# Simplicity of Lyapunov exponents for integral cocycles over countable shifts

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Some MCF algorithms Some applications

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#### Countable shifts

- $\Lambda = \text{finite or countable alphabet}$
- $\Sigma=\Lambda^{\mathbb{N}}=\mathsf{shift}$  space

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 $\Omega = \bigcup_{n \geq 0} \Lambda^n = \mathsf{set}$  of finite words

 $\Sigma(\underline{\ell}) = \{x \in \Sigma \text{ starting by } \underline{\ell}\} = cylinder associated to \underline{\ell} \in \Omega.$ 

#### Bounded distortion

#### Definition

 $\mu = f$ -inv. prob. measure has bounded distortion if  $\exists C \ge 1$  s.t.

 $C^{-1}\mu(\Sigma(\underline{\ell}_1)) \cdot \mu(\Sigma(\underline{\ell}_2)) \leq \mu(\Sigma(\underline{\ell}_1\underline{\ell}_2)) \leq C\mu(\Sigma(\underline{\ell}_1)) \cdot \mu(\Sigma(\underline{\ell}_2))$ 

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#### Example (Bernoulli shifts)

$$\Lambda = \{1, \dots, k\}, \ \nu(\{i\}) = p_i \in (0, 1), \ \sum_{i=1}^k p_i = 1 \implies \mu = \nu^{\mathbb{N}} \text{ has}$$
  
bounded distortion (with  $C = 1$ ).

"Bounded distortion = almost Bernoulli"

#### Locally constant integrable cocycles

Let G be a matrix group acting on  $\mathbb{K}^d$ , where  $\mathbb{K} = \mathbb{R}$ ,  $\mathbb{C}$  or **H**.

Example (some classical groups)

 $G = GL(d, \mathbb{R})$ ,  $SL(d, \mathbb{R})$ ,  $Sp(d, \mathbb{R})$ , O(p, q),  $U_{\mathbb{C}}(p, q)$ ,  $U_{\mathbf{H}}(p, q)$ , p + q = d,  $O(d, \mathbf{H})$ , etc.

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Definition (Locally constant integrable cocycle)

It is 
$$A : \Sigma \to G$$
,  $A((x_i)_{i \in \mathbb{N}}) = A_{x_0} \in G$  s.t.  $\int_{\Sigma} \log \|A^{\pm 1}(\underline{x})\| d\mu(\underline{x})$   
=  $\sum_{\ell \in \Lambda} \mu(\Sigma(\ell)) \log \|A_{\ell}^{\pm 1}\| < \infty$ .

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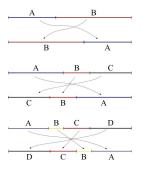
By Oseledets theorem, we have Lyapunov exponents  $\theta_1 \geq \cdots \geq \theta_d$  describing the fiber dynamics of

$$(f, A): \Sigma \times \mathbb{K}^d \to \Sigma \times \mathbb{K}^d, \quad (f, A)(\underline{x}, v) = (f(\underline{x}), A(\underline{x})v)$$

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

#### Rauzy–Veech algorithm (I): interval exchange maps

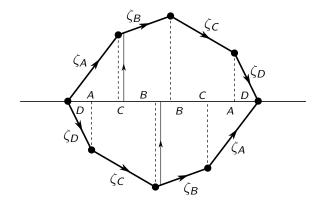
An *interval exchange map* of  $d \ge 2$  subintervals of a bounded open interval I is an injective map  $T: D_T \to D_{T^{-1}}$  where  $D_T, D_{T^{-1}} \subset I$ with  $\#(I - D_T) = \#(I - D_{T^{-1}}) = d - 1$  and  $T|_{\text{c.c. of } D_T}$  is a translation onto a c.c. of  $D_{T^{-1}}$ .



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## Rauzy–Veech algorithm (II): translation surfaces

The first return map of a translation flow on a *translation surface* is an interval exchange map.



Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

### Rauzy–Veech algorithm (III): renormalization

An elementary step of the Rauzy–Veech algorithm takes an i.e.m. T to the i.e.m.  $\hat{T}$  = first return of T-orbits to  $\hat{I} = (a, b)$  where  $a = \min\{I - D_T, I - D_{T^{-1}}\}$  and  $b = \max\{I - D_T, I - D_{T^{-1}}\}$ .

