c such that $T(c) \in T_{\emptyset}$, $c \in L$ if and only if $T(c) \in K$.

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Let $c = [x][\cdot_x a(x, y)][\cdot_z c]$. What is $T(c)$?

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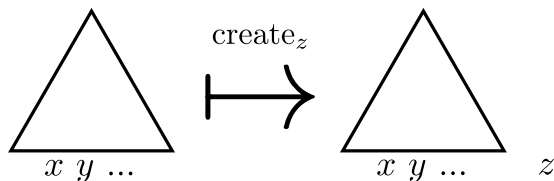
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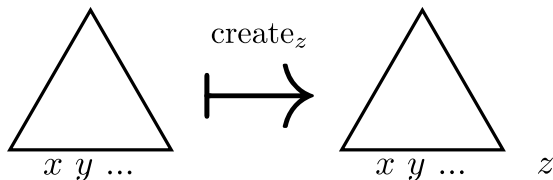


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$$T(c) = \text{create}_z(a(x, y)) \cdot_z c = a(x, y)$$

Coding automata

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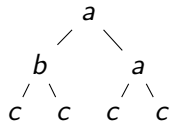
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We assume that there is no transition toward the initial state q_0 .

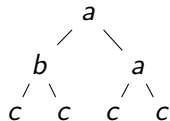
Language described by a coding automaton 1/2

$K =$ "trees with a b on the leftmost branch"



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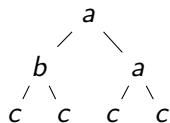
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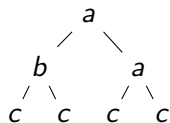
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-----	-----	-----------	-----------	-----------	-----------	-----------	-----------	-----------	-----------

q_0	x	c	$a(x, y)$	$a(x, x)$	$a(x, *)$	$a(*, x)$	$a(*, *)$	$a(x, c)$	$a(c, x)$	$a(c, c)$
-------	-----	-----	-----------	-----------	-----------	-----------	-----------	-----------	-----------	-----------

q_0	x	\perp	$a\{x, y\}$	$a\{x\}$	$a\{x\}$	$a\{x\}$	\perp	\top	\top	\top
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q_0	x	\perp	$a\{x, y\}$	$a\{x\}$	$a\{x\}$	$a\{x\}$	\perp	T	T	T
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q_0	x	\perp	$a\{x, y\}$	$a\{x\}$	$a\{x\}$	$a\{x\}$	\perp	\top	\top	\top
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$T([x][\cdot_x a(x, x)][\cdot_x c]) \in K$ and $T([x][\cdot_x a(x, y)][\cdot_x c]) \notin K$ even though
 $\delta(q_0, [x][\cdot_x a(x, x)][\cdot_x c]) = \delta(q_0, [x][\cdot_x a(x, y)][\cdot_x c])$.

Minimizing coding automata

Myhill-Nerode relation of a tree language L . Let $c, c' \in C_{\mathcal{V}}C_{\mathcal{V},\Sigma}^*$ be tree codings. $c \equiv_L c'$ if

$$T(cv) \in L \Leftrightarrow T(c'v) \in L \text{ for all } v \in C_{\mathcal{V},\Sigma}^* \text{ such that} \\ T(cv) \in T_{\emptyset} \text{ and } T(c'v) \in T_{\emptyset}.$$

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The minimal automaton Min_L of L is defined as follows:

- the set of states is $Q = \{q_0\} \uplus C_{\mathcal{V}}C_{\mathcal{V},\Sigma}^* / \equiv_L$,
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Minimal automaton

For L a tree language described by a coding automaton, Min_L is a coding automaton which describes L .

Equivalence theorem

For a regular language of finite trees, the following properties are equivalent:

- Being recognized by a finite tree algebra of **polynomial complexity**.
- Being recognized by a finite tree algebra of **bounded orbit complexity**.
- Being **described** by a **coding automaton**.

Let us prove $c. \Rightarrow a.$ and $b.$

From coding automata to tree algebras 1/2

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Every tree language L described by a coding automaton is recognized by a tree algebra that has **polynomial complexity** and **bounded orbit complexity**.

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Fix a tree t with variables x_1, \dots, x_n , we define a function δ_t as

$$\delta_t : \left(\begin{array}{c} \text{arc } q \\ \text{nodes } y_1 \ y_2 \ \dots \ y_r \\ \text{tree } t \\ \text{variables } x_1 x_2 \ \dots \ x_n \end{array} \right) \mapsto \begin{array}{c} \text{arc } q \\ \text{nodes } y_1 \ \dots \ y_r \\ \text{tree } t \\ \text{variables } x_1 x_2 \ \dots \ x_n \end{array} = \begin{array}{c} \text{arc } q' \end{array}$$

where $q \in Q \setminus \{q_0\}$ is a state supported by $\{y_1, \dots, y_m\}$.

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Example For $t = a(x_1, c)$, this is defined by $q' = \delta(q, [\cdot_{y_2} a(x_1, z)][\cdot_z c])$.

From coding automata to tree algebras 1/2

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δ_t is well defined

The definition of δ_t does not depend on a particular choice of coding.
Let $\text{Trans}(\text{Min}_L)$ be the set of all functions δ_t .

From coding automata to tree algebras 2/2

We define the tree algebra \mathcal{A} as

$$A_X = \{ \delta_t \in \text{Trans}(\text{Min}_L) \mid \delta_t \text{ is supported by } X \} .$$

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Support of δ_t

The size of the supports of the δ_t 's is bounded by an integer K .

Let A and B be orbit-finite nominal sets. The set of all functions from A to B with support of size at most K is orbit-finite.

