

The immaculate basis of the non-commutative symmetric functions

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Outline

- 1 Symmetric functions
- 2 Quasi-symmetric functions
- 3 Non-commutative symmetric functions
- 4 The immaculate basis
- 5 Applications

Symmetric Functions

Symmetric functions

Definition: Symmetric Function

A function $f = f(x_1, x_2, \dots, x_n) \in \mathbb{Q}[x_1, \dots, x_n]$ is symmetric if for every collection of positive integers $[\alpha_1, \dots, \alpha_k]$ the coefficient of $x_1^{\alpha_1} \cdots x_k^{\alpha_k}$ is equal to the coefficient of $x_{i_1}^{\alpha_1} \cdots x_{i_k}^{\alpha_k}$ for all i_1, i_2, \dots, i_k .

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Graded Hopf algebra

Sym is a graded Hopf algebra, graded by the degree of the polynomial. The dimension of the graded component of Sym_n is the number of partitions of n .

Monomial symmetric functions

Definition: Monomial Symmetric Function

The monomial symmetric function indexed by λ is:

$$m_\lambda = \sum_{\alpha} x_1^{\alpha_1} \cdots x_n^{\alpha_n},$$

where α runs over all distinct rearrangements of λ .

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Definition: Homogeneous symmetric functions

Let $h_i = \sum_{\lambda \vdash i} m_\lambda$. The complete homogenous functions are:

$$h_\lambda := h_{\lambda_1} h_{\lambda_2} \cdots h_{\lambda_m}.$$

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Definition: Scalar product

The scalar product on Sym_n is defined by $\langle m_\lambda, h_\mu \rangle = \delta_{\lambda, \mu}$.

Schur functions

The most important basis of Sym is the basis of Schur functions. The Schur basis s_λ is defined by any of the following:

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The Jacobi-Trudi rule:

$$s_\lambda := \det \begin{bmatrix} h_{\lambda_1} & h_{\lambda_1+1} & \cdots & h_{\lambda_1+l-1} \\ h_{\lambda_2-1} & h_{\lambda_2} & \cdots & h_{\lambda_2+l-2} \\ \vdots & \vdots & \ddots & \vdots \\ h_{\lambda_\ell-l+1} & h_{\lambda_\ell-l+2} & \cdots & h_{\lambda_\ell} \end{bmatrix} = \det |h_{\lambda_i+j-i}|_{1 \leq i, j \leq \ell}$$

where we use the convention that $h_0 = 1$ and $h_{-m} = 0$ for $m > 0$.

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where we use the convention that $h_0 = 1$ and $h_{-m} = 0$ for $m > 0$.

Example: $\lambda = (2, 1)$

$$s_{2,1} = \begin{vmatrix} h_2 & h_3 \\ h_0 & h_1 \end{vmatrix} = h_2 h_1 - h_3$$

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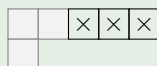
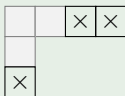
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the sum over all μ for which μ/λ is a horizontal strip of size i

Example: $\lambda = (2, 1)$ and $i = 3$

$$s_{2,1} h_3 = s_{3,2,1} + s_{4,1,1} + s_{4,2} + s_{5,1}$$



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Semi-standard tableaux:

$$s_\lambda = \sum_{T \in \text{SST}(\lambda)} x^T$$

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Example: $\lambda = (2, 1)$ in three variables

$$s_{2,1} = x_1^2 x_2 + x_1 x_2^2 + x_1^2 x_3 + 2x_1 x_2 x_3 + x_2^2 x_3 + x_1 x_3^2 + x_2 x_3^2$$

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 s_{21} & s_{21} & = & s_{2211} & + & s_{222} & + & s_{3111} \\
 \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & & \\ \hline \end{array} & \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & & \\ \hline \end{array} & & \begin{array}{|c|c|c|} \hline \square & \square & \square \\ \hline \square & \square & \square \\ \hline \square & & \\ \hline \end{array} & \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & & & \\ \hline \square & & & \\ \hline \end{array} & \begin{array}{|c|c|c|c|} \hline \square & \square & \square & \square \\ \hline \square & \square & \square & \square \\ \hline \square & & & \\ \hline \end{array} \\
 + & 2s_{321} & + & s_{33} & + & s_{411} & + & s_{42}
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Representation Theory of S_n

Via the Frobenius transformation, the Schur functions correspond to the irreducible representations of the symmetric group.

