Differentials and distances in probabilistic coherence spaces

Thomas Ehrhard
CNRS, IRIF, UMR 8243, Univ Paris Diderot,
Sorbonne Paris Cité, F-75205 Paris, France

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Abstract

In probabilistic coherence spaces, a denotational model of probabilistic functional languages, morphisms are analytic and therefore smooth. We explore two related applications of the corresponding derivatives. First we show how derivatives allow to compute the expectation of execution time in the weak head reduction of probabilistic PCF (pPCF). Next we apply a general notion of “local” differential of morphisms to the proof of a Lipschitz property of these morphisms allowing in turn to relate the observational distance on pPCF terms to a distance the model is naturally equipped with. This suggests that extending probabilistic programming languages with derivatives, in the spirit of the differential lambda-calculus, could be quite meaningful.

Introduction

Currently available denotational models of probabilistic functional programming (with full recursion, and thus partial computations) can be divided in three classes.

- **Game based models** were first proposed in [6] and further developed by various authors (see [2] for an example of this approach). From their deterministic ancestors they typically inherit good definability features.

- Models based on Scott continuous functions on domains endowed with additional probability related structures. Among these models we can mention Plotkin and Keimel Kegelspitzen [13] (domains equipped with an algebraic convex structure) and ω-quasi Borel spaces [15] (domains equipped with a generalized notion of measurability), this latter semantics, as far as we understand the situation, requiring the use of an adapted probabilistic powerdomain construction.

- Models based on (a generalization of) Berry stable functions. The first category of this kind was that of probabilistic coherence spaces (PCSs) and power series with non-negative coefficients (the Kleisli category of the model of Linear Logic developed in [5]) for which we could prove adequacy and full abstraction with respect to a probabilistic version of PCF [10]. We extended this idea to “continuous data types” (such as $\mathbb{R}$) by substituting PCSs with positive cones and power series with functions featuring an hereditary monotonicity property that we called stability and [3] showed that this extension is actually conservative (stable functions on PCSs, which are special positive cones, are exactly power series).

The main feature of this latter semantics is the extreme regularity of its morphisms. Being power series, they must be smooth. Nevertheless, the category $\mathbf{Pcoh}$ is not a model of differential linear logic in the sense of [9]. This is due to the fact that general addition of morphisms is not possible (only sub-convex linear combinations are available) thus preventing, e.g., the Leibniz rule to hold in the way it is presented in differential LL. Also a morphism $X \to Y$ in the Kleisli category $\mathbf{Pcoh}$ can be considered as a function from the closed unit ball of the cone $P$ associated with $X$ to the closed unit ball of the cone $Q$ associated with $Y$. From a differential point of view such a morphism is well behaved only in the interior of the unit ball. On the border derivatives can typically take infinite values.

1Because, when reformulated in the domain-theoretic framework of Girard’s coherence spaces, this condition exactly characterizes Berry’s stable functions.
Contents We already used the analyticity of the morphisms of Pcoh, to prove full abstraction results [10]. We provide here two more corollaries of this properties, involving now also derivatives. For both results, we consider a theoretic probabilistic purely functional programming language, which is a probabilistic extension of Scott and Plotkin’s PCF. This language pPCF features a single data type \( \iota \) of integers, a simple probabilistic choice operator \( \text{coin}(r) : \iota \) which flips a coin with probability \( r \) to get \( 0 \) and \( 1 - r \) to get \( 1 \). To make probabilistic programming possible, this language has a let \( (x, M, N) \) construct restricted to \( M \) of type \( \iota \) which allows to sample an integer according to the sub-probability distribution represented by \( M \).

The operational semantics is presented by a deterministic “stack machine” which is an environment-free version of Krivine machine parameterized by a choice sequence \( \mu \in C \), such that \( \mu \in \{0, 1\}^{\omega} \), presented as a partial evaluation function. We adopt a standard discrete probability approach, considering \( C_0 \) as our basic sample space and the evaluation function as defining a (total) probability density function on \( C_0 \). We also introduce an extension pPCF_{lab} of pPCF where terms can be labeled by elements of a set \( L \) of labels, making it possible to count the use of labeled subterms during a reduction. Evaluation for this extended calculus gives rise to a random variable on \( C_0 \) ranging in the set \( M_{\mathbb{R}_0}(L) \) of finite multisets of elements of \( L \). The expectation of number of uses of terms labeled by a given \( l \in L \) (which is a measure of the computation time) is then an \( \mathbb{N} \)-valued r.v, the expectation of which we want to evaluate. We prove that, for a given labeled closed term \( M \) of type \( \iota \), this expectation can be computed by taking a derivative of the interpretation of this term in the model Pcoh, and provide a concrete example of computation of such expectations. This result can be considered as a probabilistic version of [8]. The fact that derivatives can become infinite on the border of the unit ball corresponds then to the fact that this expectation of “computation time” can be infinite.

In the second application, we consider the contextual distance on pPCF terms generalizing Morris equivalence as studied in [4] for instance. The probabilistic features of the language makes this distance too discriminating, putting e.g. terms coin(0) and coin(\( \varepsilon \)) at distance 1 for all \( \varepsilon > 0 \) (probability amplification). Any cone (and hence any PCS) is equipped with a norm and hence a canonically defined metric. Using a locally defined notion of differential of morphisms in Pcoh, we prove that these morphisms enjoy a Lipschitz property on all balls of radius \( p < 1 \), with a Lipschitz constant \( \frac{1}{1 - p} \) (thus tending towards \( \infty \) when \( p \) tends towards 1). Modifying the definition of the operational distance by not considering all possible contexts, but only those which “perturbate” the tested terms by allowing them to diverge with probability \( 1 - p \), we upper bound this \( p \)-tamed distance by the distance of the model with a ratio \( p/(1 - p) \). Being in some sense defined wrt. linear semantic contexts, the denotational distance does not suffer from the probability amplification phenomenon. This suggests that \( p \)-tamed distances might be more suitable than ordinary contextual distances to reason on probabilistic programs.

Notations We use \( M_{\mathbb{R}_0}(I) \) for the set of finite multisets of elements of \( I \). Such a multiset is a function \( \mu : I \to \mathbb{N} \) such that \( \text{supp}(\mu) = \{ i \in I \mid \mu(i) \neq 0 \} \) is finite. We use additive operations for operations on multisets (0 for the empty multiset, \( \mu + \nu \) for their pointwise sum). We use \([i_1, \ldots, i_k]\) for the multiset \( \mu \) such that \( \mu(i) = \# \{ j \in \mathbb{N} \mid i_j = i \} \). We use \( I^{<\omega} \) for the set of finite sequences \((i_1, \ldots, i_k)\) of elements of \( I \) and \( \alpha \beta \) for the concatenation of such sequences. We use \( \emptyset \) for the empty sequence.

1 Probabilistic coherence spaces (PCS)

For the general theory of PCSs we refer to [9 10]. We recall briefly the basic definitions and provide a proof of a (folklore) characterization of these objects. PCSs are particular cones (a notion borrowed from [14]) as we used them in [10], so we start with a few words about these more general structures to which we plan to extend the constructions of this paper.

1.1 A few words about cones

A (positive) pre-cone is a cancellative \(^2\) commutative \( \mathbb{R}_{\geq 0}\)-semi-module \( P \) equipped with a norm \( \| \cdot \|_P \), that is a map \( P \to \mathbb{R}_{\geq 0} \), such that \( \| r \cdot x \|_P = r \cdot \| x \|_P \) for \( r \in \mathbb{R}_{\geq 0} \), \( \| x + y \|_P \leq \| x \|_P + \| y \|_P \) and \( \| x \|_P = 0 \Rightarrow x = 0 \). It is moreover assumed that \( \| x \|_P \leq \| x + y \|_P \), this condition expressing that the elements of \( P \) are positive. Given \( x, y \in P \), one says that \( x \) is less than \( P \) (notation \( x \leq y \)) if there exists

\(^2\)One distinctive feature of our approach is to not consider probabilities as an effect.
\(^3\)Meaning that \( x + y = x' + y \Rightarrow x = x' \).
z ∈ P such that x + z = y. By cancellativity, if such a z exists, it is unique and we denote it as y − x. This subtraction obeys usual algebraic laws (when it is defined). Notice that if x, y ∈ P satisfy x + y = 0 then since ∥x∥p ≤ ∥x + y∥p, we have x = 0 (and of course also y = 0). Therefore, if x ≤ y and y ≤ x then x = y and so is an order relation.