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#### Example (Elementary step on i.e.m. with d = 2)

The i.e.m. 
$$T(x) = \begin{cases} x + \alpha, & \text{if } 0 < x < 1 - \alpha \\ x - (1 - \alpha), & \text{if } 1 - \alpha < x < 1 \end{cases}$$
 is taken to  
$$\widehat{T}(x) = \begin{cases} x + \alpha, & \text{if } 0 < x < 1 - 2\alpha \\ x - (1 - 2\alpha), & \text{if } 1 - 2\alpha < x < 1 - \alpha \end{cases} \text{for } 0 < \alpha < \frac{1}{2}.$$

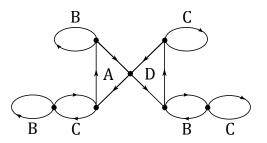
#### Remark

The previous example is an elementary step of the Euclidean division algorithm on the lengths  $1 - \alpha$  and  $\alpha$  of the c.c. of  $D_T$ .

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

# Rauzy–Veech algorithm (IV): finite shifts

The Rauzy–Veech algorithm is coded by a finite graph (*Rauzy diagram*) whose arrows are decorated with  $d \times d$  matrices  $B_{\gamma} = \text{Id} + E_{\alpha\beta} \in SL(d, \mathbb{Z})$  (where  $E_{\alpha\beta} = \text{elementary matrix}$ ).



Roughly speaking, the vertices of this graph account for the permutations of subintervals and the matrices  $B_{\gamma}$  encode the changes of lengths of subintervals.

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

# Rauzy–Veech algorithm (IV): countable shifts

After *accelerating* (Zorich, Yoccoz, Avila-Viana, etc.), one gets a loc. constant integ. (Kontsevich-Zorich) cocycle over a countable shift with a (Masur-Veech) prob. meas. having *bounded distortion*.

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The Lyapunov exponents of this cocycle have the form

$$\theta_1 > \theta_2 \ge \cdots \ge \theta_g \ge \underbrace{0 = \cdots = 0}_{s-1 \text{ times}} \ge -\theta_g \ge \cdots \ge -\theta_2 > -\theta_1$$

where d = 2g + s - 1 and g is the genus of the underlying translation surfaces.

#### Remark

This structure of the Lyapunov spectrum is explained by the fact that  $B_{\gamma} \in SL(d, \mathbb{Z})$  corresponds to an action in the first relative homology of a translation surface, i.e.,  $B_{\gamma}$  is symplectic in disguise.

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#### Rauzy gasket (I): special systems of isometries

A special system of isometries is a collection  $\phi_j : [0, x_j] \rightarrow [y_j, 1]$ ,  $1 \le j \le 3$ , of translations between intervals with  $x_1 + x_2 + x_3 = 1$ .

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Some eclectic motivations for the study of systems of isometries come from:

- pseudo-groups of rotations and free actions on ℝ-trees (Levitt, Gaboriau, Paulin),
- Novikov's problem (Dynnikov, de Leo),
- letter freq. in ternary episturmian words (Arnoux, Starosta).

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# Rauzy gasket (II): Rauzy–Dynnikov algorithm

Similarly to the case of interval exchange maps, we can renormalize special systems of isometries as follows.

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# Rauzy gasket (II): Rauzy–Dynnikov algorithm

Similarly to the case of interval exchange maps, we can renormalize special systems of isometries as follows.

The parameter space is  $\Delta = \{(x_1, x_2, x_3) \in \mathbb{R}^3_+ : x_1 + x_2 + x_3 = 1\}$ . Let  $\Delta_j = \{(x_1, x_2, x_3) \in \Delta : x_j \ge \sum_{k \neq j} x_k\}$ ,  $1 \le j \le 3$ . The projectivizations of

$$M_1 = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \quad M_2 = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}, \quad M_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

induce weakly contracting maps  $f_j \colon \Delta o \Delta_j$ , j = 1, 2, 3.

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induce weakly contracting maps  $f_j \colon \Delta \to \Delta_j$ , j = 1, 2, 3.

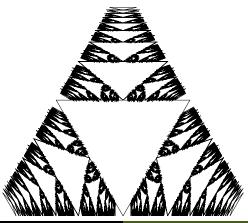
We renormalize a parameter outside the hole  $\Delta \setminus \bigcup_{j=1}^{3} \Delta_{j}$  by applying the inverse of the appropriate  $f_{j}$ .