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Via the Frobenius transformation, the Schur functions correspond to the irreducible representations of the symmetric group.

Representation Theory of GL_n

The Schur functions are the characters of the irreducible representations of the general linear group.

Quasi-symmetric functions

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Definition: Quasi-symmetric function

A function $f = f(x_1, x_2, \dots, x_n) \in \mathbb{Q}[x_1, \dots, x_n]$ is quasi-symmetric if for every collection of positive integers $(\alpha_1, \dots, \alpha_k)$, the coefficient of $x_1^{\alpha_1} \cdots x_k^{\alpha_k}$ is equal to the coefficient of $x_{i_1}^{\alpha_1} \cdots x_{i_k}^{\alpha_k}$ for all $i_1 < i_2 < \cdots < i_k$.

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Hopf Algebra

QSym is a graded Hopf algebra, graded by the degree of the polynomial. The dimension of the graded component QSym_n is the number of compositions of n .

Monomial quasi-symmetric functions

Definition: Monomial quasi-symmetric function

The monomial quasi-symmetric function indexed by a composition α is defined as

$$M_\alpha = \sum_{i_1 < i_2 < \dots < i_m} x_{i_1}^{\alpha_1} x_{i_2}^{\alpha_2} \dots x_{i_m}^{\alpha_m}.$$

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Positive expansion of monomials

It is clear that

$$m_\lambda = \sum_{\alpha} M_\alpha,$$

the sum over all compositions which re-arrange to form the partition λ . This implies that Sym is a subalgebra of QSym .

Fundamental quasi-symmetric functions

Definition: Fundamental basis

The fundamental basis of QSym is defined by:

$$F_\alpha = \sum_{\beta \leq \alpha} M_\beta.$$

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Positive expansion of Schur functions

The Schur functions expand positively in the Fundamental basis nicely:

$$s_\lambda = \sum_{T \in \text{SYT}(\lambda)} F_{D(T)}$$

Non-commutative symmetric functions

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NSym is the algebra generated by the non-commuting elements H_i of degree i , i.e. $\text{NSym} = \mathbb{Q}\langle H_1, H_2, \dots \rangle$.

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Complete homogenous functions

A basis for NSym_n are the non-commutative complete homogenous functions

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Sym is a quotient of NSym

$\chi : \text{NSym} \rightarrow \text{Sym}$ is defined by $\chi(H_\alpha) = h_{\lambda(\alpha)}$.

Representation theory behind NSym

Dual Hopf algebras

NSym and QSym are in fact dual Hopf algebras. There is a scalar product between the two algebras by viewing M_α and H_β as dual bases:

$$\langle M_\alpha, H_\beta \rangle = \delta_{\alpha,\beta}$$

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Representation theory

NSym and QSym are isomorphic to $K_0(H_n(0))$ and $G_0(H_n(0))$ respectively, where $H_n(0)$ denotes the 0-Hecke algebra.

The immaculate basis

Immaculate tableaux

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- 2 the sequence of entries in each row, from left to right, is weakly increasing;
- 3 the sequence of entries in the *first* column, from top to bottom, is increasing.

Example: $\alpha = [4, 2, 3]$ and $\beta = [3, 1, 2, 3]$

1	1	1	3
2	3		
4	4	4	

1	1	1	3
2	4		
3	4	4	

1	1	1	4
2	3		
3	4	4	

1	1	1	4
2	4		
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1	1	1	2
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The immaculate basis

The immaculate basis of NSym can be defined by any of the following:

Jacobi-Trudi type rule:

$$\begin{aligned} \mathfrak{G}_\alpha &:= \det \begin{bmatrix} H_{\alpha_1} & H_{\alpha_1+1} & \cdots & H_{\alpha_1+l-1} \\ H_{\alpha_2-1} & H_{\alpha_2} & \cdots & H_{\alpha_2+l-2} \\ \vdots & \vdots & \ddots & \vdots \\ H_{\alpha_\ell-l+1} & H_{\alpha_\ell-l+2} & \cdots & H_{\alpha_\ell} \end{bmatrix} \\ &= \sum_{\sigma \in \mathcal{S}_\ell} (-1)^\sigma H_{\alpha_1+\sigma_1-1, \alpha_2+\sigma_2-2, \dots, \alpha_\ell+\sigma_\ell-\ell} \end{aligned}$$

where $H_0 = 1$ and $H_{-m} = 0$ for $m > 0$.