A (positive) cone is a positive pre-cone P whose unit ball BP = {x ∈ P | ∥x∥p ≤ 1} is ω-order-complete in the sense that any increasing sequence of elements of BP has a least upper bound in BP. In [10] we show how a notion of stable function on cones can be defined, which gives rise to a cartesian closed category.

The following construction will be crucial in Section 3.2. Given a cone P and x ∈ BP, we define the local cone at x as the set P_x = {u ∈ P | ∃ε > 0 ex ∈ BP}. Equipped with the algebraic operations inherited from P, this set is clearly a $\mathbb{R}_{≥0}$-semi-ring. We equip it with the following norm: ∥u∥p = inf{ε^{-1} | ε > 0 and x + εu ∈ BP} and then it is easy to check that P_x is indeed a cone. It is reduced to 0 exactly when x is maximal in BP. In that case one has ∥x∥p = 1 but notice that the converse is not true in general.

1.2 Basic definitions on PCSs

Given an at most countable set I and u, u’ ∈ $\mathbb{R}_{≥0}$^I, we set ⟨u, u’⟩ = $\sum_{i \in I} u_i u_i’$. Given P ⊆ $\mathbb{R}_{≥0}$^I, we define $P^I ⊆ \mathbb{R}_{≥0}$^I as $P^I = \{u’ ∈ \mathbb{R}_{≥0}^I | \forall u ∈ P ⟨u, u’⟩ ≤ 1\}$. Observe that if P satisfies $\forall a ∈ I \exists x ∈ P x_a > 0$ and $\forall a ∈ I \exists m ∈ \mathbb{R}_{≥0}∀x ∈ P x_a ≤ m$ then $P^I ⊆ \mathbb{R}_{≥0}^I$ and $P^I$ satisfies the same two properties.

A probabilistic pre-coherence space (pre-PCS) is a pair X = (|X|, PX) where |X| is an at most countable set and PX ⊆ $\mathbb{R}_{≥0}$^{|X|} satisfies PX^⊥⊥ = PX. A probabilistic coherence space (PCS) is a pre-PCS X such that $\forall a ∈ |X| \exists x ∈ PX x_a > 0$ and $\forall a ∈ |X| \exists m ∈ \mathbb{R}_{≥0}∀x ∈ PX x_a ≤ m$ so that PX ⊆ ($\mathbb{R}_{≥0}$)^{|X|}.

Given any PCS X we can define a cone P^X as follows:

$$P^X = \{x ∈ \mathbb{R}_{≥0}^{|X|} | ∃e > 0 ex ∈ PX\}.$$ 

that we equip with the following norm: ∥x∥_P^X = inf{r > 0 | x ∈ r P^X} and then it is easy to check that P(B(P^X)) = P^X. We simply denote this norm as ∥∥_X.

Given $t ∈ \mathbb{R}_{≥0}^{I × J}$, considered as a matrix (where I and J are at most countable sets) and $u ∈ \mathbb{R}_{≥0}^J$, we define $tu ∈ \mathbb{R}_{≥0}^I$ by $(tu)_j = I_{i,j}u_j$ (usual formula for applying a matrix to a vector), and if $s ∈ \mathbb{R}_{≥0}^{J × K}$, we define the product $st ∈ \mathbb{R}_{≥0}^{I × K}$ of the matrix s and t as usual by $(st)_{i,k} = I_{i,j}s_{j,k}$. This is an associative operation.

Let X and Y be PCSs, a morphism from X to Y is a matrix $t ∈ (\mathbb{R}_{≥0})^{(|X| × |Y|)}$ such that $∀a ∈ |X| t(x,y) ≥ 0$ and $t(x,y) ∈ \mathbb{R}_{≥0}$ and $t(x,y) = 0$ whenever $x = 0$ or $y = 0$. It is clear that the identity morphism is a morphism from X to X and that the matricial product of two morphisms is a morphism and therefore, PCS equipped with this notion of morphism form a category Pcoh.

The condition $t ∈ Pcoh(X, Y)$ is equivalent to $∀a ∈ \mathbb{R}_{≥0}∀y’ ∈ P^Y ⊆ P^X ⊆ (\mathbb{R}_{≥0})^{(|X| × |Y|)}$ (t, x ⊙ y’, x ⊙ y) ≤ 1 but (t, x ⊙ y’) = ⟨t, x ⊙ y’⟩(a,b) = xa y’b. This strongly suggests to introduce a construction $X ⊗ Z$, by setting |X ⊗ Z| = |X| × |Z| and P(X ⊗ Z) = {x ⊙ z | x ∈ PX and z ∈ PZ}⊥⊥ where (x ⊙ z)(a,c) = xa zc. Then it is easy to see that $X ⊗ Z$ is not only a pre-PCS, but actually a PCS and that we have equipped in that way the category Pcoh with a symmetric monoidal structure for which it is $*$-autonomous wrt. a dualizing object $\bot = 1 = ([*], [0, 1])$ (it is at the same time the unit of $\otimes$ and $\bot ⊆ (X ⊗ \bot) ⊆ (X)$ up to a trivial iso).

The category Pcoh is cartesian: if $(X_i)_{i ∈ I}$ is an at most countable family of PCSs, then $(\bigotimes_{i ∈ I} X_i, (π_i)_{i ∈ I})$ is the cartesian product of the $X_i$s, with $[π_i]_{X_i} = \bigcup_{i ∈ I} \{i\} × X_i$; $(π_i)_{i(a),a'}$ = 1 if $i = j$ and $a = a'$ and $(π_i)(i(a),a') = 0$ otherwise, and $x ∈ P([π_i]_{X_i})$ if $π_i x ∈ PX_i$ for each $i ∈ I$ (for $x ∈ \mathbb{R}_{≥0}^{|X|}$).

Given $t_i ∈ Pcoh(Y, X_i)$, the unique morphism $t = t_i$ ∈ Pcoh(Y, $\bigotimes_{i ∈ I} X_i$) such that $t_i(x) = 1$ is simply defined by $t_i(a,a) = (t_i)_{a,b}$. The dual operation $\bigoplus_{i ∈ I} X_i$, which is a coproduct, is characterized by $[\bigoplus_{i ∈ I} X_i] = \bigcup_{i ∈ I} \{i\} × X_i$ and $x ∈ P(\bigoplus_{i ∈ I} X_i)$ and $\bigoplus_{i ∈ I} π_i x$ ⊥, $\bigoplus_{i ∈ I} π_i x$ ⊥, $\bigoplus_{i ∈ I} π_i x$ ⊥. A particular case is

4This restriction is not technically necessary, but very meaningful from a philosophic point of view; the non countable case should be handled via measurable spaces and then one has to consider more general objects as in [10] for instance.
N = \oplus_{n \in \mathbb{N}} X_n where X_n = 1 for each n. So that \(|N| = \mathbb{N}\) and \(x \in (\mathbb{R}_{\geq 0})^{|N|}\) belongs to \(\mathrm{PN}\) if \(\sum_{n \in \mathbb{N}} x_n \leq 1\) (that is, \(x\) is a sub-probability distribution on \(N\)). There are successor and predecessor morphisms \(\mathrm{suc}, \mathrm{pred} \in \mathbf{Pcoh}(N,N)\) given by \(\mathrm{suc}_{n,n'} = \delta_{n+1,n'}\) and \(\mathrm{pred}_{n,n'} = 1\) if \(n = n' = 0\) or \(n = n' + 1\) and \(\mathrm{pred}_{n,n'} = 0\) in all other cases. An element of \(\mathbf{Pcoh}(N,N)\) is a (sub)stochastic matrix and our model should be understood as this kind of representation of programs.

