

Stable and measurable functions on positive cones

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Thomas Ehrhard, IRIF, CNRS and Univ Paris Diderot

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Joint work with Michele Pagani and Christine Tasson.

General goal: Extend the Probabilist Coherence Space (PCS) denotational semantics to “continuous data-types” such as the real line.

↪ models of functional “programming languages” computing probability distributions, real PCF.

PCS duality

Let I be a finite or countable set.

If $u, u' \in (\mathbb{R}^+)^I$, set

$$\langle u, u' \rangle = \sum_{i \in I} u_i u'_i \in \overline{\mathbb{R}^+}$$

and if $\mathcal{F} \subseteq (\mathbb{R}^+)^I$ then

$$\mathcal{F}^\perp = \{u' \in (\mathbb{R}^+)^I \mid \forall u \in \mathcal{F} \langle u, u' \rangle \leq 1\}.$$

PCS: $X = (|X|, PX)$ where $|X|$ countable and $PX \subseteq (\mathbb{R}^+)^{|X|}$ such that $PX = PX^{\perp\perp}$.

Equivalently: PX is downwards-closed (for the product order), convex and directed-complete.

Additional conditions to avoid ∞ coefficients:

- $\forall a \in |X| \exists x \in PX \ x_a \neq 0$
- $\forall a \in |X| \{x_a \mid x \in PX\}$ bounded

Examples:

- 1 with $|1| = \{*\}$ (singleton) and $P1 = \{(0, \alpha) \mid \alpha \in [0, 1]\} = [0, 1]$.
- \mathbb{N} with $|\mathbb{N}| = \mathbb{N}$ and $u \in (\mathbb{R}^+)^{\mathbb{N}} \in \text{PN}$ if $\sum_{i=0}^{\infty} u_i \leq 1$.
Sub-probability distributions on \mathbb{N} .
- \mathbb{N}^\perp with $\mathbb{N}^\perp = \mathbb{N}$ and $u' \in (\mathbb{R}^+)^{\mathbb{N}} \in \text{PN}^\perp$ if $\forall i \in \mathbb{N} u'_i \in [0, 1]$.
These are not at all probability distributions!

Standard ℓ_1/ℓ_∞ duality in Banach spaces.

Linear morphisms

In the category of PCS's, a morphism from X to Y is an element of $P(X \multimap Y)$ where $X \multimap Y$ is the PCS given by

- $|X \multimap Y| = |X| \times |Y|$
- given $s \in (\mathbb{R}^+)^{|X| \times |Y|}$, one has $s \in P(X \multimap Y)$ if

$$\forall u \in PX \quad s u = \left(\sum_{a \in |X|} s_{a,b} u_a \right)_{[b \in |Y|]} \in PY$$

that is

$$\forall u \in PX \forall v' \in PY^\perp \quad \sum_{a \in |X|, b \in |Y|} s_{a,b} u_a v'_b \leq 1$$

Example: a morphism from \mathbb{N} to \mathbb{N} (element of $\mathcal{P}(\mathbb{N} \multimap \mathbb{N})$) is a sub-stochastic matrix indexed by $\mathbb{N} \times \mathbb{N}$.

Just as ordinary coherence spaces, PCS, with these linear morphisms

- are a model of full classical LL
- with fixpoints (hence a model of PCF etc)
- with fixpoints of types (hence contain various models of the pure lambda-calculus, of FPC, of CBPV with recursive types etc)
- 2nd order LL, polymorphism? (never explored)

All these languages extended with probabilistic primitives, for instance: random integers in a given range, (fair) coin etc.

Examples of type constructions:

- $|1| = \{*\}$, $P1 = [0, 1]$
- $|X \& Y| = |X| + |Y|$ and
 $P(X \& Y) = \{x \oplus y \mid x \in PX \text{ and } y \in PY\} \simeq PX \times PY$
- $|X \oplus Y| = |X| + |Y|$ and
 $P(X \oplus Y) = \{px \oplus (1-p)y \mid x \in PX, y \in PY \text{ and } p \in [0, 1]\}$

So $|1 \oplus 1| = \{\mathbf{t}, \mathbf{f}\}$ and

$$P(1 \oplus 1) = \{pt + qf \mid p, q \in \mathbb{R}^+, p + q \leq 1\}$$

$N = 1 \oplus N$ (“least” fixpoint) so that $|N| = \mathbb{N}$ and PN is the set of sub-probability distributions on \mathbb{N} .

Similarly one defines probabilistic types of lists, trees, streams etc.