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\mathcal{A} has bounded orbit complexity. $\text{Trans}(\text{Min}_L)$ has finitely many orbits. $f, g \in A_X$ are on the same $\text{Sym}(X)$ -orbit if and only if they are on the same $\text{Sym}(\mathcal{V})$ -orbit.

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\mathcal{A} has polynomial complexity. A_X has boundedly many orbits. On any orbit, there are at most $\frac{|X|!}{(|X|-k)!}$ elements under the action of $\text{Sym}(X)$.

From tree algebras to coding automata

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Structure of the proof.

1. Extend the notion of support to tree algebras, which are a collection of $\mathbf{Sym}(X)$ -sets for $X \subseteq \mathcal{V}$ finite.

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2. Prove that tree algebras of polynomial complexity or bounded orbit complexity have supports of bounded size (say K).
3. Thus, only the elements in sorts A_X where $|X| \leq K$ matter. Let

$$Q = \bigcup_{|X| \leq K} A_X .$$

This is used to define a coding automaton that describes L .

Decidability

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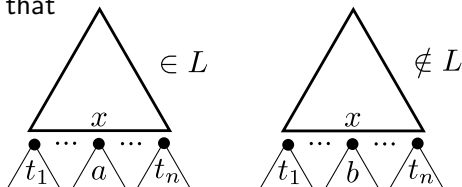
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Fix L . A tree $t \in T_{\{\bullet\}}$ is L -sensitive to a leaf x if there exist trees a, b, t_1, \dots, t_n such that

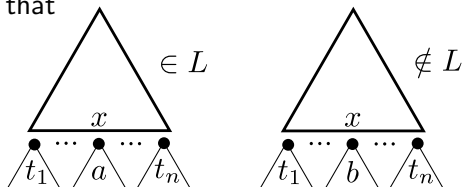


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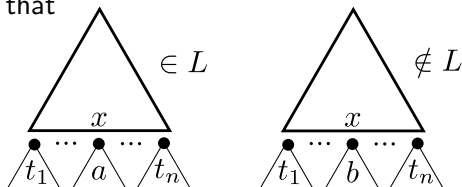
A regular language of trees L is described by a coding automaton if and only if there is a bound on the number of L -sensitive leaves in trees.

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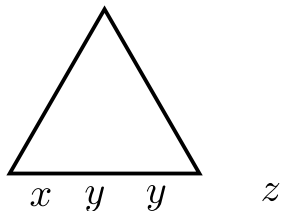
Lemma

A regular language of trees L is described by a coding automaton if and only if there is a bound on the number of L -sensitive leaves in trees.

The existence of such a bound can be encoded into cost-MSO. Thus, it is decidable.

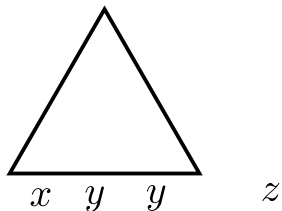
Different types of tree algebras

Unrestrained tree algebras

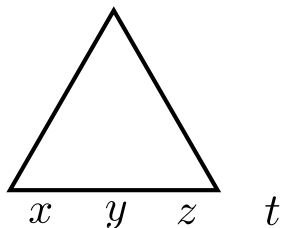


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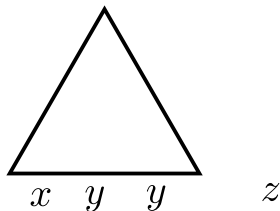


Sublinear tree algebras

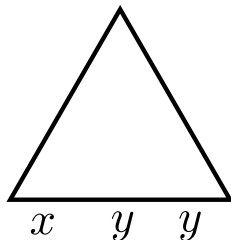


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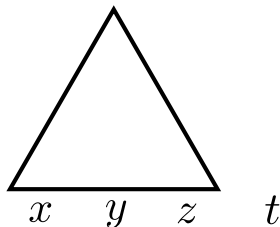
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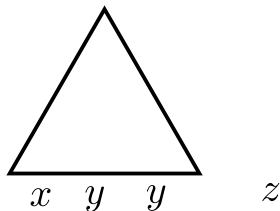


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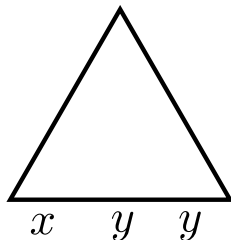


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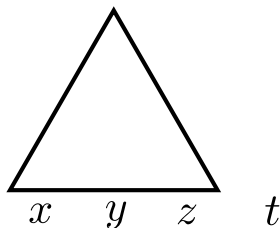
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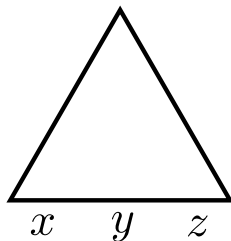
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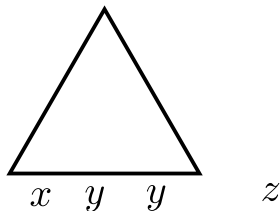


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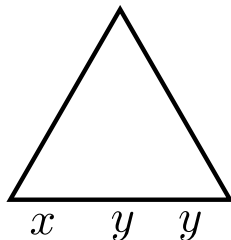


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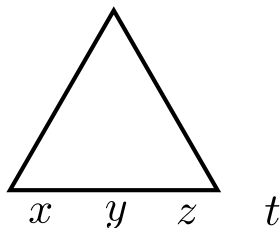
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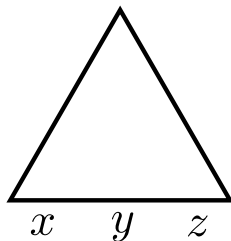
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Conclusion

Equivalence theorem

For a regular language of finite trees, the following properties are equivalent:

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- b. Being recognized by a finite tree algebra of bounded orbit complexity.
- c. Being described by a coding automaton.

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