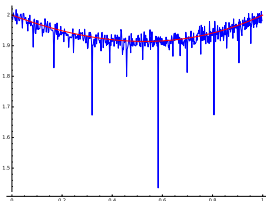


Random Number Generation and Fitting Interval Partitions

Pablo Rotondo¹



AleaEnAmSud,
Caen, 6 June, 2017.

¹IRIF, Paris 7 Diderot. Universidad de la República, Uruguay. GREYC, associate

Random Variable Simulation

Objective: given a perfect source of *independent fair bits*

$$\mathcal{X} = X_1, X_2, \dots$$

simulate a random variable Y with a *prescribed distribution*.

- Generating random bits \rightarrow **costly**.
- What if X_i were not random bits? \rightarrow **other distributions**.

Classical algorithm in probability courses

- given uniform $U \in [0, 1]$ and a continuous distribution function F consider the so called **inverse method**

$$Y := F^{-1}(U).$$

- in **our context** we may consider

$$U := (0.X_1X_2\dots)_2.$$

Interval algorithm: intro

Discrete random variable $Y \in \mathbb{Z}_{>0}$ with distribution vector p_1, p_2, \dots

The inverse method gives intervals

$$I_i(\mathbf{p}) := \left[\sum_{j < i} p_j, \sum_{j \leq i} p_j \right),$$

and defines

$$Y = i \iff U \in I_i(\mathbf{p}).$$

Question

How many fair bits X_1, X_2, \dots do we need to determine Y ?

Interval algorithm: intro

Discrete random variable $Y \in \mathbb{Z}_{>0}$ with distribution vector p_1, p_2, \dots

The inverse method gives intervals

$$I_i(\mathbf{p}) := \left[\sum_{j < i} p_j, \sum_{j \leq i} p_j \right),$$

and defines

$$Y = i \iff U \in I_i(\mathbf{p}).$$

Question

How many fair bits X_1, X_2, \dots do we need to determine Y ?

More precisely, given $u \in [0, 1]$ in binary $u = (0.x_1x_2\dots)_2$ we define

$$k_{\mathbf{p}}(u) := \inf \left\{ k \geq 0 : \exists i \text{ s.t. } (0.x_1 \dots x_k, 0.x_1 \dots x_k + 2^{-k}) \subset I_i(\mathbf{p}) \right\}$$

Interval algorithm: intro

Discrete random variable $Y \in \mathbb{Z}_{>0}$ with distribution vector p_1, p_2, \dots

The inverse method gives intervals

$$I_i(\mathbf{p}) := \left[\sum_{j < i} p_j, \sum_{j \leq i} p_j \right),$$

and defines

$$Y = i \iff U \in I_i(\mathbf{p}).$$

Question

How many fair bits X_1, X_2, \dots do we need to determine Y ?

More precisely, given $u \in [0, 1]$ in binary $u = (0.x_1x_2\dots)_2$ we define

$$k_{\mathbf{p}}(u) := \inf \left\{ k \geq 0 : \exists i \text{ s.t. } (0.x_1\dots x_k, 0.x_1\dots x_k + 2^{-k}) \subset I_i(\mathbf{p}) \right\}$$

What is

$$\mathbb{E}[k_{\mathbf{p}}(U)] \quad ?$$

Lower bound: the entropy

Theorem

The expected number of bits is bounded from below by the entropy of \mathbf{p}

$$\mathbb{E}[k_{\mathbf{p}}(U)] \geq H(Y),$$

where $H(Y) := \sum_i p_i \log_2(1/p_i)$.

Lower bound: the entropy

Theorem

The expected number of bits is bounded from below by the entropy of \mathbf{p}

$$\mathbb{E}[k_{\mathbf{p}}(U)] \geq H(Y),$$

where $H(Y) := \sum_i p_i \log_2(1/p_i)$.

Proof.