Morphisms in the CCC of PCS

By standard LL/categorical considerations we know that we have a CCC: the “Kleisli category” of the “!” comonad that we have not described.

One defines $X \Rightarrow Y$ by

- $|X \Rightarrow Y| = \mathcal{M}_{\text{fin}}(|X|) \times |Y|$
- If $u \in (\mathbb{R}^+)^{|X|}$ and $m \in \mathcal{M}_{\text{fin}}(|X|)$, set $u^m = \prod_{a \in |X|} u_a^{m(a)}$
- Then $t \in (\mathbb{R}^+)^{|X \Rightarrow Y|}$ is in $P(X \Rightarrow Y)$ if for all $u \in PX$,

$$\hat{t}(u) = \left(\sum_{m \in \mathcal{M}_{\text{fin}}(|X|)} t_{m,b} u^m \right)_{b \in |Y|} \in PY$$

NB: such a t defines therefore a function $\hat{t} : PX \rightarrow PY$ and t is easily seen to be determined by this function ($\hat{s} = \hat{t} \Rightarrow s = t$).

These morphisms are closed under composition: this defines the CCC \mathbf{Pcoh}_1 . In other words, given $s \in P(X \Rightarrow Y)$ and $t \in P(Y \Rightarrow Z)$, there is $t \circ s \in P(X \Rightarrow Z)$ such that

$$\widehat{t \circ s} = \widehat{t} \circ \widehat{s}$$

and there is an $\text{Id} \in P(X \Rightarrow X)$, given by $\text{Id}_{[a],a} = 1$ and $\text{Id}_{m,a} = 0$ if $m \neq [a]$. Of course $\widehat{\text{Id}}(x) = x$.

- The cartesian product of X and Y is $X \& Y$.
- The object of morphisms from X to Y is $X \Rightarrow Y$.

PX is naturally ordered by: $x \leq y$ if $\forall a \in |X| x_a \leq y_a$. Then PX is directed-complete (it is actually an ω -continuous cpo).

For any $s \in P(X \Rightarrow Y)$, the function \hat{s} is Scott continuous, and hence we can interpret (e.g. PCF) fixpoint operators.

Example of morphisms in this CCC

A $s \in P(1 \Rightarrow 1)$ is a family $(s_n)_{n \in \mathbb{N}}$ of elements of \mathbb{R}^+ such that $\sum_{n=0}^{\infty} s_n \leq 1$, and the associated function is $\hat{s}: [0, 1] \rightarrow [0, 1]$ given by $\hat{s}(x) = \sum_{n=0}^{\infty} s_n x^n$.

Functions of this kind are

- very smooth (analytic)
- very monotonic (all derivatives are ≥ 0)

Example of such function $[0, 1] \rightarrow [0, 1]$: $f(x) = \frac{1}{3} + \frac{x^2}{2}$.

An example coming from a simple program

Consider $\vdash M : 1 \rightarrow 1$ given by the recursive definition

$$M x = \text{ifz}(\text{coin}_{1/2}, (), x; M x; M x)$$

where coin_p reduces to $\underline{0}$ with proba p and to $\underline{1}$ with proba $1 - p$, and “;” is the “unary conditional” ($P; Q \rightsquigarrow Q$ if $P \rightsquigarrow ()$).

Then M is represented by the least function $f : [0, 1] \rightarrow [0, 1]$ (in $P[1 \Rightarrow 1]$) such that $f(x) = \frac{1}{2} + \frac{1}{2}xf(x)^2$ so that

$$f(x) = \frac{1 - \sqrt{1 - x}}{x} \text{ if } x \neq 0 \text{ and } f(0) = \frac{1}{2}$$

NB: $f'(1) = \infty!$ Possible singularities on the border of PX .

Completely similar characterization of $s \in P((1 \& 1) \Rightarrow 1)$.

The “weak parallel or” $wpor : [0, 1]^2 \rightarrow [0, 1]$ defined by $wpor(x, y) = x + y - xy$ is not a morphism (there is a negative coefficient).

NB 1: adding such a morphism to the model is incompatible with the fact that all morphisms are analytic and the presence of least fixpoints. We would be able to define a function $f : [0, 1] \rightarrow [0, 1]$ by $f(x) = wpor(x, f(x)) = x + f(x) - xf(x)$ as a least fixpoint. But then $f(0) = 0$ and $f(x) = 1$ if $x > 0$ so f is not analytic.

NB 2: f is Scott continuous, but not continuous for the standard topology of \mathbb{R} .