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where $H_0 = 1$ and $H_{-m} = 0$ for $m > 0$.

Example: $\alpha = (1, 2)$

$$\mathfrak{S}_{1,2} = \begin{vmatrix} H_1 & H_2 \\ H_1 & H_2 \end{vmatrix} = H_1 H_2 - H_2 H_1$$

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Pieri type rule:

$$\mathfrak{G}_\alpha H_i = \sum_{\beta} \mathfrak{G}_\beta,$$

the sum over all β for which $\alpha_i \leq \beta_i$ and $\text{len}(\beta) \leq \text{len}(\alpha) + 1$.

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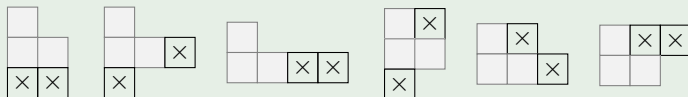
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Example: $\alpha = (1, 2)$ and $i = 2$

$$\mathfrak{G}_{1,2} H_2 = \mathfrak{G}_{1,2,2} + \mathfrak{G}_{1,3,1} + \mathfrak{G}_{1,4} + \mathfrak{G}_{2,2,1} + \mathfrak{G}_{2,3} + \mathfrak{G}_{3,2}$$



The immaculate basis

The immaculate basis of NSym can be defined by any of the following:

Littlewood Richardson type rule:

$$\mathfrak{S}_\alpha \mathfrak{S}_\lambda = \sum_{\beta} c_{\alpha, \lambda}^{\beta} \mathfrak{S}_\beta,$$

$c_{\alpha, \lambda}^{\beta}$ is the number of Yamanouchi tableau of shape β/α and content λ .

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Example: $\alpha = (1, 2), \lambda = (2, 1)$

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 \mathfrak{S}_{12} & \mathfrak{S}_{21} & = & \mathfrak{S}_{1221} & + & \mathfrak{S}_{1311} & + & \mathfrak{S}_{132} & + & \mathfrak{S}_{2211} & + & \mathfrak{S}_{222} \\
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 + & 2\mathfrak{S}_{231} & + & \mathfrak{S}_{141} & + & \mathfrak{S}_{24} & + & \mathfrak{S}_{33} & + & \mathfrak{S}_{321}
 \end{array}$$

The immaculate basis

The immaculate basis of NSym can be defined by any of the following:

A tableaux expansion:

$$\mathfrak{G}_\alpha^* = \sum_{T \in IT(\alpha)} x^T,$$

the sum over immaculate tableaux, where \mathfrak{G}_α^* is the basis of QSym which is dual to the immaculate basis.

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Example: $\alpha = (2, 2)$ in three variables

$$\mathfrak{G}_{22}^* = x_1^2 x_2^2 + x_1 x_2^3 + x_1^2 x_2 x_3 + 2x_1 x_2^2 x_3 + x_1^2 x_3^2 + 2x_1 x_2 x_3^2 + x_2^2 x_3^2 + x_1 x_3^3 + x_2 x_3^3$$