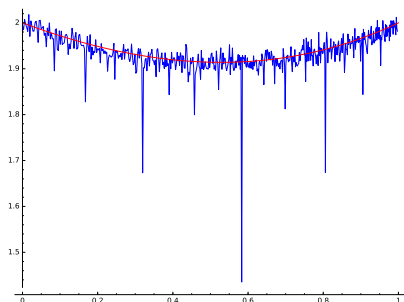
The code

$$\mathcal{C} := \left\{ x_1 \dots x_k \in \{0, 1\}^+ : \right. \\ \left. \begin{array}{l} \exists i \text{ s.t. } (0.x_1 \dots x_k, 0.x_1 \dots x_k + 2^{-k}) \subset I_i(\mathbf{p}), \\ \forall j (0.x_1 \dots x_{k-1}, 0.x_1 \dots x_{k-1} + 2^{-(k-1)}) \subset I_j \end{array} \right\}$$

is prefix free and determines Y .



The distribution $\mathbf{p}_N := (1/N, 1/N \dots, 1/N)$



Theorem

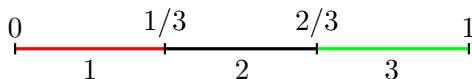
The redundancy $\mathbb{E}[k_{\mathbf{p}_N}(U)] - H(Y)$ equals

$$R(x) = 2^x - x + 1 - \frac{2^{\nu(N)} - 1}{N - 1} 2^x - \log_2 \left(1 + \frac{1}{N-1} \right),$$

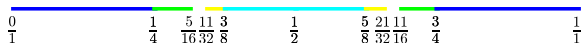
where $x = \{\log_2(N - 1)\}$, $\{\cdot\}$ denotes the fractional part and $\nu(N)$ is the greatest t such that 2^t divides N .

Example: fair 3-sided dice

First $\mathbf{p}_3 = (1/3, 1/3, 1/3)$ divides the interval $[0, 1]$ as follows



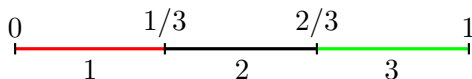
while the subdivision procedure, a binary search for U , gives



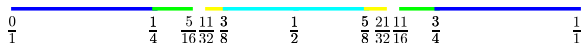
where we remark that the number of bits can be deduced from the denominators.

Example: fair 3-sided dice

First $\mathbf{p}_3 = (1/3, 1/3, 1/3)$ divides the interval $[0, 1]$ as follows



while the subdivision procedure, a binary search for U , gives



where we remark that the number of bits can be deduced from the denominators.

In this case we have

$$\mathbb{E}[k_{\mathbf{p}_3}(U)] = 3 \doteq \log_2(3) + 1.41503\dots$$

Generic Distribution

For an arbitrary probability vector $\mathbf{p} = (p_1, p_2, \dots)$

Theorem

The redundancy $\mathbb{E}[k_{\mathbf{p}}(U)] - H(Y)$ is at most 2, i.e.

$$H(Y) \leq \mathbb{E}[k_{\mathbf{p}}(U)] \leq H(Y) + 2.$$

Furthermore, the +2 is tight by our example \mathbf{p}_N .

Generic Distribution

For an arbitrary probability vector $\mathbf{p} = (p_1, p_2, \dots)$

Theorem

The redundancy $\mathbb{E}[k_{\mathbf{p}}(U)] - H(Y)$ is at most 2, i.e.

$$H(Y) \leq \mathbb{E}[k_{\mathbf{p}}(U)] \leq H(Y) + 2.$$

Furthermore, the +2 is tight by our example \mathbf{p}_N .

Knuth-Yao proved that the **optimal algorithm** satisfies these **bounds**.

- ▶ Algorithm seen as **binary tree**.
- ▶ Optimal algorithm obtained by decomposing each

$$p_i = (0.p_1^{(i)} p_2^{(i)} \dots)_2$$

in binary and assigning a leaf of probability $p_j^{(i)}$ for each (i, j) .

Example: continued fractions

Procedures gives way to, given the **binary representation** of U , decide to which **interval** among the **partition**

$$[0, p_1), [p_1, p_1 + p_2), [p_1 + p_2, p_1 + p_2 + p_3), \dots$$

it belongs to. This can be applied to **other partitions**.

