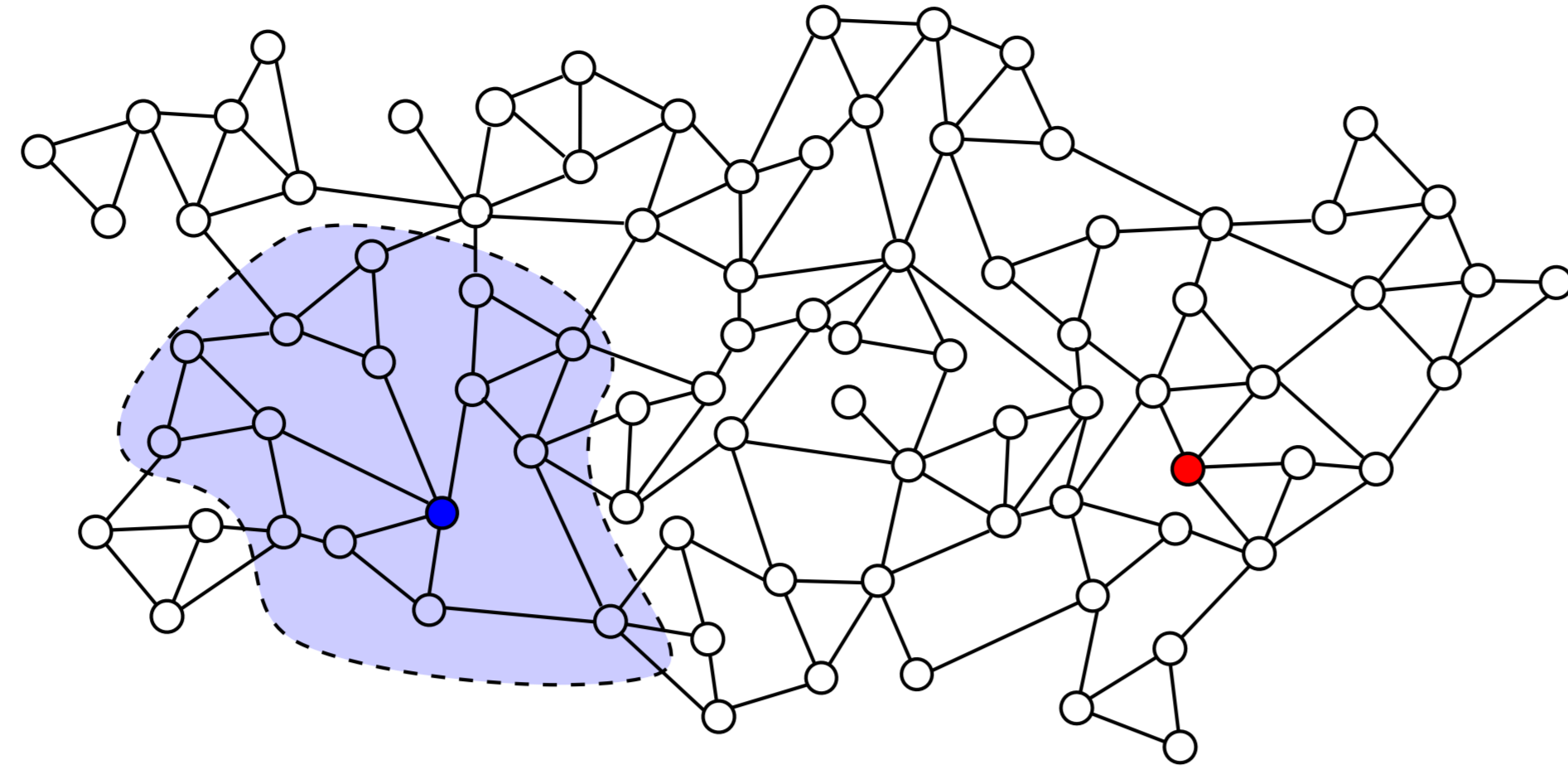


DISTRIBUTED GRAPH ALGORITHMS

A distributed graph algorithm is an algorithm that every node of a network will run to compute a solution to a graph problem. The nodes have the knowledge of a small neighbourhood only which, in this poster, is a constant radius ball.