A $s \in P((1 \oplus 1) \Rightarrow 1)$ is a family $(s_{n,m})_{n,m \in \mathbb{N}}$ such that

$$\forall p \in [0, 1] \quad \sum_{n,m \in \mathbb{N}} s_{n,m} p^n (1-p)^m \leq 1$$

For instance: $f : P(1 \oplus 1) \rightarrow [0, 1]$ given by $f(x) = 4x_t x_f$ is such a morphism because $p \in [0, 1] \Rightarrow p(1-p) \leq \frac{1}{4}$.

NB 1: this function is not definable in “PCF” (but the function $f(x) = 2x_t x_f$ is).

NB 2: we have no “parallel or” function in the model (requires negative coefficients), but we have an analogue of Gustave’s function $g \in P((1 \oplus 1) \& (1 \oplus 1) \& (1 \oplus 1) \Rightarrow 1)$ given by $g(x, y, z) = x_t y_f + y_t z_f + z_t x_f$. But $\frac{1}{2}g$ is definable whereas no $\varepsilon wpor$ (for $\varepsilon > 0$) is!

Main properties of this model

For probabilistic PCF (and its extensions with recursive types etc):

- Adequacy: if $\vdash M : \iota$, then the interpretation $[M]$ of M , which is an element of PN (ι is interpreted as the PCS \mathbb{N}) satisfies:
For all $n \in \mathbb{N}$, $[M]_n$ is the probability of M to reduce to \underline{n} .
- Equational full abstraction: semantical equality \Rightarrow observational equivalence (same probability to reduce to $\underline{0}$ in any context of ground type ι).

Inequational full abstraction fails for the standard order of the model: $x, y \in PX$ satisfy $x \leq y$ if $\forall a \in |X| x_a \leq y_a$.

Major limitation of PCS: no “continuous” types

Main limitation of this model: apparently, does not allow to interpret “continuous types” like the real line \mathbb{R} (very important for the semantics of Machine Learning oriented languages).

Idea to overcome it: our morphisms are functions acting on the cpos PX . Introduce more general such cpos and find a notion of morphisms generalizing those of PCS.

However, the Cantor space is (almost) here!

Let X be the PCS which is the “least solution” (there is a natural order relations on PCS such that all connectives of LL are Scott continuous wrt. this order) of

$$X = 1 \ \& \ (X \oplus X).$$

Then $|X| \simeq \{0, 1\}^*$.

NB: if $\theta \in \{0, 1\}^{\mathbb{N}}$ then $x \in (\mathbb{R}^+)^{|X|}$ given by

$$x_s = \begin{cases} 1 & \text{if } s \text{ prefix of } \theta \\ 0 & \text{otherwise} \end{cases}$$

is an element of PX : PX contains the Cantor space.

The elements x of PX such that

$$\forall s \in |X| \quad x_s = x_{s0} + x_{s1}$$

are exactly the sub-probability measures of the Cantor space with its standard Borelian σ -algebra.

$X = 1$ & $(N \otimes X)$ contains all sub-probability measures on Baire space.

We don't know how to do the same for $[0, 1]$, seems impossible.

Warning: $X = 1 \oplus (N \otimes X) \rightsquigarrow$ lists of integers with all sub-probability distributions; a much simpler PCS.

The cone generated by a PCS

Given a PCS X we can consider its associated “cone” $C(X)$: the set of all $x \in (\mathbb{R}^+)^{|X|}$ such that $\varepsilon x \in PX$ for some $\varepsilon > 0$. Then

- $C(X)$ is an \mathbb{R}^+ -semi module: if $x, y \in C(X)$ and $\alpha, \beta \in \mathbb{R}^+$ then $\alpha x + \beta y = (\alpha x_a + \beta y_a)_{a \in |X|} \in C(X)$ (with the usual algebraic properties).
- The canonical order relation can be defined by: $x \leq y$ if there is $z \in C(X)$ such that $y = x + z$.
- There is a “norm” $\| _ \| : C(X) \rightarrow \mathbb{R}^+$ defined by $\|x\| = \sup_{x' \in PX^\perp} \langle x, x' \rangle$ which satisfies $\|\alpha x\| = \alpha \|x\|$, $\|x + y\| \leq \|x\| + \|y\|$ and $x \leq y \Rightarrow \|x\| \leq \|y\|$.
- Any monotonic bounded sequence of elements of $C(X)$ has a least upper bound.

$C(X)$ is a kind of “order complete positive Banach space”.