Example: continued fractions

Procedures gives way to, given the **binary representation** of U , decide to which **interval** among the **partition**

$$[0, p_1), [p_1, p_1 + p_2), [p_1 + p_2, p_1 + p_2 + p_3), \dots$$

it belongs to. This can be applied to **other partitions**.

For example, if we consider the **convergents** $(q_k)_k$ of U , the set

$$I_k(a, b) := \{U \in [0, 1] : (q_{k-1}(U), q_k(U)) = (a, b)\}$$

is an interval of length $\frac{1}{b(a+b)}$ when $\gcd(a, b) = 1$ and $a \leq b$.

Example: continued fractions

Procedures gives way to, given the **binary representation** of U , decide to which **interval** among the **partition**

$$[0, p_1), [p_1, p_1 + p_2), [p_1 + p_2, p_1 + p_2 + p_3), \dots$$

it belongs to. This can be applied to **other partitions**.

For example, if we consider the **convergents** $(q_k)_k$ of U , the set

$$I_k(a, b) := \{U \in [0, 1] : (q_{k-1}(U), q_k(U)) = (a, b)\}$$

is an interval of length $\frac{1}{b(a+b)}$ when $\gcd(a, b) = 1$ and $a \leq b$.

A possible **partition** (negligible intersection) is given by fixing k

$$\mathcal{I}_k := \{I_k(a, b) : \gcd(a, b) = 1, 1 \leq a \leq b\},$$

which **determines the value** of $(q_{k-1}(U), q_k(U))$.

Example: continued fractions

A different **partition**, relating to our ANALCO paper is:

- ▶ Fix $n \in \mathbb{Z}_{>0}$, and consider

$$\mathbb{I}_n := \{(a, b) \in \mathbb{Z}_{>0} \times \mathbb{Z}_{>0} : \gcd(a, b) = 1, a \leq n < b\}.$$

Example: continued fractions

A different **partition**, relating to our ANALCO paper is:

- ▶ Fix $n \in \mathbb{Z}_{>0}$, and consider

$$\mathbb{I}_n := \{(a, b) \in \mathbb{Z}_{>0} \times \mathbb{Z}_{>0} : \gcd(a, b) = 1, a \leq n < b\}.$$

- ▶ Consider $k := k(U, n)$ such that $q_{k-1}(U) \leq n < q_k(U)$ and define

$$I_{a,b} := \{U \in [0, 1] : (q_{k(U,n)-1}, q_{k(U,n)}) = (a, b)\},$$

where $(a, b) \in \mathbb{I}_n$, again an **interval**, forming a **partition**.

Example: continued fractions

A different **partition**, relating to our ANALCO paper is:

- ▶ Fix $n \in \mathbb{Z}_{>0}$, and consider

$$\mathbb{I}_n := \{(a, b) \in \mathbb{Z}_{>0} \times \mathbb{Z}_{>0} : \gcd(a, b) = 1, a \leq n < b\}.$$

- ▶ Consider $k := k(U, n)$ such that $q_{k-1}(U) \leq n < q_k(U)$ and define

$$I_{a,b} := \{U \in [0, 1] : (q_{k(U,n)-1}, q_{k(U,n)}) = (a, b)\},$$

where $(a, b) \in \mathbb{I}_n$, again an **interval**, forming a **partition**.

- ▶ Then the number of **bits needed** to determine

$$(q_{k(U,n)-1}, q_{k(U,n)}),$$

is roughly

$$\begin{aligned} H(q_{k(U,n)-1}, q_{k(U,n)}) &= 2 \log_2 n + 1 \\ &\quad - \frac{12}{\pi^2} \iint_{0 < x < 1 \leq y} \frac{\log_2(y(x+y))}{y(x+y)} dx dy + o(1) \\ &= 2 \log_2 n - 2.4263 \dots + o(1) \end{aligned}$$

Interval Algorithm

- ▶ **Generalization** of the previous procedure for **fair bits**

$$\mathcal{X} = (X_1, X_2, \dots).$$

- ▶ Each X_i takes values on $[M]$ with vector (q_1, q_2, \dots, q_M) .