As to the exponentials, one sets \(|X| = \mathcal{M}_{\mathbb{R}_{\geq 0}}(|X|)\) and \(\mathbb{P}(|X|) = \{x^i \mid x \in PX\}^{\perp}\) where, given \(\mu \in \mathcal{M}_{\mathbb{R}_{\geq 0}}(|X|)\), \(x^\mu = x = \sum_{a \in |X|} \mu(a)\). Then given \(t \in \mathbf{Pcoh}(X,Y)\), one defines \(!t \in \mathbf{Pcoh}(|X|,|Y|)\) in such a way that \(!x! = (tx)!\) (the precise definition is not relevant here; it is completely determined by this equation). We do not really need here either to specify the monoidal comonad structure of this exponential. The resulting cartesian closed category \(\mathbf{Pcoh}\) can be seen as a category of functions (actually, of stable functions as proved in [3]). Indeed, a morphism \(t \in \mathbf{Pcoh}(X,Y) = \mathbf{Pcoh}(|X|,|Y|)\) is completely characterized by the associated function \(\bar{t} : PX \to PY\) such that \(\bar{t}(x) = tx^i = \left(\sum_{\mu \in |X|} t_{x,\mu} x^\mu\right)_{x \in |Y|}\) so that we consider morphisms as power series (they are in particular monotonic and Scott continuous functions \(PX \to PY\)). In this cartesian closed category, the product of a family \((X_i)_{i \in I}\) is \(\otimes_{i \in I} X_i\), which is compatible with our viewpoint on morphisms as functions since \(\mathbf{P}(\otimes_{i \in I} X_i) = \prod_{i \in I} PX_i\) up to trivial iso. The object of morphisms from \(X\) to \(Y\) is \(|X| \to |Y|\) with evaluation mapping \((t,x) \in |X| \times PX \mapsto \bar{t}(x)\) that we simply denote as \(t(x)\) from now on. The well defined function \(\mathbb{P}(|X| \to |Y|) \to PX\) which maps \(t \mapsto \sup_{n \in \mathbb{N}} t^n(0)\) is a morphism of \(\mathbf{Pcoh}\) (and thus can be described as a power series in the vector \(t = \left(t_{m,a} \mid m \in \mathcal{M}_{\mathbb{R}_{\geq 0}}(|X|), a \in |X|\right)\) by standard categorical considerations using cartesian closedness: it provides us with fixed point operators at all types.

## 2 Probabilistic PCF, time expectation and derivatives

We introduce now the probabilistic functional programming language considered in this paper. The operational semantics is presented using elementary probability theoretic tools.

### 2.1 The core language

The types and terms are given by

\[\begin{align*}
\sigma, \tau, \ldots &::= \iota \quad | \quad \sigma \Rightarrow \tau \\
M, N, P, \ldots &::= n \quad | \quad \text{suc}(M) \quad | \quad \text{pred}(M) \quad | \quad x \quad | \quad \text{let}(x, M, N) \quad | \quad \text{if}(M, N, P) \\
&\quad | \quad (M)N \quad | \quad \lambda x^\sigma M \quad | \quad \text{fix}(M)
\end{align*}\]

The typing rules are as follows (for typing contexts \(\Gamma = (x_1 : \sigma_1, \ldots, x_n : \sigma_n)\)):

\[
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash n : \iota \\
\hline
\Gamma, x : \sigma \vdash x : \sigma
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash M : \iota \\
\hline
\Gamma \vdash \text{suc}(M) : \iota
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash M : \iota \\
\hline
\Gamma \vdash \text{pred}(M) : \iota
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash M : \iota \\
\hline
\Gamma \vdash \text{let}(z, M, N) : \sigma
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma, x : \sigma \vdash M : \tau \\
\Gamma \vdash \lambda x^\sigma M : \sigma \Rightarrow \tau
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash (M)N : \tau \\
\hline
\Gamma \vdash \text{fix}(M) : \sigma
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash M : \sigma \Rightarrow \sigma \\
\Gamma, x : \sigma \vdash \text{let}(x, M, N) : \sigma
\end{array}
\end{array}
\begin{array}{c}
\begin{array}{c}
\Gamma \vdash \text{coin}(r) : \iota \\
\Gamma \vdash \text{fix}(M) : \sigma
\end{array}
\end{array}
\end{array}
\]

\[r \in [0,1] \cap \mathbb{Q}\]

### 2.1.1 Denotational semantics

We survey briefly the interpretation of pPCF in PCFs thoroughly described in [10]. Types are interpreted by \(\llbracket \iota \rrbracket = \mathbb{N}\) and \(\llbracket \sigma \Rightarrow \tau \rrbracket = \llbracket \sigma \rrbracket \to \llbracket \tau \rrbracket\). Given \(M \in \text{pPCF}\) such that \(\Gamma \vdash M : \sigma\) (with \(\Gamma = (x_1 : \sigma_1, \ldots, x_k : \sigma_k)\)) one defines \(\llbracket M \rrbracket_{\Gamma} \in \mathbf{Pcoh}(\otimes_{i=1}^{k} \llbracket \sigma_i \rrbracket, \llbracket \sigma \rrbracket)\) that we see as a function \(\prod_{i=1}^{k} \mathbb{P}(\llbracket \sigma_i \rrbracket) \to \mathbb{P}(\llbracket \sigma \rrbracket)\). For instance \(\llbracket x_i \rrbracket_{\Gamma}(\underline{u}) = u_i\), \(\llbracket n \rrbracket_{\Gamma}(\underline{u}) = \underline{u}\) where \(\underline{u} \in \text{PN}\) is defined by \(u_i = \delta_{n_i}\), \(\llbracket \text{suc}(M) \rrbracket_{\Gamma}(\underline{u}) = \llbracket M \rrbracket_{\Gamma}(\underline{u})\) and
Similarly for \( \text{pred}(M) \), more importantly
\[
\|\text{coin}(r)\|\tau_\alpha = r \|0\| + (1 - r) \|1\| \\
\|\text{let}(x, M, N)\|\tau_\alpha = \bigoplus_{n \in \mathbb{N}} \|M\|\tau_\alpha \|N[x/\alpha]\|\tau_\alpha
\]
\[
\|\text{if}(M, N, P)\|\tau_\alpha = [\|M\|\tau_\alpha \|N\|\tau_\alpha + \bigoplus_{n \in \mathbb{N}} \|M\|\tau_\alpha \|N\|\tau_\alpha + \|P\|\tau_\alpha] \|\tau_\alpha.
\]
Application and \( \lambda \)-abstraction are interpreted as usual in a cartesian closed category (in particular \( \|M\|\tau_\alpha \|\text{let}(\alpha, M, N)\|\tau_\alpha \)). Last \( \text{fix}(M)\|\tau_\alpha = \sup_{n \in \mathbb{N}} \|M\|\tau_\alpha^n(0) \).

### 2.1.2 Operational semantics

Given an extension \( \Lambda \) of this language (with the same format for typing rules), we define the associated language of stacks (called \( \Lambda \)-stacks).

\[
\pi := \varepsilon | \text{arg}(M) \cdot \pi \cdot \text{succ} \cdot \pi \cdot \text{pred} \cdot \pi \cdot \text{seq}(N) \cdot \pi \cdot \text{let}(x, N) \cdot \pi
\]
where \( M \) and \( N \) range over \( \Lambda \). A stack typing judgment is of shape \( \sigma \vdash \pi \) (meaning that it takes a term of type \( \sigma \) and returns an integer) and the typing rules are as follows.

\[
\frac{}{\varepsilon \vdash \varepsilon} \quad \frac{\vdash M : \sigma}{\sigma \Rightarrow \tau \vdash \text{arg}(M) \cdot \pi} \quad \frac{\vdash \pi}{\vdash \text{succ} \cdot \pi} \quad \frac{\vdash \pi}{\vdash \text{pred} \cdot \pi} \quad \frac{\vdash N : \sigma}{\vdash P : \sigma} \quad \frac{\sigma \vdash \pi}{\sigma \vdash \text{seq}(N) \cdot \pi} \quad \frac{\sigma \vdash \pi}{\vdash \text{let}(x, N) \cdot \pi}
\]