Positive cone

We generalize this situation. A (Selinger) *cone* is an \mathbb{R}^+ -semi module P (there are operations $+$ and \mathbb{R}^+ scalar multiplication satisfying the usual laws) equipped with a function $\|_P : P \rightarrow \mathbb{R}^+$ such that:

- $x + y = x' + y \Rightarrow x = x'$ (simplifiability).
- $\|\alpha x\|_P = \alpha \|x\|_P$, $\|x + y\|_P \leq \|x\|_P + \|y\|_P$ and $\|x\|_P = 0 \Rightarrow x = 0$ ($\|_P$ is a norm).
- Defining $x \leq y$ by $\exists z y = x + z$, we have $\|x\|_P \leq \|y\|_P$ (monotonicity of the norm).
- Any sequence $(x_n)_{n \in \mathbb{N}}$ of elements of P such that $\forall n \in \mathbb{N} x_n \leq x_{n+1}$ and $\exists \alpha \in \mathbb{R}^+ \forall n \in \mathbb{N} \|x_n\|_P \leq \alpha$ (the sequence is bounded) has a lub $\sup_{n \in \mathbb{N}} x_n \in P$.

Subtraction

If $x \leq y$, there is a unique z such that $x + z = y$, by simplifiability.

This z is denoted as $y - x$.

This subtraction, when defined, satisfies all the usual algebraic laws.

Main motivating examples of cones

- For any PCS X , $C(X) = \{x \in (\mathbb{R}^+)^{|X|} \mid \exists \varepsilon > 0 \ \varepsilon x \in PX\}$ is a cone with $\|x\|_{C(X)} = \sup_{x' \in PX} \langle x, x' \rangle$.
- Let $(\mathcal{X}, \Sigma_{\mathcal{X}})$ be a measurable space. We define a cone $\text{Meas}(\mathcal{X})$ as the set of all \mathbb{R}^+ -valued measures μ on $\Sigma_{\mathcal{X}}$ (in particular $\mu(\mathcal{X}) < \infty$). Algebraic operations defined in the obvious way. $\|\mu\|_{\text{Meas}(\mathcal{X})} = \mu(\mathcal{X})$.

What morphisms?

Unit ball of P : $\mathcal{B}P = \{x \in P \mid \|x\|_P \leq 1\}$.

It is a poset where all monotone sequences have a lub (we do not consider uncountable directed subsets because we will have to use the Monotone Convergence Theorem at some point).

By analogy with (the CCC of) PCS's, a morphism from P to Q should be a Scott continuous function $\mathcal{B}P \rightarrow \mathcal{B}Q$.

But if we take all Scott continuous functions, we don't get a CCC.

Problem: the curried version $\Lambda(\text{wpor})$ of $\text{wpor} : [0, 1] \times [0, 1] \rightarrow [0, 1]$ should be a monotonic function $[0, 1] \rightarrow P$ where P is a cone of Scott continuous functions $[0, 1] \rightarrow [0, 1]$. Remember $\text{wpor}(x, y) = x + y - xy$ is Scott continuous.

$$\Lambda(\text{wpor})(x)(y) = \text{wpor}(x, y) = x + y - xy$$

We should have $\Lambda(\text{wpor})(0) \leq \Lambda(\text{wpor})(1)$ in this cone P where the operations are defined pointwise.

$$\Lambda(\text{wpor})(0)(y) = y$$

$$\Lambda(\text{wpor})(1)(y) = 1$$

So $f = \Lambda(\text{wpor})(1) - \Lambda(\text{wpor})(0) : [0, 1] \rightarrow [0, 1]$ is the function defined by $f(y) = 1 - y$ which is not monotonic.

Local cone

Let P be a cone and $u \in \mathcal{BP}$.

We define a new cone P_u as follows

- $P_u = \{x \in P \mid \exists \varepsilon > 0 \ \varepsilon x + u \in \mathcal{BP}\}$
- algebraic operations defined as in P .
- $\|x\|_{P_u} = \inf\{1/\varepsilon \mid \varepsilon > 0 \text{ and } \varepsilon x + u \in \mathcal{BP}\}$

Fact: P_u is a cone.

Observe that $\mathcal{B}(P_u) = \{x \in P \mid x + u \in \mathcal{BP}\} \subseteq \mathcal{BP}$.

Let P and Q be cones and $f : \mathcal{BP} \rightarrow Q$.

Assume that f is monotonic. Then, given $u \in \mathcal{BP}$, we have $\forall x \in \mathcal{B}(P_u) f(x) \leq f(x + u)$.