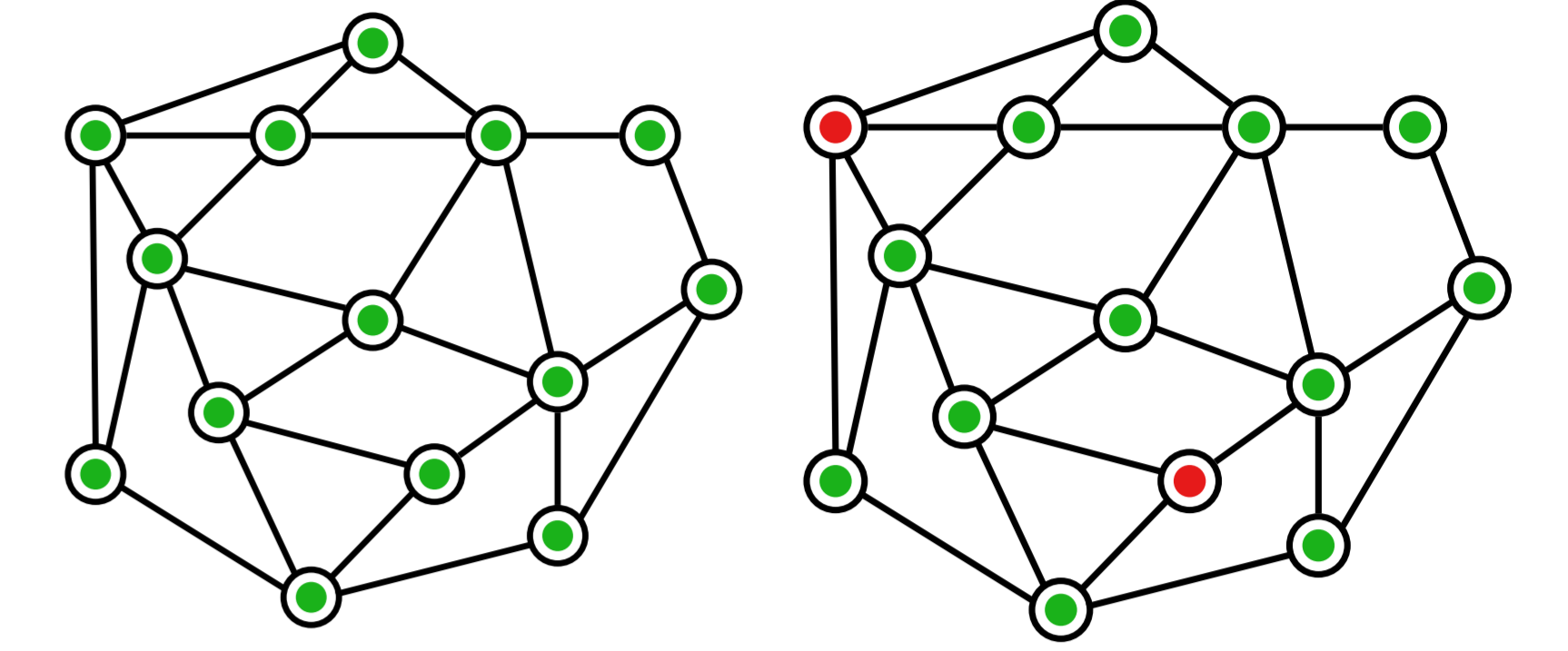
LOCAL DECISION

Most of the literature → computing something, e.g. a colouring

Local decision → deciding properties, e.g. acyclicity of the graph.

Goal: study complexity classes of decision problems (see *Survey of distributed decision* by F&F).

Decision mechanism: the graph is accepted if and only if all the nodes accept locally.