A **state** is a pair \((M, \pi)\) such that \( \vdash M : \sigma \) and \( \sigma \vdash \pi \) for some (uniquely determined) type \( \sigma \), let \( S \) be the set of states. Let \( C_0 = \{0, 1\}^{<\omega} \) be the set of finite lists of booleans, we define a **partial function** \( \text{Ev} : S \times C_0 \rightarrow \mathbb{R}_{\geq 0} \):

\[
\begin{align*}
\text{Ev}(\langle \text{let}(x, M, N), \pi \rangle, \alpha) &= \text{Ev}(\langle M, \text{let}(x, N) \rangle, \alpha) \\
\text{Ev}(\langle \text{let}(x, N) \cdot \pi \rangle, \alpha) &= \text{Ev}(\langle N \langle x/\alpha \rangle \cdot \pi \rangle, \alpha) \\
\text{Ev}(\langle \text{if}(M, N, P), \pi \rangle) &= \text{Ev}(\langle M, \text{if}(N, P) \cdot \pi \rangle, \alpha) \\
\text{Ev}(\langle \text{arg}(N) \cdot \pi \rangle, \alpha) &= \text{Ev}(\langle N, \pi \rangle, \alpha) \\
\text{Ev}(\langle \text{pred}(N) \cdot \pi \rangle, \alpha) &= \text{Ev}(\langle P, \pi \rangle, \alpha) \\
\text{Ev}(\langle M \cdot N, \pi \rangle, \alpha) &= \text{Ev}(\langle M, \text{arg}(N) \cdot \pi \rangle, \alpha) \\
\text{Ev}(\langle \lambda x.\sigma M, \text{arg}(N) \cdot \pi \rangle, \alpha) &= \text{Ev}(\langle M \cdot [N/x], \pi \rangle, \alpha) \\
\text{Ev}(\langle \text{fix}(M), \pi \rangle, \alpha) &= \text{Ev}(\langle M, \text{arg}(\text{fix}(M)) \cdot \pi \rangle, \alpha) \\
\text{Ev}(\langle \text{coin}(r), \pi \rangle, \langle 0, \alpha \rangle) &= \text{Ev}(\langle 0, \pi \rangle, \alpha) \cdot r \\
\text{Ev}(\langle \text{coin}(r), \pi \rangle, \langle 1, \alpha \rangle) &= \text{Ev}(\langle 0, \pi \rangle, \alpha) \cdot (1 - r) \\
\text{Ev}(\langle \text{let}(x, N), \pi \rangle, \alpha) &= 1.
\end{align*}
\]

So the only possibility for a state to terminate is that it evaluates to \( 0 \) (this is of course an arbitrary choice). Let \( \mathcal{D}(s) \) be the set of all \( \alpha \in C_0 \) such that \( \text{Ev}(s, \alpha) \) is defined. When \( \alpha \in \mathcal{D}(s) \), the number \( \text{Ev}(s, \alpha) \in [0, 1] \) is the probability that the sequence of choices \( \alpha \) occurs during the execution. When all coins are fair (all the values of the parameters \( r \) are \( 1/2 \)), this probability is \( 2^{-\text{len}(\alpha)} \). The sum of these (possibly infinitely many) probabilities is \( \leq 1 \). In order to fit within a standard probabilistic setting, we extend this partial function of \( \alpha \), defining a total probability distribution \( \text{Ev}(s) : C_0 \rightarrow [0, 1] \) as follows

\[
\text{Ev}(s)(\alpha) = \begin{cases} 
\text{Ev}(s, \beta) & \text{if } \alpha = \langle 0 \rangle \beta \text{ and } \beta \in \mathcal{D}(s) \\
1 - \sum_{\beta \in \mathcal{D}(s)} \text{Ev}(s, \beta) & \text{if } \alpha = \langle 1 \rangle \\
0 & \text{in all other cases}
\end{cases}
\]

Let \( P_s \) be the associated probability measure\(^6\) (we are in a discrete setting so simply \( P_s(A) = \sum_{\alpha \in A} \text{Ev}(s)(\alpha) \) for all \( A \subseteq C_0 \).

\(^6\)The choice of accumulating on \( 1 \) all the complementary probability is completely arbitrary and has no impact on the result: we prove because all the events of interest for us will be subsets of \( \{0\}C_0 \subseteq C_0 \).
Accordingly, the event “the evaluation of \( s \) converges to \( \langle \rangle \) is \( (s \downarrow \emptyset) = \langle \rangle / D(s) \). Its probability is \( P_{s}(s \downarrow \emptyset) = \sum_{\beta \in D(s)} Ev(s, \beta) \). In the case \( s = \langle M, \varepsilon \rangle \) \((\text{with } \vdash M : \iota)\) this probability is exactly the probability of \( M \) to reduce to \( \emptyset \) in the probabilistic rewriting system presented e.g. in [10] (see [12] for more details on the connection between these two operational semantics), that is the sum of all probabilistic weights of reduction paths from \( M \) to \( \emptyset \), since each element of \( D(s) \) determines exactly one such path. So the Adequacy Theorem of [10] can be reformulated as follows.

**Theorem 1.** Let \( M \in pPCF \) with \( \vdash M : \iota \). Then \( \|M\|_{0} = P_{(M, \varepsilon)}((M, \varepsilon) \downarrow \emptyset) \).

We use sometimes \( P(M \downarrow \emptyset) \) as an abbreviation for \( P_{(M, \varepsilon)}((M, \varepsilon) \downarrow \emptyset) \).

### 2.2 Probabilistic PCF with labels and the associated random variable

We extend pPCF into pPCF\(_{\text{lab}}\) by adding a term labeling construct \( M^{l} \). It allows counting, during the execution of a closed term \( M \) of type \( \iota \), how many occurrences of subterms labeled by \( l \) arrive in head position. The typing rule for this new construct is simply \( \Gamma \vdash M : \sigma \). Of course pPCF\(_{\text{lab}}\)-stacks involve now such labeled terms but their syntax is not extended otherwise; let \( S_{\text{lab}} \) be the corresponding set of states. Then we have a partial evaluation function \( Ev_{\text{lab}} : S_{\text{lab}} \times C_{0} \rightarrow M_{\text{fin}}(L) \) which is defined exactly as \( Ev \) apart for the following cases,

\[
Ev_{\text{lab}}((M^{l}, \pi), \alpha) = Ev_{\text{lab}}((M, \pi), \alpha) + [l] \\
Ev_{\text{lab}}((\text{coin}(r), \pi), \langle \rangle) = Ev_{\text{lab}}((\langle \rangle, \pi), \alpha) \\
Ev_{\text{lab}}((\emptyset, \varepsilon), \langle \rangle) = 0 \quad \text{(the empty multiset)}.
\]

Let \( D_{\text{lab}}(s) \) be the set of \( \alpha \) such that \( Ev_{\text{lab}}(s, \alpha) \) is defined. Defining \( \mathcal{S} \) as \( s \) stripped from its labels, we clearly have \( D_{\text{lab}}(s) = D(\mathcal{S}) \). We define a r.v. \( Ev_{\text{lab}}(s) : C_{0} \rightarrow M_{\text{fin}}(L) \) by

\[
Ev_{\text{lab}}(s)(\alpha) = \begin{cases} 
Ev_{\text{lab}}(s, \beta) & \text{if } \alpha = (0) \beta \text{ and } \beta \in D(s) \\
0 & \text{in all other cases.}
\end{cases}
\]

Let \( l \in L \) and let \( Ev_{\text{lab}}(s)_{l} : C_{0} \rightarrow \mathbb{N} \) be the r.v. defined by \( Ev_{\text{lab}}(s)_{l}(\alpha) = Ev_{\text{lab}}(s)(\alpha)(l) \). Its expectation is

\[
E(Ev_{\text{lab}}(s)_{l}) = \sum_{n \in \mathbb{N}} n P_{s}(Ev_{\text{lab}}(s)_{l} = n) = \sum_{n \in \mathbb{N}} n \sum_{\mu \in M_{\text{fin}}(L)} P_{s}(Ev_{\text{lab}}(s) = \mu) \sum_{\mu \in M_{\text{fin}}(L)} \mu(l) P_{s}(Ev_{\text{lab}}(s) = \mu).
\]

This is the expected number of occurrences of \( l \)-labeled subterms of \( s \) arriving in head position during successful executions of \( s \). It is more meaningful to condition this expectation under convergence of the execution of \( s \) (that is, under the event \( s \downarrow \emptyset \)). We have \( E(Ev_{\text{lab}}(s)_{l} | s \downarrow \emptyset) = E(Ev_{\text{lab}}(s)_{l}) / P_{s}(s \downarrow \emptyset) \) as the r.v. \( Ev_{\text{lab}}(s)_{l} \) vanishes outside the event \( s \downarrow \emptyset \) since \( D_{\text{lab}}(s) = D(s) \).

