



Towards less manipulable voting systems

François Durand, Fabien Mathieu, Ludovic Noirie

Introduction: voting systems

Context:

- ▶ Origins in **politics**.
- ▶ Applications in any situation of **collective choice**.

Questions:

- ▶ Is there a natural way to select a **reasonable winner**?
- ▶ Can we **trust** the electors?
- ▶ If not, is it possible to design a voting system that is **resistant to manipulation**?

Terminology warning: “manipulation”

= internal manipulation by electors themselves

= tactical voting

≠ “bribery” (somebody pays electors to change their votes), etc.



Plan

Previously on voting systems. . .

- In quest for a reasonable winner

- Presentation of manipulability

- Reducing manipulability, step 1: condorcification

Reducing manipulability, step 2: slicing

- Introduction

- Idea of the theorem in a particular case

- Generalization of the theorem

Conclusion and future work



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A simplified framework

n **electors**.

m **candidates** named A, B, C...

Each elector i has a **binary relation** r_i over the candidates, that represents her **preferences**.

- ▶ Example of i 's preferences: $A \sim B \succ D \succ C$.

Voting system $f : (r_1, \dots, r_n) \rightarrow v \in \{A, B, C \dots\}$.

2 candidates: May's theorem

Plurality (= “uninominal à un tour”):

- ▶ Each elector votes for one candidate.
- ▶ The candidate with most votes gets elected.

May's theorem (1952): plurality is the only anonymous, neutral and positively responsive voting system for 2 candidates.

3 candidates or more: Condorcet winner

Independence of irrelevant alternatives (IIA): if we remove one of the losing candidates, the winner should remain the same.

E.g. if C wins, then she must win any electoral duel versus A or B. If it is the case, we say that she's a **Condorcet winner**.

Example:

		Electors		
		40	35	25
Preferences	A	B	C	
	C	C	A	
	B	A	B	

"Majority matrix":

	A	B	C	Victories
A				0
B				0
C				0

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A		65		1
B	35			0
C				0

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	A	B	C
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“Majority matrix”:

	A	B	C	Victories
A		65	40	1
B	35			0
C	60			1

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“Majority matrix”:

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A		65	40	1
B	35		35	0
C	60	65		2

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B	35		35	0
C	60	65		2

If we want to extend Plurality for $m \geq 3$ and respect IIA, then C must be elected. We then say that our voting system respects **Condorcet criterion**.

3 candidates or more: Condorcet's paradox

Example:

		Electors		
		40	35	25
Preferences	A	B	C	A
	B	C	A	B
	C	A	B	C

"Majority matrix":

		A	B	C	Victories
A			65	40	1
B	35			75	1
C	60	25			1

Condorcet's paradox (1785): A defeats B, B defeats C and C defeats A.

It's not possible to extend Plurality for $m \geq 3$ while respecting independence of irrelevant alternatives (IIA).

Arrow's theorem

We would like a voting system with the following properties.

- ▶ **Non-dictatorship:** there is not one elector who always decides alone.
- ▶ **Unanimity:** whenever all electors prefers A to B, candidate B cannot get elected.
- ▶ **Independence of irrelevant alternatives (IIA):** if we remove one of the losing candidates, the winner should remain the same.



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- ▶ **Independence of irrelevant alternatives (IIA):** if we remove one of the losing candidates, the winner should remain the same.

Arrow's theorem (1951): for $m \geq 3$ candidates, such a voting system does not exist.

⇒ For $m \geq 3$ candidates, there is no “natural”, canonical way to aggregate binary relations of preferences from several electors in order to choose a winning candidate.



Extending the framework of preferences

Old framework: binary relations of preferences only.

Example of extended framework:

- ▶ Each elector has a **utility vector** about the candidates, e.g. $(10, 10, 0, 2)$.
- ▶ This utility vector induces a binary relation of preferences over the candidates, e.g. $A \sim B \succ D \succ C$.



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General extended framework:

- ▶ Each elector i has a **state** $\omega_i \in \Omega_i$,
- ▶ This state contains enough information so that we can extract her **binary relation of preference** $r_i = R_i(\omega_i)$.

Voting system $f : (\omega_1, \dots, \omega_n) \rightarrow v \in \{A, B, C, \dots\}$.



Escaping Arrow's theorem

Example: range voting.

- ▶ Each elector gives her utility vector, that is, a note for each candidate.
- ▶ The candidate with highest average (or median) wins.

This voting system is **non-dictatorial**, **unanimous** and **independent of irrelevant alternatives**... and infinitely many other voting systems are too!