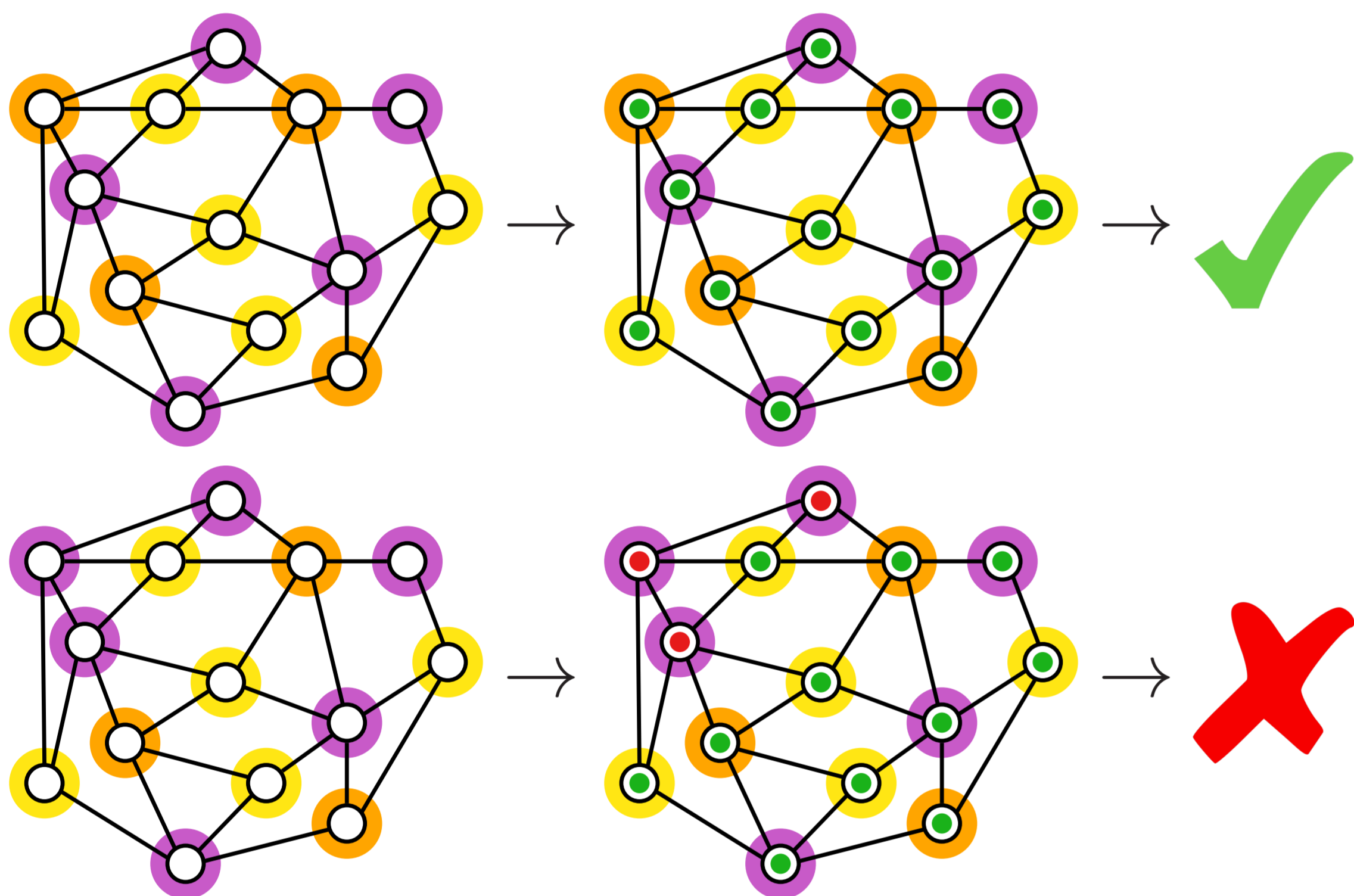


LEVEL 0: LOCALLY DECIDABLE

We consider languages, that are sets of graphs (G) , with inputs on the nodes $(x_v, v \in V(G))$. For example, let $\mathcal{L}_{3\text{-coloured}}$ be the language of the coloured graphs such that the colouring is a proper 3-colouring. A language is locally decidable if the nodes can decide locally if the network belongs to it, using the above mechanism.