Interval Algorithm

- ▶ **Generalization** of the previous procedure for **fair bits**

$$\mathcal{X} = (X_1, X_2, \dots).$$

- ▶ Each X_i takes values on $[M]$ with vector (q_1, q_2, \dots, q_M) .

Now the **procedure** goes as follows:

⊗ Let $K_k(\mathbf{q}) = [A_k, B_k)$ be our **working interval** after processing X_1, \dots, X_k .

⊗ **Partition** $K_k(\mathbf{q})$ into **intervals**

$$K_{k,j}(\mathbf{q}) := [A_k + Q_{j-1}(B_k - A_k), A_k + Q_j(B_k - A_k)),$$

according to $Q_j(\mathbf{q}) := \sum_{i \leq j} q_i$.

⊗ Suppose $X_{k+1}(\mathbf{q}) = j$, then set $K_{k+1}(\mathbf{q}) := K_{k,j}(\mathbf{q})$.

Interval $K_k(\mathbf{q})$ corresponds to what before was

$$[0.x_1 \dots x_k, 0.x_1 \dots x_k + 2^{-k}).$$

We continue until

$$k_{\mathbf{q}, \mathbf{p}} := \inf \left\{ k \geq 0 : \exists i \text{ s.t. } K_k(\mathbf{q}) \subset I_i(\mathbf{p}) \right\},$$

in which case we return $Y = i$ if $K_k(\mathbf{q}) \subset I_i(\mathbf{p})$

Interval $K_k(\mathbf{q})$ corresponds to what before was

$$[0.x_1 \dots x_k, 0.x_1 \dots x_k + 2^{-k}).$$

We continue until

$$k_{\mathbf{q},\mathbf{p}} := \inf \left\{ k \geq 0 : \exists i \text{ s.t. } K_k(\mathbf{q}) \subset I_i(\mathbf{p}) \right\},$$

in which case we return $Y = i$ if $K_k(\mathbf{q}) \subset I_i(\mathbf{p})$

Theorem (Lower bound)

The cost of simulating the random variable Y having prob. vector \mathbf{p} by using the Interval Algorithm with an M -valued “coin flips” according to the prob. vector \mathbf{q} is bounded from below by

$$\frac{H(\mathbf{p})}{H(\mathbf{q})} \leq \mathbb{E}[k_{\mathbf{q},\mathbf{p}}].$$

Interval Algorithm: efficiency

Theorem (Han,Hoshi 95)

For any probability vectors $\mathbf{p} = (p_1, \dots, p_n)$ and $\mathbf{q} = (q_1, \dots, q_m)$, the expected number of coin tosses in the interval algorithm is upper-bounded

$$\mathbb{E}[k_{\mathbf{q},\mathbf{p}}] \leq \frac{H(\mathbf{p})}{H(\mathbf{q})} + \frac{\log 2(M-1)}{H(\mathbf{q})} + \frac{h(q_{\max})}{(1-q_{\max})H(\mathbf{q})}.$$

Proof.

Whiteboard (or blackboard).



Generalization to random processes

We want to simulate a **random process**

$$\mathcal{Y} = (Y_1, Y_2, Y_3, \dots),$$

rather than a **single** Y with a prescribed distribution.

The question now is

what is the **asymptotic** cost of producing $\mathcal{Y}_n = (Y_1, Y_2, \dots, Y_n)$?

Generalization to random processes

We want to simulate a **random process**

$$\mathcal{Y} = (Y_1, Y_2, Y_3, \dots),$$

rather than a **single** Y with a prescribed distribution.

The question now is

what is the **asymptotic** cost of producing $\mathcal{Y}_n = (Y_1, Y_2, \dots, Y_n)$?

Remark

If the “target” source Y_1, Y_2, \dots is **stationary**, \mathbf{p}^n denotes the vector of $(Y_{j+1}, \dots, Y_{j+n})$ for $j \geq 0$ and $k_n := k_{\mathbf{q}, \mathbf{p}^n}$:

$$\lim_{n \rightarrow \infty} \frac{\mathbb{E}[k_n]}{n} = \frac{H(\mathcal{Y})}{H(\mathcal{X})}$$

Generalization to random processes

We want to simulate a **random process**

$$\mathcal{Y} = (Y_1, Y_2, Y_3, \dots),$$

rather than a **single** Y with a prescribed distribution.