### 2.3 Probabilistic PCF with labeled coins

Let pPCF\(_{c}\) be pPCF extended with a construct \( \text{coin}(l, r) \) typed as \( \Gamma \vdash \text{coin}(l, r) : \iota \). This language features the usual \( \text{coin}(r) \) construct for probabilistic choice as well as a supply of identical constructs labeled by \( L \) that we will use to simulate the counting of Section 2.2. Of course pPCF\(_{c}\)-stacks involve now terms with labeled coins but their syntax is not extended otherwise; let \( S_{\text{lab}} \) be the corresponding set of states. We use \( \text{lab}(M) \) for the set of labels occurring in \( M \) (and similarly \( \text{lab}(s) \) for \( s \in S_{\text{lab}} \)). Given a finite subset \( L \) of \( L \), we use \( \text{pPCF}_{c}(L) \) for the set of terms \( M \) such that \( \text{lab}(M) \subseteq L \) and we define similarly \( S_{\text{lab}}(L) \). We shall also use the similar notations \( \text{pPCF}_{\text{lab}}(L) \) and \( S_{\text{lab}}(L) \).

---

\(^{6}\)That is, simply, a function since we are in a discrete probability setting.
Lemma 3. Let lc (for instance by induction on terms. For all term constructs but labeled coins, the transformation does nothing.

Proof. (Sketch) With each \( \alpha(l) \in D_{lc}(s) \) we can associate a uniquely defined \( \eta_{s}(\alpha, \tilde{\alpha}) \in D(\bar{s}) \) which is a shuffle of \( \alpha \) and of the \( \alpha(l) \)'s (for \( l \in L \)) such that \( Ev_{lc}(s, \alpha, \tilde{\alpha}) = Ev(s, \eta_{s}(\alpha, \tilde{\alpha})) \), uniquely determined by the run of \( (s, \alpha, \tilde{\alpha}) \) in the “machine” \( Ev_{lab} \). This mapping \( \eta_{s} \) (which is defined much like \( Ev_{lc}(s, \alpha, \tilde{\alpha}) \)) is easily seen to be bijective. 

\[ P_{2}(s \downarrow 0) = \sum_{(\alpha, \tilde{\alpha}) \in D_{lc}(s)} Ev_{lc}(s, \alpha, \tilde{\alpha}). \]

2.3.1 Spying labeled terms in pPCF

Given \( \bar{r} = (r_{l})_{l \in L} \in (\mathbb{Q} \cap [0, 1])^{L} \), we define a (type preserving) translation \( lc_{\bar{r}} : pPCF_{lab}(L) \rightarrow pPCF_{lc} \) by induction on terms. For all term constructs but labeled coins, the transformation does nothing (for instance \( lc_{\bar{r}}(x) = x \), \( lc_{\bar{r}}(\lambda x^{\sigma} M) = \lambda x^{\sigma} lc_{\bar{r}}(M) \)) etc., the only non trivial case being \( lc_{\bar{r}}(M') = if(lcoin(l, r_{l}), lc_{\bar{r}}(M), \Omega^{\bar{r}}) \) where \( \sigma \) is the type of \( M \) and \( \Omega^{\bar{r}} = fix(\lambda x^{\sigma} x) \).

Lemma 3. Let \( s \in S_{lab}(L) \). Then \( D_{lab}(s) = D(s), \) \( D_{lc}(lc_{\bar{r}}(s)) = \{(\alpha, ((0)_{\bar{r}}Ev_{lab}(s, \alpha)(l))_{l \in L}) | \alpha \in D(\bar{s})\} \) and \( Ev_{lc}(lc_{\bar{r}}(s), \alpha, (0)_{\bar{r}}Ev_{lab}(s, \alpha)(l)) = P(\bar{r})((\alpha)_{\bar{r}})Ev_{lab}(s, \alpha) \).

2.3.2 Lemma 4. Let \( M \in pPCF_{lab}(L) \) with \( + M : \sigma \). If \( \bar{\sigma} \in M_{fin}(N)_{L} = M_{fin}(L \times N) \) and \( a \in ||\sigma|| \) satisfy \( (\bar{\sigma})(\bar{x}) \neq 0 \) then \( \rho_{t}(n) 
eq 0 \Rightarrow n = 0. \)

The proof is a simple induction on \( M \) (of course we also have to consider open terms) and uses the fact that \( ||\Omega^{\bar{r}}|| = 0. \) Given \( \mu \in M_{fin}(L) \), we use \( \mu [0] \) for the element \( \mu \) of \( M_{fin}(N)_{L} \) such that \( \rho_{t}(n) = \mu(l) \) if \( n = 0 \) and \( \rho_{t}(n) = 0 \) otherwise. Accordingly we define \( \bar{r}e_{0} = (r_{l}e_{0})_{l \in L} \in PN_{L} \) for \( \bar{r} \in [0, 1]^{L}. \)

Lemma 5. Let \( \bar{r} \in (\mathbb{Q} \cap [0, 1])^{L} \) and \( M \in pPCF_{lab}(L) \) with \( + M : \sigma \). Then \( [sp_{\bar{r}}(M)]_{\bar{r}} (\bar{r}e_{0}) = [lc_{\bar{r}}(M)] \).

Easy induction on \( M \) based on the fact that \( [\text{coin}(r)] = re_{0} + (1 - r)e_{1} \) (again, one needs a more general statement involving open terms).
the probability of convergence decrease when $q > 2$ way, so we found it useful to provide a detailed proof for further references. We say that a partially

The following simple lemma will show quite useful in the sequel. It is proven in [12] in a rather sketchy

Example 7. The point of this formula is that we can apply it to algebraic expressions of the semantics of the program. Consider the following term $M_q$ (for $q \in (Q \cap [0,1])$ such that $M_q = \varepsilon \Rightarrow \varepsilon$ $M_q = \text{fix}(\lambda x. x \cdot \text{if}(\text{coin}(q). \text{if}(f(x), 0, 0), \Omega^2), \text{if}(x, 0, \Omega^1), \Omega^2))$), we study $(M_q)^0$ (for a fixed label $l \in L$). So in this example, “time” means “number of uses of the parameter 0”. For all $v \in \text{PN}$, we have $[M_q]_0 = \varphi_q(u)$ where $\varphi_q : [0,1] \rightarrow [0,1]$ is such that $\varphi_q(x)$ is the least element of $[0,1]$ which satisfies $\varphi_q(x) = (1-q)x^2 + q \varphi_q(x)^2$. So $\varphi_q(u) = (1 - \sqrt{1 - 4q(1-q)u^2})/2q$ if $q > 0$ and $\varphi_q(u) = u$, the choice between the two solutions of the quadratic equation being determined by the fact that the resulting function $\varphi_q$ must be monotonic in $u$. So by Theorem 4 (for $q \in (0,1)$)

$$
\mathbb{E}(\mathbb{E}_{\text{lab}}(\langle M, \varepsilon \rangle_l) \mid (\langle M, \varepsilon \rangle_l) \downarrow 0) = \frac{\partial [\mathbb{sp}_2 M]_0}{\partial \varepsilon}(1, \ldots, 1)/[M]_0 .
$$

Theorem 6. Let $M \in \text{pPCF}_{\text{lab}}(L)$ with $\vdash M : \tau$. Then

$$
\mathbb{E}(\mathbb{E}_{\text{lab}}(\langle M, \varepsilon \rangle_l) \mid (\langle M, \varepsilon \rangle_l) \downarrow 0) = \frac{\partial [\mathbb{sp}_2 M]_0}{\partial \varepsilon}(1, \ldots, 1)/[M]_0 .
$$