So we can define a function $\Delta f(_ ; u) : \mathcal{B}(P_u) \rightarrow Q$ by $\Delta f(x; u) = f(x + u) - f(x)$. We require this function to be also monotonic.

Given $v \in \mathcal{BP}$ such that $u + v \in \mathcal{BP}$, we can consider the function $\Delta f(_ ; u, v) : \mathcal{B}(P_{u,v}) \rightarrow Q$ given by

$$\begin{aligned} \Delta f(x; u, v) &= \Delta(\Delta f(_ ; u))(x; v) \\ &= f(x + u + v) - f(x + u) - f(x + v) + f(x) \end{aligned}$$

We require this function to be also monotonic.

And the same for all functions $\Delta f(_ ; u_1, \dots, u_n)$ for $u_1, \dots, u_n \in \mathcal{BP}$ such that $\sum_{i=1}^n u_i \in \mathcal{BP}$.

$$P_{\vec{u}} = P_{\sum_{i=1}^n u_i}$$

Third iterated difference:

$$\Delta f(x; u_1, u_2, u_3) = f(x + u_1 + u_2 + u_3) - f(x + u_1 + u_2) - f(x + u_1 + u_3) - f(x + u_2 + u_3) + f(x + u_1) + f(x + u_2) + f(x + u_3) - f(x).$$

More generally, if $\vec{u} \in \mathcal{BP}^n$ with $\sum_{i=1}^n u_i \in \mathcal{BP}$ and $x \in \mathcal{B}(P_{\vec{u}})$ and $\varepsilon \in \{+, -\}$, one defines

$$\Delta^\varepsilon f(x; \vec{u}) = \sum_{I \in \mathcal{P}_\varepsilon(n)} f(x + \sum_{i \in I} u_i) \in Q$$

where $\mathcal{P}_+(n)$ (resp. $\mathcal{P}_-(n)$) is the set of all $I \subseteq \{1, \dots, n\}$ such that $n - \#I$ is even (resp odd).

Absolutely monotonic and stable functions

Definition

The function $f : \mathcal{BP} \rightarrow Q$ is *absolutely monotonic* if, for all $\vec{u} \in \mathcal{BP}^n$ with $\sum_{i=1}^n u_i \in \mathcal{BP}$ and $x \in \mathcal{BP}_{\vec{u}}$, one has

$$\Delta^- f(x; \vec{u}) \leq \Delta^+ f(x; \vec{u})$$

Then we set $\Delta f(x; \vec{u}) = \Delta^+ f(x; \vec{u}) - \Delta^- f(x; \vec{u})$. This generalizes our previous examples, and the function $\Delta f(_ ; \vec{u})$ is monotonic.

Definition

The function $f : \mathcal{BP} \rightarrow Q$ is *stable* if it is absolutely monotonic, bounded (that is $\exists \alpha \forall x \in \mathcal{BP} \|f(x)\|_Q \leq \alpha$) and Scott continuous, that is:

For all monotonic sequence $(x_n)_{n \in \mathbb{N}}$ in \mathcal{BP} , one has $\sup_{n \in \mathbb{N}} f(x_n) = f(\sup_{n \in \mathbb{N}} x_n)$.

Fact

If X and Y are PCS's and $s \in P(X \Rightarrow Y)$, then the function $\hat{s} : PX \rightarrow PY$ is stable.

NB: Raphaëlle Crubillé proved the converse (based on work by Bernstein in the... 1930's).

The cone of stable functions

We define a cone $P \Rightarrow Q$ as follows.

- The elements of $P \Rightarrow Q$ are the stable functions $\mathcal{B}P \rightarrow Q$.
- Addition and scalar multiplication are defined pointwise
 $((f + g)(x) = f(x) + g(x)$ and $(\alpha f)(x) = \alpha f(x)$; these functions are stable by linearity of the operators $\Delta^\varepsilon_-(x; \vec{u})$).
- $\|f\|_{P \Rightarrow Q} = \sup_{x \in \mathcal{B}P} \|f(x)\|_Q$.

Then $f \leq g$ is equivalent to the following condition: for all $n \in \mathbb{N}$, all $\vec{u} \in \mathcal{B}P^n$ such that $\sum u_i \in \mathcal{B}P$ and all $x \in \mathcal{B}(P_{\vec{u}})$, one has

$$\Delta f(x; \vec{u}) \leq \Delta g(x; \vec{u})$$

that is

$$\Delta^+ f(x; \vec{u}) + \Delta^- g(x; \vec{u}) \leq \Delta^- f(x; \vec{u}) + \Delta^+ g(x; \vec{u})$$

Composing stable functions

If $f \in \mathcal{B}(P \Rightarrow Q)$ then $f : \mathcal{B}P \rightarrow \mathcal{B}Q$.