The question now is

what is the **asymptotic** cost of producing $\mathcal{Y}_n = (Y_1, Y_2, \dots, Y_n)$?

Remark

If the “target” source Y_1, Y_2, \dots is **stationary**, \mathbf{p}^n denotes the vector of $(Y_{j+1}, \dots, Y_{j+n})$ for $j \geq 0$ and $k_n := k_{\mathbf{q}, \mathbf{p}^n}$:

$$\lim_{n \rightarrow \infty} \frac{\mathbb{E}[k_n]}{n} = \frac{H(\mathcal{Y})}{H(\mathcal{X})}$$

Proof.

By independence $H(\mathcal{X}) = H(\mathbf{q})$, while $H(\mathcal{Y}_n)/n \rightarrow H(\mathcal{Y})$. □

Generalization

- ▶ We may imagine now that the variables X_1, X_2, \dots are not necessarily independent or identically distributed
→ natural if produced by a dynamical system (e.g. Euclid).
- ▶ The question can be framed more purely in terms of sequences of interval partitions.

Generalization

- ▶ We may imagine now that the variables X_1, X_2, \dots are not necessarily independent or identically distributed
→ natural if produced by a dynamical system (e.g. Euclid).
- ▶ The question can be framed more purely in terms of sequences of interval partitions.

Definition (Interval partition)

An interval partition is a finite or countable partition of $[0, 1]$ into intervals. If \mathcal{P} is an interval partition and $x \in [0, 1]$, we let $\mathcal{P}(x)$ denote the interval $I \in \mathcal{P}$ such that $x \in I$.

Generalization

- ▶ We may imagine now that the variables X_1, X_2, \dots are not necessarily independent or identically distributed
→ natural if produced by a dynamical system (e.g. Euclid).
- ▶ The question can be framed more purely in terms of sequences of interval partitions.

Definition (Interval partition)

An interval partition is a finite or countable partition of $[0, 1]$ into intervals. If \mathcal{P} is an interval partition and $x \in [0, 1]$, we let $\mathcal{P}(x)$ denote the interval $I \in \mathcal{P}$ such that $x \in I$.

Now our problem is rephrased in terms of

$$k_{\mathcal{Q}, \mathcal{P}}(n, x) = \inf \{k \geq 0 : \mathcal{Q}_k(x) \subset \mathcal{P}_n(x)\};$$

Generalization

- ▶ We may imagine now that the variables X_1, X_2, \dots are not necessarily independent or identically distributed
→ natural if produced by a dynamical system (e.g. Euclid).
- ▶ The question can be framed more purely in terms of sequences of interval partitions.

Definition (Interval partition)

An interval partition is a finite or countable partition of $[0, 1]$ into intervals. If \mathcal{P} is an interval partition and $x \in [0, 1]$, we let $\mathcal{P}(x)$ denote the interval $I \in \mathcal{P}$ such that $x \in I$.

Now our problem is rephrased in terms of

$$k_{\mathcal{Q}, \mathcal{P}}(n, x) = \inf \{k \geq 0 : \mathcal{Q}_k(x) \subset \mathcal{P}_n(x)\};$$

compare it with $k_{\mathbf{q}, \mathbf{p}^n}$:

- ▶ \mathcal{P}_n corresponds to the partition according to (Y_1, \dots, Y_n) .
- ▶ \mathcal{Q}_k corresponds to the partition according to (X_1, \dots, X_k) .