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

## Rauzy gasket (III): Rauzy gasket

The *Rauzy gasket* is the non-empty compact subset R of  $\Delta$  s.t.

 $R = f_1(R) \cup f_2(R) \cup f_3(R).$ 



C. Matheus

Simplicity of Lyapunov exponents and Galois theory

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

#### Rauzy gasket (IV): countable shifts

The Rauzy-Dynnikov algorithm is also coded by a finite graph whose arrows are decorated by matrices in  $SL(3,\mathbb{Z})$ .

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### Rauzy gasket (IV): countable shifts

The Rauzy-Dynnikov algorithm is also coded by a finite graph whose arrows are decorated by matrices in  $SL(3,\mathbb{Z})$ .

By *accelerating* (and using thermodynamical methods), one gets a loc. constant integ. cocycle over a countable shift with a (Avila-Hubert-Skripchenko) prob. meas. with bounded distortion.

#### Remark

An analogous discussion holds for the *fully subtractive algorithm* because it is "dual" to the Rauzy-Dynnikov algorithm (as it was first noticed by Arnoux-Starosta).

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

#### Selmer and Cassaigne algorithms

The (homogenous) Selmer algorithm sends  $(x_1, x_2, x_3) \in \Delta$  with  $0 < x_1 < x_2 < x_3$  to  $\frac{1}{1-x_1}(x_1, x_2, x_3 - x_1) \in \Delta$ , etc.

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

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It was noticed by Cassaigne the dynamics can be also encoded by the algorithm

$$(x_1, x_2, x_3) \in \Delta \mapsto \left\{ egin{array}{cc} (x_1 - x_3, x_3, x_2) & ext{if } x_1 > x_3 \ (x_2, x_1, x_3 - x_1) & ext{if } x_1 < x_3 \end{array} 
ight.$$

Rauzy–Veech algorithm Rauzy gasket Cassaigne algorithm

#### Countable shifts

In the same spirit of the Rauzy-Veech algorithm, the Cassaigne algorithm was accelerated by Fougeron-Skripchenko to produce a loc. constant integ. cocycle over a countable shift with a prob. meas. with bounded distortion.

# Furstenberg simplicity criterion for $SL(2,\mathbb{R})$

#### Theorem (Furstenberg)

Consider a loc. constant  $SL(2,\mathbb{R})$ -valued cocycle  $A : \Sigma \to SL(2,\mathbb{R})$ over a Bernoulli shift  $(\Sigma, \mu)$  (i.e., a finitely supported random walk on  $SL(2,\mathbb{R})$ ). If

 the group generated by A(Σ) is not contained in a conjugated of SO(2, ℝ) nor preserves a line in ℝ<sup>2</sup>, and

• the group generated by  $A(\Sigma)$  does not preserve a pair of lines, then  $\theta_1 > 0$ .

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#### Remark

We shall see that these assumptions are particular instances of *Zariski-density* (cf. Guivarc'h-Raugi, Goldsheid-Margulis) and *pinching and twisting* (cf. Avila-Viana).

# Guivarc'h-Raugi and Goldsheid-Margulis simplicity criteria

Let G be a semisimple Lie group.

#### Theorem (Guivarc'h-Raugi, Goldsheid-Margulis)

Consider a loc. constant G-valued cocycle  $A : \Sigma \to G$  over a Bernoulli shift  $(\Sigma, \mu)$  (i.e., a finitely supported random walk on G). If the monoid generated by  $A(\Sigma)$  is Zariski dense in G, then the Lyapunov exponents are "as simple as possible": the Lyapunov vector belongs to the interior of the Weyl chamber.

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#### Example

For G = SO(p,q),  $q \le p$ , a typical diagonal matrix has the form  $\operatorname{diag}(e^{\theta_1}, \ldots, e^{\theta_q}, \underbrace{1, \ldots, 1}_{p-q \text{ times}}, e^{-\theta_q}, \ldots, e^{-\theta_1})$  and, hence, a "simple" Lyapunov spectrum is  $\theta_1 > \cdots > \theta_q > 0^{p-q} > -\theta_q > \cdots > -\theta_1$ .