Example 7. The point of this formula is that we can apply it to algebraic expressions of the semantics of the program. Consider the following term $M_q$ (for $q \in (Q \cap [0,1])$ such that $M_q = \varepsilon \Rightarrow \varepsilon$ $M_q = \text{fix}(\lambda x. x \cdot \text{if}(\text{coin}(q). \text{if}(f(x), 0, 0), \Omega^2), \text{if}(x, 0, \Omega^1), \Omega^2))$), we study $(M_q)^0$ (for a fixed label $l \in L$). So in this example, “time” means “number of uses of the parameter 0”. For all $v \in \text{PN}$, we have $[M_q]_0 = \varphi_q(u)$ where $\varphi_q : [0,1] \rightarrow [0,1]$ is such that $\varphi_q(x)$ is the least element of $[0,1]$ which satisfies $\varphi_q(x) = (1-q)x^2 + q \varphi_q(x)^2$. So $\varphi_q(u) = (1 - \sqrt{1 - 4q(1-q)u^2})/2q$ if $q > 0$ and $\varphi_q(u) = u$, the choice between the two solutions of the quadratic equation being determined by the fact that the resulting function $\varphi_q$ must be monotonic in $u$. So by Theorem 4 (for $q \in (0,1)$)

$$
\mathbb{P}((M_q)_0 \downarrow 0) = \varphi_q(1) = \frac{1 - |2q - 1|}{2q} = \begin{cases} 1 \text{ if } q \leq 1/2, \\ 1-q \text{ if } r > 1/2. \end{cases}
$$

Observe that we have also $\mathbb{P}(M_0 \downarrow 0) = \varphi_0(1) = 1$ so that Equation 2 holds for all $q \in [0,1]$ (the corresponding curve is the second one in Figure 4). Then by Theorem 6 we have $\mathbb{E}(\mathbb{E}_{\text{lab}}((M_q)^0, \varepsilon)_l) \mid ((M_q)_0, \varepsilon) \downarrow 0 = \varphi_q(1)/\varphi_0(1)$. Since $\varphi_q(u) = (1-q)u^2 + q \varphi_q(u)$ we have $\varphi_q(1) = 2(1-q)u + 2q \varphi_q(1)u \varphi_q(1)$ and hence $\varphi_q(1) = 2(1-q)/(1 - 2q)$ if $q < 1/2$, $\varphi_{1/2}(1) = \infty$ and $\varphi_q(1) = (1-q)/(2q-1)$ if $q > 1/2$ (using the expression of $\varphi_q(1)$ given by Equation 2), see the third curve in Figure 4. For $q > 1/2$ notice that the conditional time expectation and the probability of convergence decrease when $q$ tends to 1. When $q$ is very close to 1, $(M_q)_0$ has a very low probability to terminate, but when it does, it uses its argument only twice. For $q = 1/2$ we have almost sure termination with an infinite expected computation time.

3 Differentials and distances

3.1 Order theoretic characterization of PCSs

The following simple lemma will show quite useful in the sequel. It is proven in [12] in a rather sketchy way, so we found it useful to provide a detailed proof for further references. We say that a partially
Figure 1: Plot of \( \varphi_{0,5}(u) \) with \( u \) on the x-axis (vertical slope at \( u = 1 \)). Plots of \( \varphi_q(1) \) and \( \mathbb{E}[\ell((M_q)_i^b, \varepsilon)]_i \) with \( q \) on the x-axis. See Example 7.

ordered set \( S \) is \( \omega \)-complete if any increasing sequence of elements of \( S \) has a least upper bound.

**Lemma 8.** Let \( I \) be a countable set and let \( P \subseteq [\mathbb{R}_{\geq 0}]^I \). Then \( (I, P) \) is a probabilistic coherence space iff the following properties hold (equipping \( P \) with the product order).

1. \( P \) is downwards closed and closed under barycentric combinations.
2. \( P \) is \( \omega \)-complete.
3. and for all \( a \in I \) there is \( \varepsilon > 0 \) such that \( \varepsilon e_n \in P \) and \( P_a \subseteq [0,1/\varepsilon] \).

**Proof.** The \( \Rightarrow \) implication is easy (see [3]), we prove the converse, which uses the Hahn-Banach theorem in finite dimension. Let \( y \in ([\mathbb{R}_{\geq 0}]^I) \) such that \( y \notin P \). We must prove that there exists \( x' \in P^\perp \) such that \( \langle y, x' \rangle > 1 \) and \( \forall x \in P \langle x, x' \rangle \leq 1 \). Given \( J \subseteq I \) and \( z \in ([\mathbb{R}_{\geq 0}]^J) \), let \( z_j \) by the element of \( ([\mathbb{R}_{\geq 0}]^J) \) which takes value \( z_j \) for \( j \in J \) and \( 0 \) for \( j \notin J \). Then \( y \) is the hub of the increasing sequence \( \{y_{(i_1, \ldots, i_n)} \mid n \in \mathbb{N} \} \) (where \( i_1, i_2, \ldots \) is any enumeration of \( I \)) and hence there must be some \( n \in \mathbb{N} \) such that \( y_{(i_1, \ldots, i_n)} \notin P \). Therefore it suffices to prove the result for \( I \) finite, which we assume now. Let \( Q = \{x \in \mathbb{R}^I \mid \langle x, i \rangle \in I \} \) which is a convex subset of \( \mathbb{R}^I \). Let \( t_0 = \sup \{t \in \mathbb{R}_{\geq 0} \mid ty \in P \} \). By our closeness assumption on \( P \), we have \( t_0y \in P \) and therefore \( t_0 < 1 \). Let \( h : \mathbb{R}y \rightarrow \mathbb{R} \) be defined by \( h(ty) = t/t_0 \) (\( t_0 \neq 0 \) by our assumption [6] about \( P \) and because \( I \) is finite). Let \( q : \mathbb{R}^I \rightarrow \mathbb{R}_{\geq 0} \) be the gauge of \( Q \), which is the semi-norm given by \( q(z) = \inf \{\varepsilon > 0 \mid z \in \varepsilon Q \} \). It is actually a norm by our assumptions on \( P \). Observe that \( h(z) \leq q(z) \) for all \( z \in \mathbb{R} \), this boils down to showing that \( t \leq t_0g(ty) = \inf \{t \mid t_0g(y) \in P \} \) for all \( t \in \mathbb{R} \) which is clear since \( t_0g(y) = 1 \) by definition of these numbers. Hence, by the Hahn-Banach Theorem, there exists a linear \( l : \mathbb{R}^I \rightarrow \mathbb{R} \) which is \( \leq q \) and coincides with \( h \) on \( \mathbb{R}y \). Let \( y' \in \mathbb{R}^I \) be such that \( (z, y') = (z, y) \) for all \( z \in \mathbb{R}^I \) (using again the finiteness of \( I \)). Let \( x' \in ([\mathbb{R}_{\geq 0}]^I) \) be defined by \( x'_i = |y'|_i \). It is clear that \( \langle y, x' \rangle > 1 \) since \( y \in ([\mathbb{R}_{\geq 0}]^I) \) we have \( \langle y, x' \rangle \geq (y, y') = \langle l(y), h(y) = 1/t_0 > 1 \). Let \( N = \{i \mid y'_i < 0 \} \). Given \( z \in P \), let \( \tilde{z} \in \mathbb{R}^I \) be given by \( \tilde{z}_i = -z_i \) if \( i \in N \) and \( \tilde{z}_i = z_i \) otherwise. Then \( \langle z, x' \rangle = \langle z, y' \rangle = \langle l(z), y' \rangle \leq 1 \) since \( z \in Q \) (by definition of \( Q \) and because \( z \in P \)). It follows that \( x' \in P^\perp \).

### 3.2 Local PCS and derivatives

Let \( X \) be a PCS and let \( x \in PX \). We define a new PCS \( X_x \) as follows. First we set \( |X_x| = \{a \in |X| \mid \exists \varepsilon > 0 \ x + \varepsilon e_a \in PX \} \) and then \( P(X_x) = \{u \in ([\mathbb{R}_{\geq 0}]^{|X|}) \mid x + u \in PX \} \). There is a slight abuse of notation here: \( u \) is not an element of \( ([\mathbb{R}_{\geq 0}]^{|X|}) \), but we consider it as such by simply extending it with 0 values to the elements of \( |X| \setminus X_x \). Observe also that, given \( u \in PX \), if \( x + u \in PX \), then we must have \( u \in P(X_x) \), in the sense that \( u \) necessarily vanishes outside \( |X_x| \). It is clear that \( (X_x, P(X_x)) \) satisfies the conditions of Lemma 8 and therefore \( X_x \) is actually a PCS, called the local PCS of \( X \) at \( x \).