Theorem

Let $f \in \mathcal{B}(P \Rightarrow Q)$ and $g \in \mathcal{B}(Q \Rightarrow R)$. Then $g \circ f \in \mathcal{B}(P \Rightarrow R)$.

The proof is not straightforward because morphisms are not defined by a preservation property (like Scott continuity of Berry stability).

So we have a category **Cstab** whose objects are the cones and morphisms, the stable functions.

Intermezzo: why do we call these functions “stable”?

Reminder: a coherence space is a structure $E = (|E|, \circlearrowright_E)$ where $|E|$ is a countable set and \circlearrowright_E is a binary, reflexive and symmetric relation on $|E|$.

Cliques of E : $\text{Cl}(E) = \{x \subseteq |E| \mid \forall a, a' \in x \ a \circlearrowright_E a'\}$.

$(\text{Cl}(E), \subseteq)$ is a cpo, any subset of a clique is a clique.

A function $f : Cl(E) \rightarrow Cl(F)$ is stable if it is monotonic, Scott continuous and “conditionally multiplicative”, that is:

$$\forall x, x' \in Cl(E) \quad x \cup x' \in Cl(E) \Rightarrow f(x \cap x') = f(x) \cap f(x')$$

Let $f, g : Cl(E) \rightarrow Cl(F)$ be stable.
 f is stably less than g ($f \leq g$) if

$$\forall x, x' \in Cl(E) \quad x \subseteq x' \Rightarrow f(x) = f(x') \cap g(x)$$

Reformulating stability in coherence spaces

Let E be a coherence space. If $u \in \text{Cl}(E)$, define a “local” coherence space E_u as follows:

$|E_u| = \{a \in |E| \setminus u \mid \forall a' \in u \ a \supset_E a'\}$. So if $x \in \text{Cl}(E_u)$, $x + u$ (disjoint union) is in $\text{Cl}(E)$.

Let $f : \text{Cl}(E) \rightarrow \text{Cl}(F)$ be a function and $u \in \text{Cl}(E)$. We define

$\Delta f(_ ; u) : \text{Cl}(E_u) \rightarrow \text{Cl}(F)$ by

$\Delta f(x ; u) = f(x + u) \setminus f(x) \in \text{Cl}(F)$.

Theorem

A Scott continuous function $f : Cl(E) \rightarrow Cl(F)$ is stable iff for all $u \in Cl(E)$, the function $\Delta f(_ ; u) : Cl(E_u) \rightarrow Cl(F)$ is monotonic.

If f is stable, then $\Delta f(_ ; u) : Cl(E_u) \rightarrow Cl(F)$ is also stable.

So there is no need to consider $\Delta f(x; u_1, \dots, u_n)$ for $n \geq 2$: the corresponding conditions are redundant (this due to the idempotency of union).

Theorem

Let $f, g : Cl(E) \rightarrow Cl(F)$ be stable functions.

One has $f \leq g$ (for the stable order) iff

- $\forall x \in Cl(E) f(x) \subseteq g(x)$
- $\forall u \in Cl(E) \forall x \in Cl(E_u) \Delta f(x; u) \subseteq \Delta g(x; u)$.

Back to cones. The CCC **Cstab**

The cartesian product is defined in the obvious way: $P \times Q$ with norm defined by $\|(x, y)\|_{P \times Q} = \max(\|x\|_P, \|y\|_Q)$.

We have already defined the cone $P \Rightarrow Q$. The evaluation map $\text{Ev} : (P \Rightarrow Q) \times P \rightarrow Q$ is defined by $\text{Ev}(f, x) = f(x)$. It is stable.

If $f : \mathcal{B}R \times \mathcal{B}P \rightarrow \mathcal{B}Q$ is stable, it is a very nice exercise to prove that the function $\Lambda(f) : \mathcal{B}R \rightarrow \mathcal{B}(P \Rightarrow Q)$ defined as usual by $\Lambda(f)(z)(x) = f(z, x)$ takes actually its values in $\mathcal{B}(P \Rightarrow Q)$ and is stable.

What is the trouble with measurability?