# Avila-Viana simplicity criteria (I)

#### Theorem (I)

Consider a loc. constant integ. cocycle  $A : \Sigma \to GL(d, \mathbb{C})$  over a countable shift with a prob. meas. having bounded distortion. If

- A is pinching: ∃ a finite word <u>ℓ</u> = (ℓ<sub>0</sub>,..., ℓ<sub>n-1</sub>) ∈ Ω s.t. all eigenvalues of A<sup>ℓ</sup> := A<sub>ℓn-1</sub>... A<sub>ℓ0</sub> have distinct moduli;
- A is twisting: ∃ a finite word <u>k</u> ∈ Ω s.t. A<sup>k</sup>(F) ∩ F' = {0} for all A<sup>ℓ</sup>-invariant n-plane F and (d − n)-plane F', 1 ≤ n ≤ d,

then the Lyapunov spectrum of A is simple.

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#### Remark

It is *crucial* to get a *single* element  $A^{\underline{k}}$  twisting *all*  $A^{\underline{\ell}}$ -invariant subspaces at the *same* time: e.g.,  $A_0 = \text{diag}(2, 1/2)$  and  $A_1$ =rotation by  $\pi/2$  lead to zero exponents.

#### Avila-Viana simplicity criteria (II)

#### Theorem (II)

Consider a loc. constant integ. cocycle  $A : \Sigma \to Sp(2d, \mathbb{R})$  over a countable shift with a prob. meas. having bounded distortion. If

- A is pinching: ∃ a finite word <u>ℓ</u> ∈ Ω s.t. all eigenvalues of A<sup>ℓ</sup> are real and simple;
- A is twisting: ∃ <u>k</u> ∈ Ω s.t. A<sup><u>k</u></sup>(F) ∩ F' = {0} for all A<sup>ℓ</sup>-inv. isotropic F and coisotropic F' with dim F + dim F' = 2d,

then the Lyapunov spectrum of A is simple.

# Zariski-density versus pinching and twisting

Zariski density implies pinching and twisting, but the converse is *not* true in general.

On the other hand, Zariski density is *easier* to check in practice and it allows for an *uniform* statement independently of the semisimple Lie group G.

For this reason, Möller, Yoccoz and I looked for simplicity criteria *closer* to the Zariski density assumption of Guivarc'h-Raugi and Goldsheid-Margulis.

## Galois-theoretical simplicity criterion

#### Theorem (M.-Möller-Yoccoz)

Let G = SL(d) or Sp(2d). Consider a loc. const. integ. cocycle  $A : \Sigma \to G(\mathbb{Z})$  over a countable shift with a prob. meas. with bounded distortion. If the monoid generated by  $A(\Sigma)$  contains two Galois-pinching elements (i.e., their characteristic polynomials are irreducible with all roots  $\in \mathbb{R}$  and largest possible Galois group) with disjoint splitting fields, then A has simple Lyapunov spectrum.

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#### Remark

This result holds for other semisimple Lie groups (after adjusting the definition of Galois-pinching).

## Galois-pinching and Zariski density

The Galois-theoretical simplicity criterion is closer to Zariski density thanks to the following results of Prasad-Rapinchuk:

- any Zariski-dense subgroup of G(Z) contains a Galois-pinching element;
- if a monoid Γ ⊂ G(Z) contains a Galois-pinching element γ<sub>1</sub> and an element γ<sub>2</sub> of infinite order not commuting with γ<sub>1</sub>, then the Zariski closure of Γ is G or the subgroup H associated to the longest roots.

### How to check the Galois-theoretical criterion in practice?

Let  $P(x) = x^4 + ax^3 + bx^2 + ax + 1 \in \mathbb{Z}[x]$  be the characteristic polynomial of an element of  $Sp(4,\mathbb{Z})$ .

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By Galois theory, P has the largest possible Galois group if and only if  $\Delta_1 := a^2 - 4b + 8$ ,  $\Delta_2 := (b + 2 + 2a)(b + 2 - 2a)$  and  $\Delta_1 \Delta_2$  are not squares. In this case, the quadratic subfields of the splitting field are  $\mathbb{Q}(\sqrt{\Delta_1})$ ,  $\mathbb{Q}(\sqrt{\Delta_2})$ ,  $\mathbb{Q}(\sqrt{\Delta_1\Delta_2})$ .

Moreover, P has real, positive, simple roots if and only if  $\Delta_1 > 0$ , t := -a - 4 > 0 and d := b + 2 + 2a > 0.