Let \( t \in \text{Poiso}(X, Y) \) and let \( x \in PX \). Given \( u \in P(X_x) \), we know that \( x + u \in PX \) and hence we can compute \( t(x + u) \in PY \): \( t(x + u)_b = \sum_{\mu \in |X|} t_\mu b(x + u)^\mu = \sum_{\mu \in |X|} t_\mu b \sum_{\nu \leq \mu} (\binom{\nu}{\mu}) x^{\mu - \nu} u^\nu \). Upon considering only the \( u \)-constant and the \( u \)-linear parts of this summation (and remembering that actually \( u \in P(X_x) \)), we get \( t(x) + \sum_{a \in |X|} u_a \sum_{\mu \in |X|} (\mu(a) + 1) t_{\mu + a} x^\mu \leq t(x + u) \in PY \). Given \( a \in |X_x| \) and \( b \in |Y(x)| \), we set \( t'(x)_{a,b} = \sum_{\mu \in |X|} (\mu(a) + 1) t_{\mu + a} x^\mu \) and we have proven that actually
It succeeds to write

\[ t'(x) \in P(X, Y(x)). \]

By definition, this linear morphism \( t'(x) \) is the **derivative (or differential, or jacobian)** of \( t \) at \( x \).

It is uniquely characterized by the fact that, for all \( x \in PX \) and \( u \in PX \), we have

\[ t(x + u) = t(x) + t'(x) u + \hat{t}(x, u) \tag{3} \]

where \( \hat{t} \) is a power series in \( x \) and \( u \) whose all terms have global degree \( \geq 2 \) in \( u \).

As a typical example, consider the case where \( Y = !X \) and \( t = \delta = !dX : X \to Pcoh(X, !X) \), so that \( \delta(x) = x' \). Given \( a \in [X] \) and \( \nu \in ![X, x] \), we have

\[
\delta'(x)_{a, \nu} = \sum_{\mu \in ![X]} (\mu(a) + 1) \delta_{\mu[a], a} x^\mu = \begin{cases} 0 & \text{if } \nu(a) = 0 \\ \nu(a) x^{\nu[a]} & \text{if } \nu(a) > 0. \end{cases}
\]

We know that \( \delta'(x) \in P(X \to !X) \) so that \( \delta'(x) \) is a “local version” of DiLL’s codereliction \( \boxed{} \). Observe for instance that \( \delta'(0) \) satisfies \( \delta'(0)_{a, \nu} = \delta_{\nu[a]} \) and therefore coincides with the ordinary definition of codereliction.

**Proposition 9** (Chain Rule). Let \( s \in Pcoh(X, Y) \) and \( t \in Pcoh(Y, Z) \). Let \( x \in PX \) and \( u \in PX \).

Then we have \((t \circ s)'(x) u = t'(s(x)) s'(x) u\).

**Proof.** It suffices to write

\[
(t \circ s)(x + u) = t(s(x + u)) = t(s(x) + s'(x) u + \bar{s}(x, u)) \\
= t(s(x)) + t'(s(x)) (s'(x) u + \bar{s}(x, u)) + \bar{t}(s(x), s'(x) u + \bar{s}(x, u)) \\
= t(s(x)) + t'(s(x)) (s'(x) u) + t'(s(x)) (\bar{s}(x, u)) + \bar{t}(s(x), s'(x) u + \bar{s}(x, u))
\]

by linearity of \( t'(s(x)) \) which proves our contention by the observation that, in the power series \( t'(s(x)) (\bar{s}(x, u)) + \bar{t}(s(x), s'(x) u + \bar{s}(x, u)) \), \( u \) appears with global degree \( \geq 2 \) by what we know on \( \bar{s} \) and \( \bar{t} \).

\[ \square \]

### 3.3 Glb’s, lub’s and distance

Since we are working with probabilistic coherence spaces, we could deal directly with families of real numbers and define these operations more concretely. We prefer not to do so to have a more canonical presentation generalizable to cones such as those considered in \( \Box \).

Given \( x, y \in PX \), observe that \( x \land y \in PX \), where \( (x \land y)_a = \min(x_a, y_a) \), and that \( x \land y \) is the glb of \( x \) and \( y \) in \( PX \) (with its standard ordering). It follows that \( x \) and \( y \) have also a lub \( x \lor y \in PX \) which is given by \( x \lor y = x + y - (x \land y) \) (and of course \( (x \lor y)_a = \max(x_a, y_a) \)).

Let us prove that \( x + y - (x \land y) \) is actually the lub of \( x \) and \( y \). First, \( x \leq x + y - (x \land y) \) simply because \( x \land y \leq y \).

Next, let \( z \in PX \) be such that \( x \leq z \) and \( y \leq z \).

We have used the fact that \( + \) distributes over \( \land \) so let us prove this last fairly standard property: \( x + (x \land y) = (x + z) \land (z + y) \). The “\(<\)” inequality is obvious (monotonicity of \( + \)) so let us prove the converse, which amounts to \( x \land y \leq (x + z) \land (z + y) - z \) (observe that indeed that \( z \leq (x + z) \land (z + y) \)).

This in turn boils down to proving that \( x \geq z + y - z \) which results from \( x + y \geq z + y \) and we are done.

Then we define the distance between \( x \) and \( y \) by \( \delta_X(x, y) = \|x - (x \land y)\|_X + \|y - (x \land y)\|_X \).

The only non obvious fact to check for proving that this is actually a distance is the triangular inequality, so let \( x, y, z \in PX \). We have \( x - (x \land z) \leq x - (x \land y \land z) = x - (x \land y) + (x \land y) - (x \land y \land z) \) and hence \( \|x - (x \land z)\|_X \leq \|x - (x \land y)\|_X + \|(x \land y) - (x \land y \land z)\|_X \). Now we have \( (y \land y) \leq y \), that is \( (x \land y) - (y \land y \land z) \leq y - (y \land z) \). It follows that \( \|x - (x \land z)\|_X \leq \|x - (x \land y)\|_X + \|y - (y \land z)\|_X \) and symmetrically \( \|z - (x \land z)\|_X \leq \|z - (x \land y)\|_X + \|y - (y \land x)\|_X \) and summing up we get, as expected \( \delta_X(x, z) \leq \delta_X(x, y) + \delta_X(y, z) \).

\[ \Box \]

But unlike our models of Differential LL, this derivative is only defined locally; this is slightly reminiscent of what happens in differential geometry.
3.4 A Lipschitz property

First of all, observe that, if \( w \in \mathbb{P}(X \rightarrow Y) \) and \( x \in \mathbb{P}X \), we have \( \|w_x\|_Y \leq \|w\|_{X \rightarrow Y} \|x\|_X \). Indeed, let \( \|w\|_{X \rightarrow Y} \in \mathbb{P}(X \rightarrow Y) \) and \( \|x\|_X \in \mathbb{P}X \), therefore \( \|w\|_{X \rightarrow Y} \times \|x\|_X \in \mathbb{P}Y \) and our contention follows.

Let \( p \in [0, 1] \). If \( x \in \mathbb{P}X \) and \( \|x\|_X \leq p \), observe that, for any \( u \in \mathbb{P}X \), one has \( \|x + (1 - p)u\|_X \leq \|x\|_X + (1 - p)\|u\|_X \leq 1 \) and hence \((1 - p)u \in \mathbb{P}(X_x \rightarrow \mathbb{O})\). Therefore, given \( w \in \mathbb{P}(X_x \rightarrow \mathbb{O}) \), we have \( \|w\|_{X \rightarrow \mathbb{O}} \leq 1 \) for all \( u \in \mathbb{P}X \) and hence \((1 - p)w \in \mathbb{P}(X \rightarrow \mathbb{O})\).

Let \( t \in \mathbb{P}(!X \rightarrow 1) \). We have seen that, for all \( x \in \mathbb{P}X \) we have \( t'(x) \in \mathbb{P}(X \rightarrow 1) \). Therefore, if we assume that \( \|x\|_X \leq p \), we have

\[
(1 - p)t'(x) \in \mathbb{P}(X \rightarrow 1) = \mathbb{P}X. \tag{4}
\]

Let \( x \leq y \in \mathbb{P}X \) be such that \( \|y\|_X \leq p \). Observe that \( 2 - p > 1 \) and that \( x + (2 - p)(y - x) = y + (1 - p)(y - x) \in \mathbb{P}X \) (because \( \|y\|_X \leq p \) and \( y - x \in \mathbb{P}X \)). We consider the function \( h : [0, 2 - p] \rightarrow [0, 1] \), defined by \( h(y) = t(x + \theta(y - x)) \), which is clearly analytic on \([0, 2 - p] \). More precisely, one has \( h(\theta) = \sum_{n=0}^{\infty} c_n \theta^n \) for some sequence of non-negative real numbers \( c_n \) such that \( \sum_{n=0}^{\infty} c_n (2 - p)^n \leq 1 \).