$\begin{array}{ c c } \hline 1 & 1 \\ \hline 2 & 2 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 2 \\ \hline 2 & 2 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 1 \\ \hline 2 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 2 \\ \hline 2 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 3 \\ \hline 2 & 2 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 1 \\ \hline 3 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 2 \\ \hline 3 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 3 \\ \hline 2 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 2 & 2 \\ \hline 3 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 1 & 3 \\ \hline 3 & 3 \\ \hline \end{array}$	$\begin{array}{ c c } \hline 2 & 3 \\ \hline 3 & 3 \\ \hline \end{array}$
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Example: $\alpha = [2, 1, 3]$

$$\mathfrak{G}_{213}^* = F_{1122} + F_{1131} + F_{114} + F_{123} + F_{213}$$

1	4	
2		
3	5	6

1	5	
2		
3	4	6

1	6	
2		
3	4	5

1	3	
2		
4	5	6

1	2	
3		
4	5	6

Applications

A new computation of Littlewood-Richardson coefficients

Relationship amongst coefficients

For compositions α, β, ν and a partition λ such that $\ell(\nu) \leq \ell(\alpha)$,

$$C_{\alpha, \lambda}^{\beta} = C_{\alpha + \nu, \lambda}^{\beta + \nu}$$

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Example: $\lambda = (2, 1)$ and $\alpha = (1, 1)$

$$\begin{aligned} \mathfrak{S}_{1,1} \mathfrak{S}_{2,1} &= \mathfrak{S}_{1,1,2,1} + \mathfrak{S}_{1,2,1,1} + \mathfrak{S}_{1,2,2} + \mathfrak{S}_{1,3,1} + \mathfrak{S}_{2,1,1,1} + \mathfrak{S}_{2,1,2} \\ &\quad + 2\mathfrak{S}_{2,2,1} + \mathfrak{S}_{2,3} + \mathfrak{S}_{3,1,1} + \mathfrak{S}_{3,2}. \end{aligned}$$

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Therefore:

$$\begin{aligned} \mathfrak{S}_{3,2} \mathfrak{S}_{2,1} &= \mathfrak{S}_{3,2,2,1} + \mathfrak{S}_{3,3,1,1} + \mathfrak{S}_{3,3,2} + \mathfrak{S}_{3,4,1} + \mathfrak{S}_{4,2,1,1} + \mathfrak{S}_{4,2,2} \\ &\quad + 2\mathfrak{S}_{4,3,1} + \mathfrak{S}_{4,4} + \mathfrak{S}_{5,2,1} + \mathfrak{S}_{5,3} \end{aligned}$$

Modules for the immaculate basis

Representation Theory of 0-Hecke algebra

The irreducible representations of $H_n(0)$ are all one dimensional. Under the identification of QSym with $G_0(H_n(0))$, an irreducible indexed by α corresponds to the fundamental quasi-symmetric function F_α .

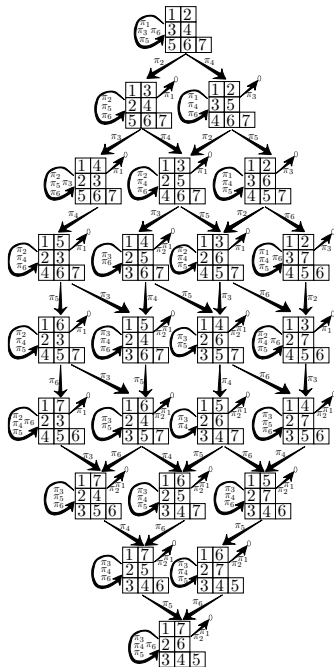
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Construction of modules

There exists a combinatorially defined, indecomposable, finite dimensional, representation \mathcal{V}_α of $H_n(0)$ whose characteristic is \mathfrak{S}_α^* .



The hook length formula by example

Proposition: Hook length formula

If $\alpha \models n$, the number of standard immaculate tableaux of shape α is equal to

$$\frac{n!}{\prod_{c \in \alpha} h_{\alpha}(c)}$$

where $c \in \alpha$ indicates $c = (i, j)$ with $1 \leq i \leq \ell(\alpha)$ and $1 \leq j \leq \alpha_i$.

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Example: $\alpha = [4, 2, 3]$

9	3	2	1
5	1		
3	2	1	

The number of standard immaculate tableaux of shape $[4, 2, 3]$ is equal to

$$\frac{9!}{9 \cdot 3 \cdot 2 \cdot 1 \cdot 5 \cdot 1 \cdot 3 \cdot 2 \cdot 1} = 224 .$$

THANKS!

Slides to be available on the web.

Immaculate basis and their duals available in Sage!

Papers: 1208:5191, 1304:1224 , 1305:4700

FPSAC Abstract: 1303:4801