So... have we won? Have we found a voting system that is fully satisfying?



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Manipulability: an example

Voting system: range voting.

		Sincere			
		A	B		
Electors	80%	7	5		
	20%	2	5		
Average		6	5		
Winner		A			

Manipulability: an example

Voting system: range voting.

		Sincere		Tactical	
		A	B	A	B
Electors	80%	7	5	7	5
	20%	2	5	0	10
Average		6	5	5,6	6
Winner		A		B	

We say that this situation is **manipulable** for this voting system:

- ▶ A subset of electors, by casting a tactical ballot, may change the result to a candidate they prefer.
- ▶ I.e., sincere voting is not a **strong Nash equilibrium**.

Gibbard's theorem

Gibbard's theorem (1973): for any non-dictatorial voting system with at least 3 eligible candidates, there exists a situation that is manipulable by one elector.

I.e.: this situation is not even a **weak Nash equilibrium**.



Manipulability rate

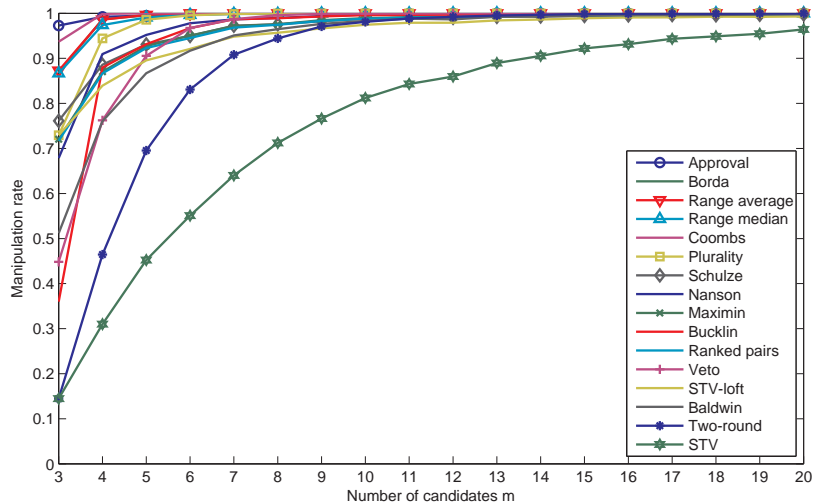
We draw a situation $\omega = (\omega_1, \dots, \omega_n)$ (states of all electors) according to a **probability measure** P .

Manipulability rate: what is the probability that this situation ω is manipulable for voting system f ?

$$\rho_P(f) = P(\omega \text{ is } f\text{-manipulable}).$$

Manipulability is quite frequent

$P =$ "Uniform spherical culture", $n = 33$ electors



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Condorcification

Durand, Mathieu and Noirie (2012)

The **condorcification** of f is a new voting system f^c :

- ▶ Whenever there exists a Condorcet winner, designate her;
- ▶ Otherwise, use f .

If f has reasonable properties, then f^c is **at most as manipulable** as f :

- ▶ Any situation ω manipulable for f^c is manipulable for f ;
- ▶ In particular, $\rho_P(f^c) \leq \rho_P(f)$ for any probability measure P .

If f meets a simple condition, then f^c is **strictly less manipulable** than f . It is the case for all classical voting systems that do not meet Condorcet criterion already (except veto).

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Goal

Some voting systems may not depend on binary relations of preference only.

- ▶ Example: range voting (a note for each candidate).

Intuition:

- ▶ Binary relations of preference = **necessary information** (define Condorcet winner and coalitions).
- ▶ More information than that = **more opportunities for lies**.

Our goal: restrict to binary relations of preferences while reducing manipulability.

- ▶ Restrict the scope of research for a voting system with the lowest manipulability.



Reminder of the framework

Electoral space:

- ▶ n : number of electors
- ▶ m : number of candidates
- ▶ ω_i : elector i 's state (utilities, etc.)
- ▶ $r_i = R_i(\omega_i)$: elector i 's binary relation of preference over the candidates

Voting system:

$$f : (\omega_1, \dots, \omega_n) \rightarrow v \in \{A, B, \dots\}.$$

Manipulability of voting system f : a more formal definition

Situation $\omega = (\omega_1, \dots, \omega_n)$ is f -**manipulable to situation** ψ iff:

$$\begin{cases} f(\psi) \neq f(\omega), \\ \forall \text{ elector } i, \psi_i \neq \omega_i \Rightarrow f(\psi) \succ_{R_i(\omega_i)} f(\omega). \end{cases}$$

Situation ω is f -**manipulable** iff there exists such a ψ .