Entropy of an interval partition

Definition (Entropy)

Let $\mathcal{P} := (\mathcal{P}_n)_{n=1}^{\infty}$ be a **sequence of interval partitions**. We say that \mathcal{P} has *entropy* $c \geq 0$ with respect to a measure λ if

$$\lim_{n \rightarrow \infty} -\frac{1}{n} \log \lambda(\mathcal{P}_n(x)) = c, \quad \lambda - a.e.$$

Entropy of an interval partition

Definition (Entropy)

Let $\mathcal{P} := (\mathcal{P}_n)_{n=1}^{\infty}$ be a **sequence of interval partitions**. We say that \mathcal{P} has *entropy* $c \geq 0$ with respect to a measure λ if

$$\lim_{n \rightarrow \infty} -\frac{1}{n} \log \lambda(\mathcal{P}_n(x)) = c, \quad \lambda - a.e.$$

Let λ be the Lebesgue measure:

- ▶ For $\mathcal{Q}_k = \left\{ \left[\frac{i}{2^k}, \frac{i+1}{2^k} \right) : i = 0, \dots, 2^k - 1 \right\}$ we get

$$-\frac{1}{k} \log \lambda(\mathcal{Q}_k(x)) = \log 2, \forall k \geq 1.$$

Entropy of an interval partition

Definition (Entropy)

Let $\mathcal{P} := (\mathcal{P}_n)_{n=1}^{\infty}$ be a **sequence of interval partitions**. We say that \mathcal{P} has *entropy* $c \geq 0$ with respect to a measure λ if

$$\lim_{n \rightarrow \infty} -\frac{1}{n} \log \lambda(\mathcal{P}_n(x)) = c, \quad \lambda - a.e.$$

Let λ be the Lebesgue measure:

- ▶ For $\mathcal{Q}_k = \left\{ \left[\frac{i}{2^k}, \frac{i+1}{2^k} \right) : i = 0, \dots, 2^k - 1 \right\}$ we get

$$-\frac{1}{k} \log \lambda(\mathcal{Q}_k(x)) = \log 2, \quad \forall k \geq 1.$$

- ▶ For $\mathcal{P}_n = \{I_n(a, b) : \gcd(a, b) = 1, 1 \leq a \leq b\}$, where

$$I_n(a, b) = \{x \in [0, 1] : (q_{n-1}(x), q_n(x)) = (a, b)\},$$

we get (blackboard explanation)

$$\lim_{n \rightarrow \infty} -\frac{1}{n} \log \lambda(\mathcal{P}_n(x)) = \frac{\pi^2}{6 \log 2}, \quad \lambda - a.e.$$

Asymptotic Cost

Theorem (Dajani, Fieldsteel, 2001)

Let $\mathcal{P} := \{\mathcal{P}_n\}_{n=1}^{\infty}$ and $\mathcal{Q} := \{\mathcal{Q}_n\}_{n=1}^{\infty}$ be sequences of interval partitions, and let λ be a Borel probability measure on $[0, 1)$.

Assume \mathcal{P} and \mathcal{Q} have entropies $H(\mathcal{P})$ and $H(\mathcal{Q})$ respectively with respect to λ , then

$$\lim_{n \rightarrow \infty} \frac{1}{n} k_{\mathcal{Q}, \mathcal{P}}(n, x) = \frac{H(\mathcal{P})}{H(\mathcal{Q})}$$

for λ -a.e. x .

Asymptotic Cost

Theorem (Dajani, Fieldsteel, 2001)

Let $\mathcal{P} := \{\mathcal{P}_n\}_{n=1}^{\infty}$ and $\mathcal{Q} := \{\mathcal{Q}_n\}_{n=1}^{\infty}$ be sequences of interval partitions, and let λ be a Borel probability measure on $[0, 1)$.

Assume \mathcal{P} and \mathcal{Q} have entropies $H(\mathcal{P})$ and $H(\mathcal{Q})$ respectively with respect to λ , then

$$\lim_{n \rightarrow \infty} \frac{1}{n} k_{\mathcal{Q}, \mathcal{P}}(n, x) = \frac{H(\mathcal{P})}{H(\mathcal{Q})}$$

for λ -a.e. x .

Example: the number of digits required to determine $(q_{n-1}(x), q_n(x))$ from the base 10 expansion of x behaves like $\frac{\pi^2}{6 \log 2 \log 10} n$ a.e. x , a result previously proved by Lochs.