Therefore, the derivative of \( h \) is well defined on \([0, 1] \subset [0, 2 - p] \) and one has \( h'(\theta) = t'(x + \theta(y - x))(y - x) \leq \|x - y\|_X \leq \|x - y\|_X \) by (4), using Proposition 3. We have

\[
0 \leq t(y) - t(x) = h(1) - h(0) = \int_0^1 h'(\theta) \, d\theta \leq \frac{\|y - x\|_X}{1 - p}. \tag{5}
\]

Let now \( x, y \in \mathbb{P}X \) be such that \( \|x\|_X, \|y\|_X \leq p \) (we don’t assume any more that they are comparable). We have \( |t(x) - t(y)| = |t(x) - t(x \land y) + t(x \land y) - t(y)| \leq |t(x) - t(x \land y)| + |t(y) - t(x \land y)| \leq \frac{1}{1 - p} \|x - (x \land y)\|_X + \|y - (x \land y)\|_X = \frac{d_X(x, y)}{1 - p} \) by (5) since \( x \land y \leq x, y \).

**Theorem 10.** Let \( t \in \mathbb{P}(X \rightarrow 1) \). Given \( p \in [0, 1] \), the function \( t \) is Lipschitz with Lipschitz constant \( \frac{1}{1 - p} \) on \( \{x \in \mathbb{P}X | \|x\|_X \leq p \} \) when \( \mathbb{P}X \) is equipped with the distance \( d_X \), that is

\[
\forall x, y \in \mathbb{P}X \quad \|x\|_X, \|y\|_X \leq p \Rightarrow |t(x) - t(y)| \leq \frac{d_X(x, y)}{1 - p}. \]

4 Application to the observational distance in pPCF

Given a term \( M \) such that \( \vdash M : \iota \), remember that we use \( \mathbb{P}(M \downarrow \mathbb{O}) \) for the probability of \( M \) to reduce to \( \mathbb{O} \) in the probabilistic reduction system of [10], so that \( \mathbb{P}(M) = \mathbb{P}(M, \varepsilon \downarrow \mathbb{O}) \) with the (admittedly heavy) notations of Section 2. Remember that \( \mathbb{P}(M, \varepsilon \downarrow \mathbb{O}) = [M]_0 \) by the Aductivity Theorem of [10].

Given a type \( \sigma \) and two pPCF terms \( M, M' \) such that \( \vdash M : \sigma \) and \( \vdash M' : \sigma \), we define the observational distance \( d_{\text{obs}}(M, M') \) between \( M \) and \( M' \) as the sum of all of the \( |\mathbb{P}((C) M \downarrow \mathbb{O}) - \mathbb{P}((C) M' \downarrow \mathbb{O})| \) taken over terms \( C \) such that \( \vdash C : \iota \) (testing contexts).

If \( \varepsilon \in [0, 1] \cap \mathbb{Q} \) we have \( d_{\text{obs}}(\text{coin}(0), \text{coin}(\varepsilon)) = 1 \) as soon as \( \varepsilon > 0 \). It suffices indeed to consider the context \( C = \text{fix } f^{(1-\varepsilon)} \lambda z \varepsilon \). The semantics \( [C] \in \mathbb{P}([N] \rightarrow N) \) is a function \( c : \mathbb{P} N \rightarrow \mathbb{P} N \) such that \( \forall u \in \mathbb{P} N c(u) = u_0 c(u) + (\sum_{i=1}^{\infty} u_i) \) and which is minimal (for the order relation of \( \mathbb{P}([N] \rightarrow N) \)). If follows that

\[
c(u) = \begin{cases}
0 & \text{if } u_0 = 1 \\
\frac{1 - u_0}{\sum_{i=1}^{\infty} u_i} & \text{otherwise}.
\end{cases}
\]

Then \( c((1 - \varepsilon) \varepsilon + \varepsilon \mathbb{T}) = 0 \) if \( \varepsilon = 0 \) and \( c((1 - \varepsilon) \varepsilon + \varepsilon \mathbb{T}) = 1 \) if \( \varepsilon > 0 \). This is a well known phenomenon called “probability amplification” in stochastic programming.

Nevertheless, we can control a tamed version of the observational distance. Given a closed pPCF term \( C \) such that \( \vdash C : \sigma \Rightarrow \iota \) we define \( C^{(p)} = \lambda z^{(p)} (C) \text{fix } (p(z, \varepsilon)) \) and a tamed version of the observational distance is defined by

\[
d_{\text{obs}}^{(p)}(M, M') = \sup \left\{ \left| \mathbb{P}((C^{(p)}) M \downarrow \mathbb{O}) - \mathbb{P}((C^{(p)}) M' \downarrow \mathbb{O}) \right| \mid \vdash C : \sigma \Rightarrow \iota \right\}
\]
Theorem 11. Let \( p \in [0, 1) \cap \mathbb{Q} \). Let \( M \) and \( M' \) be terms such that \( \vdash M : \sigma \) and \( \vdash M' : \sigma \). Then we have

\[
d^{(p)}_{\text{obs}}(M, M') \leq \frac{p}{1-p} d_{\|}([M], [M']).
\]

Proof.

\[
d^{(p)}_{\text{obs}}(M, M') = \sup\{|[C](p[M])_0 - [C](p[M'])_0| | \vdash C : \sigma \Rightarrow \tau\}
\leq \sup\{|t(p[M]) - t(p[M'])| | t \in \mathbb{P}([\sigma] \rightarrow \tau)\}
\leq \frac{d_{\|}([p[M], p[M']])}{1-p} = \frac{p}{1-p} d_{\|}([M], [M']).
\]

by the Adequacy Theorem and by Theorem 10. \( \square \)

Since \( p/(1-p) = p + p^2 + \cdots \) and \( d_{\|}(\cdot, \cdot) \) is an overapproximation of the observational distance restricted to linear contexts, this inequation carries a rather clear operational intuition in terms of execution in a Krivine machine as in Section 2.1.2 (thanks to Paul-André Melliès for this observation). Our main point is that the model \( \text{Pcoh} \) allows to prove such results in a purely denotational way using ideas coming from mainstream maths.

We finish the paper by observing that the equivalence relations induced on terms by these observational distances coincide with the ordinary observational distance if \( p \neq 0 \).

Theorem 12. Assume that \( 0 < p \leq 1 \). If \( d^{(p)}_{\text{obs}}(M, M') = 0 \) then \( M \sim M' \) (that is, \( M \) and \( M' \) are observationally equivalent).

Proof. If \( \vdash M : \sigma \) we set \( M_p = \text{if}(\text{coin}(p), M, \Omega^\sigma) \). If \( d^{(p)}_{\text{obs}}(M, M') = 0 \) then \( M_p \sim M'_p \) by definition of observational equivalence, hence \([M_p] = [M'_p]\) by our Full Abstraction Theorem 10, but \([M_p] = p[M]\) and similarly for \( M' \). Since \( p \neq 0 \) we get \([M] = [M']\) and hence \( M \sim M' \) by adequacy 10. \( \square \)

So for each \( p \in (0, 1) \) and for each type \( \sigma \) we can consider \( d^{(p)} \) as a distance on the observational classes of closed terms of type \( \sigma \). We call it the \( p \)-tamed observational distance. Our Theorem 11 shows that we can control this distance using the denotational distance. For instance we have \( d^{(p)}_{\text{obs}}(\text{coin}(0), \text{coin}(\varepsilon)) \leq \frac{2p}{1-p} \) so that \( d^{(p)}_{\text{obs}}(\text{coin}(0), \text{coin}(\varepsilon)) \) tends to 0 when \( \varepsilon \) tends to 0.

Conclusion

The two results of this paper are related: both use derivatives wrt. probabilities to evaluate the number of times arguments are used. We think that they provide motivations for investigating further differential extensions of \( \text{pCF} \) and related languages in the spirit of [11]. We thank Raphaëlle Crubillé, Paul-André Melliès, Michele Pagani and Christine Tasson for many enlightening discussions on this work.

References