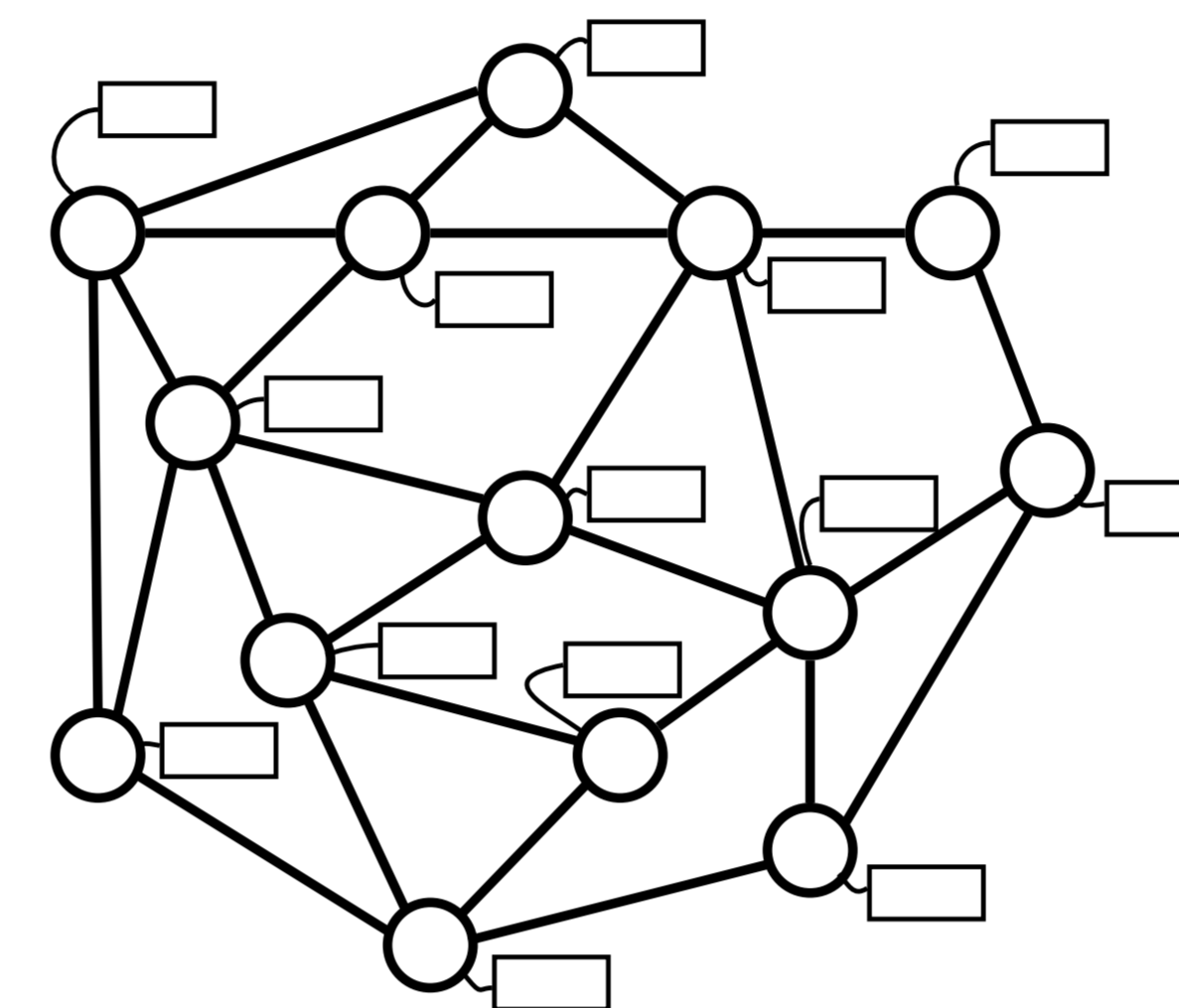
EXAMPLE

The language $\mathcal{L}_{3\text{-coloured}}$ is locally decidable.