Manipulability indicator of f :

$$M_f(\omega) = \begin{cases} 1 & \text{if } \omega \text{ is } f\text{-manipulable,} \\ 0 & \text{otherwise.} \end{cases}$$

With P a probability distribution used to draw the situation ω , the **manipulability rate** of f is:

$$\rho_P(f) = \int M_f(\omega) P(d\omega).$$

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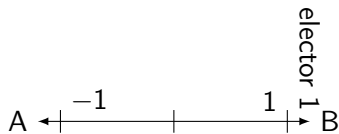
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Example

2 electors, 2 candidates named A (−) and B (+).

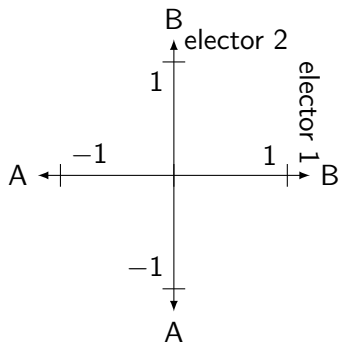
$\omega_i = (r_i, y_i)$, where $y_i \in]0, 1]$ is an intensity of preference.



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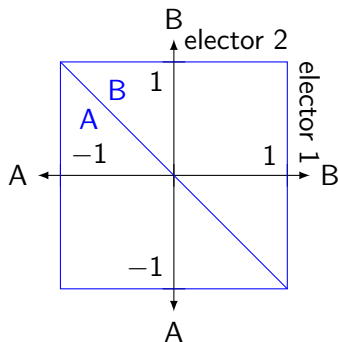


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2 electors, 2 candidates named A (−) and B (+).

$\omega_i = (r_i, y_i)$, where $y_i \in]0, 1]$ is an intensity of preference.

Voting system f : elect sign of the sum.

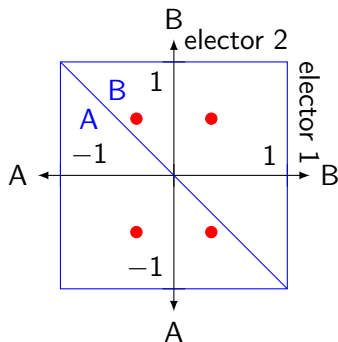


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Voting system f : elect sign of the sum.



E.g. do as if $y_1 = \frac{1}{3}$ and $y_2 = \frac{1}{2}$, whatever electors say.

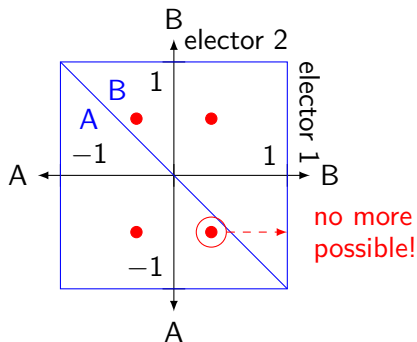
- ▶ **Sliced** voting system f_y .
- ▶ Depends on r_1 and r_2 only.

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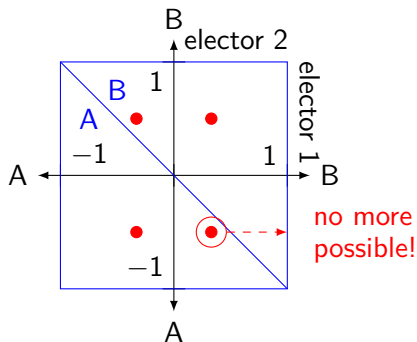
Red situations are less manipulable than before!

Example

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- ▶ **Sliced** voting system f_y .
- ▶ Depends on r_1 and r_2 only.

Red situations are less manipulable than before!

If r and y are independent, then f 's manipulability rate is the average of its restrictions to such red figures.

A particular case for the slicing theorem

Elector i 's state: $\omega_i = (r_i, y_i)$

- ▶ r_i : elector i 's binary relation of preference over the candidates
- ▶ y_i : **additional information** about elector i 's preferences

Probability laws:

- ▶ $\omega = (\omega_1, \dots, \omega_n) \in \Omega \sim P$
- ▶ $R(\omega) = (r_1, \dots, r_n) \in \mathcal{R} \sim \mu$ (law induced by P)
- ▶ $Y(\omega) = (y_1, \dots, y_n) \in \mathcal{Y} \sim \nu$ (law induced by P)

Assumption: random variables R and Y are **independent**.

- ▶ $(\Omega, P) = (\mathcal{R}, \mu) \times (\mathcal{Y}, \nu)$.