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#### Remark

Rivin found some interesting polynomial time (mostly probabilistic) algorithms to compute Galois groups of characteristic polynomials, to determine the Zariski denseness assumption in Guivarc'h-Raugi and Goldsheid-Margulis theorems when G = SL(d) or Sp(2d), etc.

## Zorich phenomenon, square-tiled surfaces, ...

Avila-Viana famously used their simplicity criterion to establish that the Lyapunov spectrum of the accelerations of the Rauzy-Veech algorithm have the form

$$\theta_1 > \theta_2 > \cdots > \theta_g > 0^{s-1} > -\theta_g > \cdots > -\theta_2 > -\theta_1,$$

so that the deviations of ergodic averages of almost all i.e.m.  $\ensuremath{\mathcal{T}}$  are

$$\sum_{n=0}^{N-1} f(T^n(x)) = \left(\int f\right) N + c_2(f,x) N^{\theta_2/\theta_1} + \dots$$

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$$\theta_1 > \theta_2 > \cdots > \theta_g > 0^{s-1} > -\theta_g > \cdots > -\theta_2 > -\theta_1,$$

so that the deviations of ergodic averages of almost all i.e.m.  $\ensuremath{\mathcal{T}}$  are

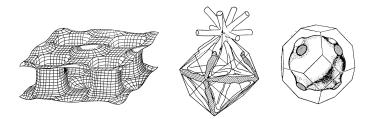
$$\sum_{n=0}^{N-1} f(T^n(x)) = \left(\int f\right) N + c_2(f,x) N^{\theta_2/\theta_1} + \dots$$

M.-Möller-Yoccoz used the Galois-theoretical criterion together with Faltings' theorem (on rational points on genus > 1 curves) to show the simplicity of the Lyapunov spectra of the cocycles over finite extensions of the Gauss map associated to the "majority" of square-tiled surfaces in  $\mathcal{H}(4)$ .

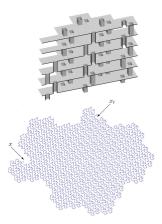
## Novikov's problem (I)

Novikov wanted to understand the trajectories of electrons in a metal subjected to an uniform magnetic field.

Mathematically, some of these electrons travel along the intersection of Fermi surfaces and the family of planes orthogonal to the magnetic field.



## Novikov's problem (II)



The diffusion rate of typical trajectories is driven by  $-\theta_3/\theta_1$  where  $\theta_1 \ge \theta_2 \ge \theta_3$  are the Lyapunov exponents of the Rauzy gasket.

# Novikov's problem (III)

By the duality with the fully subtractive algorithm, one has  $\theta_1 > 0 > \theta_2 \ge \theta_3$  (after Avila-Delecroix).

Since  $\theta_1 + \theta_2 + \theta_3 = 0$  (because the cocycle is  $SL(3, \mathbb{Z})$ -valued), Avila-Hubert-Skripchenko could apply the Galois-theoretical simplicity criterion to get  $\theta_1 > 0 > \theta_2 > \theta_3$  and, *a fortiori*,

$$- heta_3/ heta_1 > 1/2$$

## Uniform approximation exponent of Cassaigne's algorithm

In a recent work, Fougeron-Skripchenko used Lagarias' work and the Galois-theoretical simplicity criterion to check that the positivity of the uniform approximation exponent

 $1 - \theta_2/\theta_1$ 

of Cassaigne algorithm: in a nutshell, the Lyapunov spectrum  $\theta_1 > \theta_2 > \theta_3$  of this algorithm is simple because the matrices

1	_	_	$1 \setminus$				2	
	1	1	1	and	2	4	3	
			2 /				1 /	

are Galois-pinching with disjoint splitting fields (as their characteristic polynomials  $x^3 - 4x^2 + 1$  and  $x^3 - 6x^2 + 1$  have discriminants 229 and  $3^3 \cdot 31$ , etc.).

### Concluding remarks

It is clear that this list of applications of these simplicity criteria based on Galois theory and Zariski density is incomplete, and I hope that these techniques (together with suitable numerical support) will fit the context of many others MCF algorithms.

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It is clear that this list of applications of these simplicity criteria based on Galois theory and Zariski density is incomplete, and I hope that these techniques (together with suitable numerical support) will fit the context of many others MCF algorithms.

Thank you! Merci! Spasíbo!