Types of our target language are interpreted as cones. There is a type ρ of real numbers, and $[\rho] = \text{Meas}(\mathbb{R})$ (with respect to the standard Borel σ -algebra). For simplicity, ρ is our unique ground type.

A closed term M such that $\vdash M : \rho$ will be interpreted as an element $[M]$ of $\mathcal{B}(\text{Meas}(\mathbb{R}))$, that is, as a sub-probability measure.

For each $r \in \mathbb{R}$, there is a constant \underline{r} of our language $\vdash \underline{r} : \rho$. We set $[\underline{r}] = \delta_r \in \mathcal{B}(\text{Meas}(\mathbb{R}))$.

There is also a constant $\vdash \text{sample} : \rho$. Intuitively, sample draws a real number in $[0, 1]$ with uniform probability.

The language is CBN but has a “let” construct *restricted to the ground type of real numbers* (we omit contexts for readability):

$$\frac{\vdash M : \rho \quad x : \rho \vdash N : \sigma}{\vdash \text{let } x = M \text{ in } N : \sigma}$$

This construction is crucial: it draws a real number r according to the sub-probability measure defined by M and reduces to $N[r/x]$.

In our model **Cstab**: $\mu = [M]$ is an element of $\mathcal{B}(\text{Meas}(\mathbb{R}))$. And $[N]_x : \mathcal{B}(\text{Meas}(\mathbb{R})) \rightarrow [\sigma]$ is a stable function.

So we have a function $\gamma : [N]_x \circ \delta : \mathbb{R} \rightarrow [\sigma]$ where δ is the function $r \mapsto \delta_r$. We have $\gamma(r) = [N[r/x]]$ (by Substitution Lemma).

So we would like to set

$$[\text{let } x = M \text{ in } N] = \int_{\mathbb{R}} \gamma(r) \mu(dr) = \int_{\mathbb{R}} [N]_x(\delta_r) \mu(dr)$$

This integral does not make sense *a priori* for two reasons:

- We don't know how to integrate functions ranging in an arbitrary cone, but this is not a serious issue because $\sigma = \sigma_1 \rightarrow \dots \rightarrow \sigma_k \rightarrow \rho$ so we can replace our problem with: given $\gamma : \mathbb{R} \times \mathcal{BP} \rightarrow \text{Meas}(\mathbb{R})$, define $\gamma_\mu : \mathcal{BP} \rightarrow \text{Meas}(\mathbb{R})$ by

$$\gamma_\mu(x)(U) = \int_{\mathbb{R}} \gamma(r, x)(U) \mu(dr)$$

for $U \in \Sigma_{\mathbb{R}}$.

- More seriously, given $x \in \mathcal{BP}$ and $U \in \Sigma_{\mathbb{R}}$, there is no reason *a priori* for the function $r \mapsto \gamma(r, x)(U)$ (from \mathbb{R} to \mathbb{R}) to be measurable.

Our solution

Equip all cones with a family of sets of “measurability tests” $(M^n(P))_{n \in \mathbb{N}}$ where each element l of $M^n(P)$ is a function $l : \mathbb{R}^n \times P \rightarrow \mathbb{R}^+$ with the following properties:

- For each $\vec{r} \in \mathbb{R}^n$, the function $x \mapsto l(\vec{r}, x)$ is linear (commutes with all linear combinations in P) and Scott continuous from P to \mathbb{R}^+ .
- For each $x \in P$, the function $\vec{r} \mapsto l(\vec{r}, x)$ is measurable.
- For each measurable $h : \mathbb{R}^k \rightarrow \mathbb{R}^n$, $l \circ h \in M^k(P)$.
- $0 \in M^n(P)$ for all n .

Next we say that a function $\gamma : \mathbb{R}^n \rightarrow P$ is a *measurable path* if:

- $\gamma(\mathbb{R}^n)$ is bounded in P
- and for all $I \in M^k(P)$, the function $I * \gamma : \mathbb{R}^{k+n} \rightarrow \mathbb{R}^+$ defined by $(I * \gamma)(\vec{r}, \vec{s}) = I(\vec{r}, \gamma(\vec{s}))$ is measurable.

Last, a morphism $P \rightarrow Q$ in our new category \mathbf{Cstab}_m is a stable function $f : \mathcal{B}P \rightarrow \mathcal{B}Q$ such that, for any measurable path $\gamma : \mathbb{R}^n \rightarrow \mathcal{B}P$, the function $f \circ \gamma$ is a measurable path.

Such an f will be called a stable measurable function.