Good partition sequences

Theorem (Shannon,McMillan,Breiman)

Let T be an ergodic measure preserving transformation on a probability space $(\Omega, \mathcal{B}, \mu)$ and let P be a finite or countable generating partition for T for which $H_\mu(P) < \infty$. Then for μ -a.e. x ,

$$\lim_{n \rightarrow \infty} -\frac{\log \mu(P_n(x))}{n} = h_\mu(T).$$

Here $H_\mu(P)$ denotes the entropy of the partition P , $h_\mu(T)$ the entropy of T and $P_n(x)$ denotes the element of the partition $\bigvee_{i=0}^{n-1} T^{-i}P$ containing x .

Good partition sequences

Theorem (Shannon, McMillan, Breiman)

Let T be an ergodic measure preserving transformation on a probability space $(\Omega, \mathcal{B}, \mu)$ and let P be a finite or countable generating partition for T for which $H_\mu(P) < \infty$. Then for μ -a.e. x ,

$$\lim_{n \rightarrow \infty} -\frac{\log \mu(P_n(x))}{n} = h_\mu(T).$$

Here $H_\mu(P)$ denotes the entropy of the partition P , $h_\mu(T)$ the entropy of T and $P_n(x)$ denotes the element of the partition $\bigvee_{i=0}^{n-1} T^{-i}P$ containing x .

We recall that

$$h_\mu(T) = \sup\{h_\mu(T, \mathcal{A}) : \mathcal{A} \text{ countable partition of } X\},$$

and

$$h_\mu(T, \mathcal{A}) = \lim_{n \rightarrow \infty} \frac{1}{n} H(\mathcal{A}(U), \mathcal{A}(TU), \dots, \mathcal{A}(T^{n-1}U)),$$

where U is distributed according to μ .

Concluding remarks

There are other interesting results/ideas not mentioned in this talk,

- ▶ The [optimal algorithm for discrete uniform generation from coin flips](#) has a fairly simple implementation, see the note by Jérémie Lumbroso [arXiv:1304.1916v1](#).

Concluding remarks

There are other interesting results/ideas not mentioned in this talk,






- ▶ The **optimal algorithm for discrete uniform generation from coin flips** has a fairly simple implementation, see the note by Jérémie Lumbroso [arXiv:1304.1916v1](https://arxiv.org/abs/1304.1916v1).
- ▶ The **generalisation** of Bosma-Dajani-Kraaikamp of the cost of **passing from base 10 to the Continued Fraction Expansion**. One considers appropriate maps T and S called “number-theoretic fibered maps” associated with digits and get a limiting result with the quotient of $h(T)$ and $h(S)$.

Concluding remarks

There are other interesting results/ideas not mentioned in this talk,

- ▶ The **optimal algorithm for discrete uniform generation from coin flips** has a fairly simple implementation, see the note by Jérémie Lumbroso [arXiv:1304.1916v1](https://arxiv.org/abs/1304.1916v1).
- ▶ The **generalisation** of Bosma-Dajani-Kraaikamp of the cost of **passing from base 10 to the Continued Fraction Expansion**. One considers appropriate maps T and S called “number-theoretic fibered maps” associated with digits and get a limiting result with the quotient of $h(T)$ and $h(S)$.
- ▶ What about **non-discrete random variables**? See the original paper by von Neumann, Knuth-Yao and Philippe Duchon.

References

-  L. Devroye,
Non-Uniform Random Variate Generation,
Springer-Verlag, New York 1986.
-  T. Cover, J. Thomas
Elements of Information Theory,
Wiley Series in Telecommunications and Signal Processing, Second
Edition, 2006 .
-  D. Knuth and A. Yao,
The complexity of nonuniform random number generation,
Algorithms and Complexity, New Directions and Recent Results, pp.
357–428, 1976.
-  T. S. Han, and M. Hoshi,
Interval Algorithm for Random Number Generation,
IEEE Transactions on Information Theory, 32 (2), pp. 599-611,
March 1997.
-  K. Dajani, and A. Fieldsteel,
Equipartition of Interval Partitions and an Application to Number
Theory,
Proceedings of the American Mathematical Society, vol 129, n. 12,
pp. 3453–3460, 2001.