Does **not** mean that electors are independent!

Slicing theorem

Durand, Mathieu and Noirie (2013)

Lemma

For situations of type (r, y) , slice f_y is less manipulable than f :

$$M_{f_y}(r, y) \leq M_f(r, y).$$

Sketch of proof: the same candidate is elected, but opportunities for tactical voting are limited (red situations in previous example).

Theorem

There exists y such that $\rho_P(f_y) \leq \rho_P(f)$.

Remark

If f respects Condorcet criterion, then any slice f_y does.

- ▶ Final voting system f_y is interesting (not dictatorial).

Proof of the theorem

For any y , we have:

$$\begin{aligned}\rho_P(f_y) &= \int \mu(dr) \int \nu(dy') M_{f_y}(r, y') && \text{(Fubini)} \\ &= \int \mu(dr) M_{f_y}(r, y). && (f_y \text{ depends on } r \text{ only})\end{aligned}$$

Manipulability of f :

$$\begin{aligned}\rho_P(f) &= \int \nu(dy) \int \mu(dr) M_f(r, y) && \text{(Fubini)} \\ &\geq \int \nu(dy) \underbrace{\int \mu(dr) M_{f_y}(r, y)}_{=\rho_P(f_y)} && \text{(lemma)}\end{aligned}$$

So, there exists y such that $\rho_P(f_y) \leq \rho_P(f)$.

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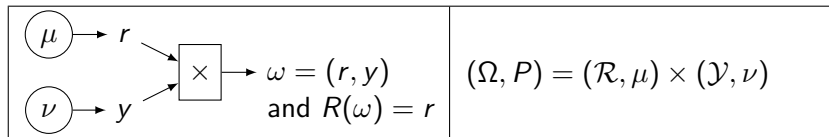
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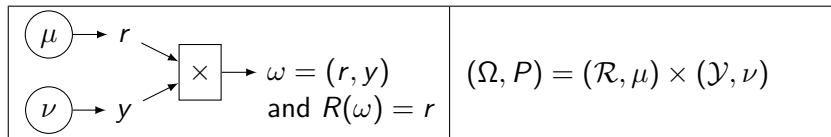
Decomposed electoral space

Particular case seen before

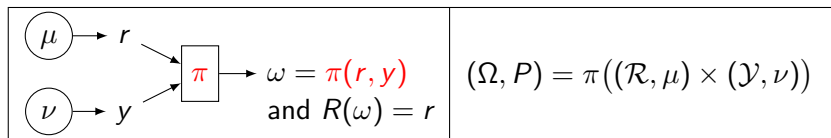


Decomposed electoral space

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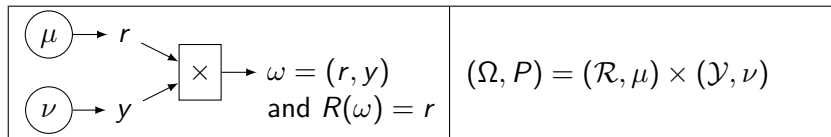


General case

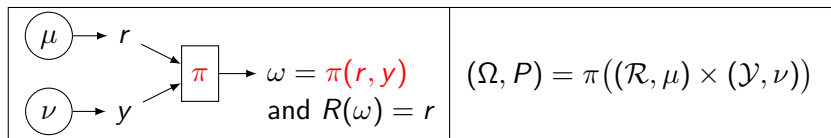


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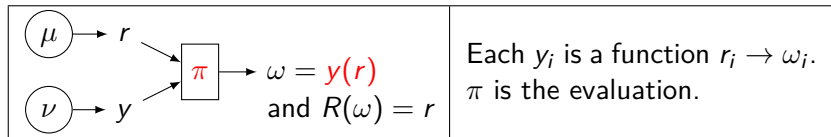
Particular case seen before



General case



Simpler (but equivalent) general case



Example of decomposed electoral space

$n = 2$ electors, $m = 2$ candidates.

μ draws equiprobably:

1. Each elector has binary relation $A \succ B$,
2. Each elector has binary relation $B \succ A$.

ν always draws functions y_1 and y_2 that each does:

$$A \succ B \rightarrow \mathcal{A} = (A \succ B, \text{orange})$$

$$B \succ A \rightarrow \mathcal{B} = (B \succ A, \text{blue}).$$

Then $P = \pi(\mu \times \nu)$ draws equiprobably:

1. Each elector is in state $\mathcal{A} = (A \succ B, \text{orange})$,
2. Each elector is in state $\mathcal{B} = (B \succ A, \text{blue})$.