Construction of measurability tests

If \mathcal{X} is a measurable space, we equip $\text{Meas}(\mathcal{X})$ with the following measurability tests: $M^n(\text{Meas}(\mathcal{X})) = \{e_U \mid U \in \Sigma_{\mathcal{X}}\}$ where $e_U(\vec{r}, \mu) = \mu(U)$ for $\vec{r} \in \mathbb{R}^n$ and $\mu \in \text{Meas}(\mathcal{X})$.

Hence a path $\gamma : \mathbb{R}^n \rightarrow \text{Meas}(\mathcal{X})$ is a bounded function $\mathbb{R}^n \rightarrow \text{Meas}(\mathcal{X})$ such that the map $\vec{r} \mapsto \gamma(\vec{r})(U)$ is measurable for each $U \in \Sigma_{\mathcal{X}}$, that is, γ is a stochastic kernel from \mathbb{R}^n to \mathcal{X} .

$P \Rightarrow Q$ is the cone of all stable and measurable functions $\mathcal{B}P \rightarrow Q$, and this cone is equipped with the following measurability tests:

- Given $\gamma : \mathbb{R}^n \rightarrow \mathcal{B}P$ a measurable path and $m \in M^n(Q)$, we define $\gamma \triangleright m : \mathbb{R}^n \times (P \Rightarrow Q) \rightarrow \mathbb{R}^+$ by $(\gamma \triangleright m)(\vec{r}, f) = m(\vec{r}, f(\gamma(\vec{r})))$.
- $M^n(P \Rightarrow Q)$ is the set of all these $\gamma \triangleright m$.

To prove the completeness property of $P \Rightarrow Q$, we need the Monotone Convergence Theorem, so we can consider only lubs of countable families. This is enough for fixpoints!

No surprise in the definition of $P \times Q$.

This defines a CCC **Cstab**_m where we can interpret our target language and prove an adequacy theorem.

This solves indeed our integration problem.

$$\frac{\vdash M : \rho \quad x : \rho \vdash N : \sigma}{\vdash \text{let } x = M \text{ in } N : \sigma}$$

We take $\sigma = \rho$ to simplify a bit the notations.

- $\mu = [M] \in \mathcal{B}(\text{Meas}(\mathbb{R}))$,
- $f = [N]_x : \mathcal{B}(\text{Meas}(\mathbb{R})) \rightarrow \mathcal{B}(\text{Meas}(\mathbb{R}))$ is stable and measurable.

The map $\delta : \mathbb{R} \rightarrow \text{Meas}(\mathbb{R})$ defined by $\delta(r) = \delta_r$ is a measurable path, because, for any $U \in \Sigma_{\mathbb{R}}$, the test $e_U \in M^n(\text{Meas}(\mathbb{R}))$ satisfies:

$$(e_U * \delta)(\vec{r}, r) = e_U(\vec{r}, \delta(r)) = \delta_r(U) = \begin{cases} 1 & \text{if } r \in U \\ 0 & \text{otherwise.} \end{cases}$$

so $e_U * \delta$ is measurable since $U \in \Sigma_{\mathbb{R}}$.

Because f is (stable) measurable, it follows that $f \circ \delta : \mathbb{R} \rightarrow \text{Meas}(\mathbb{R})$ is a measurable path which means that for all $U \in \Sigma_{\mathbb{R}}$, the function

$$\begin{aligned} \mathbb{R} &\rightarrow \mathbb{R}^+ \\ r &\mapsto f(\delta_r)(U) \end{aligned}$$

is measurable.

So we can define $[\text{let } x = M \text{ in } N] \in \text{Meas}(\mathbb{R})$ as the measure ν given by

$$\nu(U) = \int_{\mathbb{R}} f(\delta_r)(U) \mu(dr)$$

Conclusion: a few questions

- Conjecture: this is an equationally fully abstract model of our “real probabilistic PCF” target language.
- We have a natural notion of measurable linear maps on cones. Does it give rise to a model of ILL? Probably. Of classical LL? Probably not, but can we find a class of measurable cones for which it is true, and which contains the cones $\text{Meas}(\mathcal{X})$?

- Representation theorem for a sufficiently large class of cones (including $\text{Meas}(\mathcal{X})$), typically replacing the webs $|X|$ of PCS with more structured spaces? Related to the previous question. This seems a crucial step in the development of an “intersection type systems” adapted to languages with continuous data types like \mathbb{R} .
- Probabilistic sequentiality, strong stability?
- Connection with other approaches (in particular: Staton quasi-Borel spaces, Keimel and Plotkin Kegelspitzen)?