Example of R -decomposable electoral space

$n = 2$ electors, $m = 2$ candidates.

P draws equiprobably:

1. Each elector is in state $\mathcal{A} = (A \succ B, \text{orange})$,
2. Each elector is in state $\mathcal{B} = (B \succ A, \text{blue})$.

Then:

- ▶ μ (the law of R) is like before,
- ▶ we can exhibit ν like before.

We say that space (Ω, P) is R -**decomposable**.

Definition of R -decomposable electoral space

What is given:

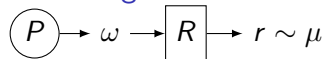
- ▶ $\omega = (\omega_1, \dots, \omega_n) \in \Omega \sim P$
- ▶ $R(\omega) = (r_1, \dots, r_n) \in \mathcal{R} \sim \mu$ (law induced by P)

We want a probability measure ν that draws n functions y_i such that:

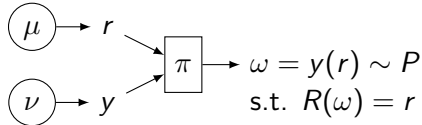
$$\left\{ \begin{array}{l} P = \pi(\mu \times \nu), \text{ where } \pi \text{ is the evaluation,} \\ (\forall r \in R(\Omega), R(y(r)) = r), \quad \nu\text{-almost surely for } y. \end{array} \right.$$

One elector: lemma of complementary random variable

What is given



What we want



Lemma

- ▶ (Ω, P) a probability space.
- ▶ R a random variable with values in a measurable space \mathcal{R} .

Assumption: \mathcal{R} is **finite** (and endowed with discrete σ -algebra).
Then (Ω, P) is **R -decomposable**.

Sketch of proof

Independently for each possible value r , we choose $y(r)$ according to P_r (conditional probability knowing r).

Several independent electors

Proposition

If electors are **independent**, then the electoral space is **R-decomposable**.

Sketch of proof

Apply lemma of complementary random variable to each elector.

Consequence

Slicing works: for any voting system f , there exists a sliced voting system f_y that is at most as manipulable as f .

Other criteria of decomposability

Independence is not a necessary condition.

Cf. example with orange and blue electors.

- ▶ We know other sufficient conditions.
- ▶ We also know a necessary condition.
- ▶ But we know no simple equivalent condition for the R -decomposability of an electoral space.

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Existence of an optimal voting system

P : probability measure used to draw population preferences (with reasonable properties = decomposability).

When looking for a voting system whose **manipulation rate is minimal** (among systems with reasonable properties), we can restrict the research to the class of those that:

- ▶ **depend on binary relations of preference only,**
- ▶ **respect Condorcet criterion.**

For each pair (n, m) , there is a finite number of such voting systems.

- ▶ **An optimal voting system exists.**

Future work: know more about optimal voting systems

For each pair (n, m) , number of voting systems that depend on binary relations of preference only and respect Condorcet criterion:

$$\sim m \left(\left(2^{\binom{m}{2}} \right)^n \right).$$

For the moment, we can give an optimal voting system explicitly for **very small** values: $n \leq 5$ electors and $m \leq 4$ candidates...

Conclusion

- ▶ For voting systems that rely on binary relations of preferences only, there is no canonical way to choose the winner (Arrow's theorem).
- ▶ For $m \geq 3$ candidates, all non-dictatorial voting systems are subject to manipulation (Gibbard's theorem).
- ▶ We can limit manipulability by **condorcification** and **slicing**.
- ▶ There exists an **optimal voting system** that depends on binary relations of preferences only and respects Condorcet criterion.

Thanks for your attention! Questions?



Why would manipulability be a problem?

If electors do not vote sincerely, the collective decision relies on **false information**.

If electors do vote sincerely, they may be frustrated and find the system nonsensical, since a non-sincere ballot, **misrepresenting** their preferences, would have **defended these preferences better**.



Restriction to sincere strategies (*reduction*)

Two-round system:

- ▶ Round 1: Fabien votes for A.
- ▶ Round 2, A versus B: Fabien votes for B.

Obviously, Fabien is not sincere!

Solution:

- ▶ do only one round,
- ▶ ask preferences directly,
- ▶ determine the corresponding sincere strategy automatically.

= ***reduced voting system***

People may still lie about their preferences. But they can no more use strategies that are obviously insincere!

Manipulability: an example

Voting system: plurality.

	Electors		
	40	35	25
Preferences	A	B	C
	B	C	A
	C	A	B
Sincere ballot	A	B	C

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We say that this situation is **manipulable** for this voting system:

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