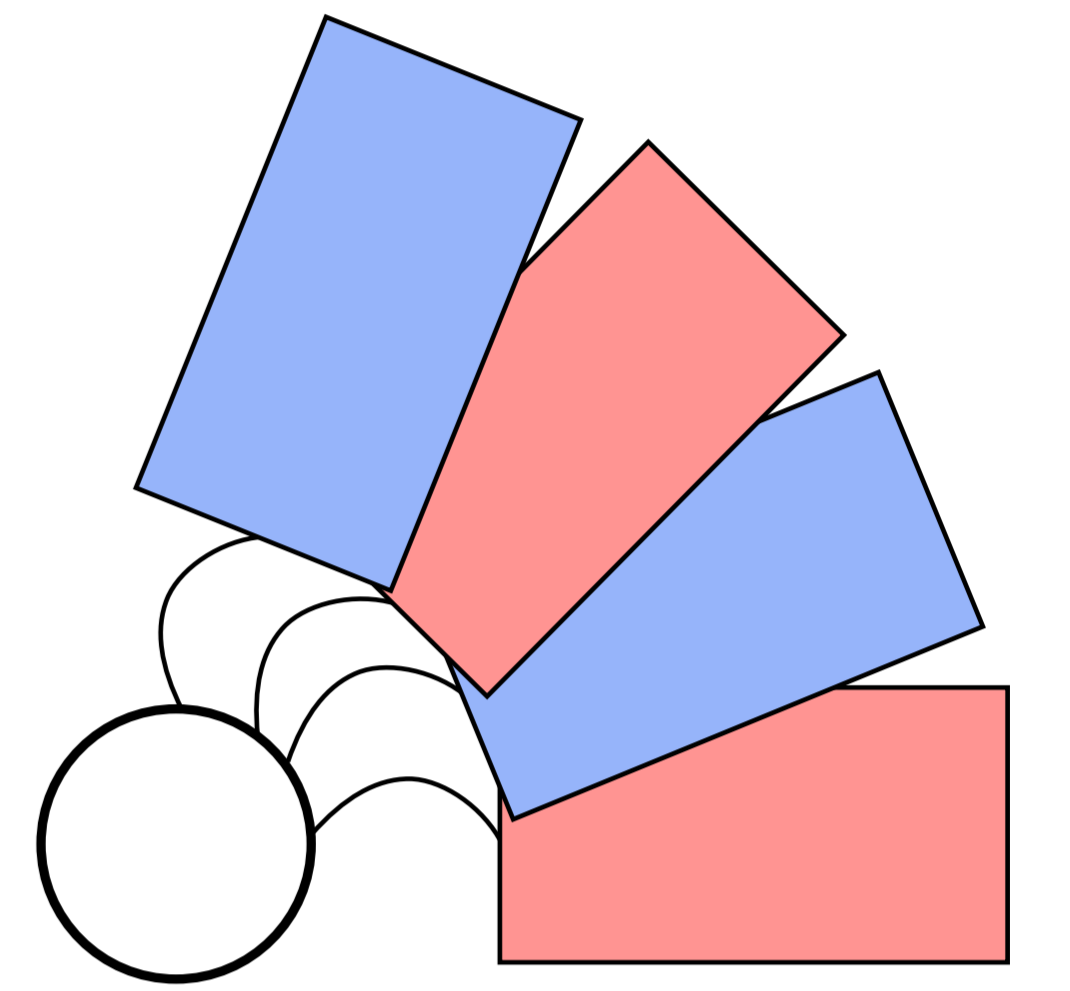
LEVEL 1: LOCALLY VERIFIABLE

Locally checkable proof = a function that assigns to each node of the graph a label. As the certificates in sequential non-determinism, it is a proof that the instance is correct. It must be verifiable locally.



LEVEL k : LOCAL HIERARCHY

- Before: analogue of P and NP.
- This work: analogue of the polynomial hierarchy
- Idea: a prover and a disprover give labels to the nodes one after the other, to convince them respectively to accept and to reject the graph.



CLASSES Σ_p^L AND Π_p^L

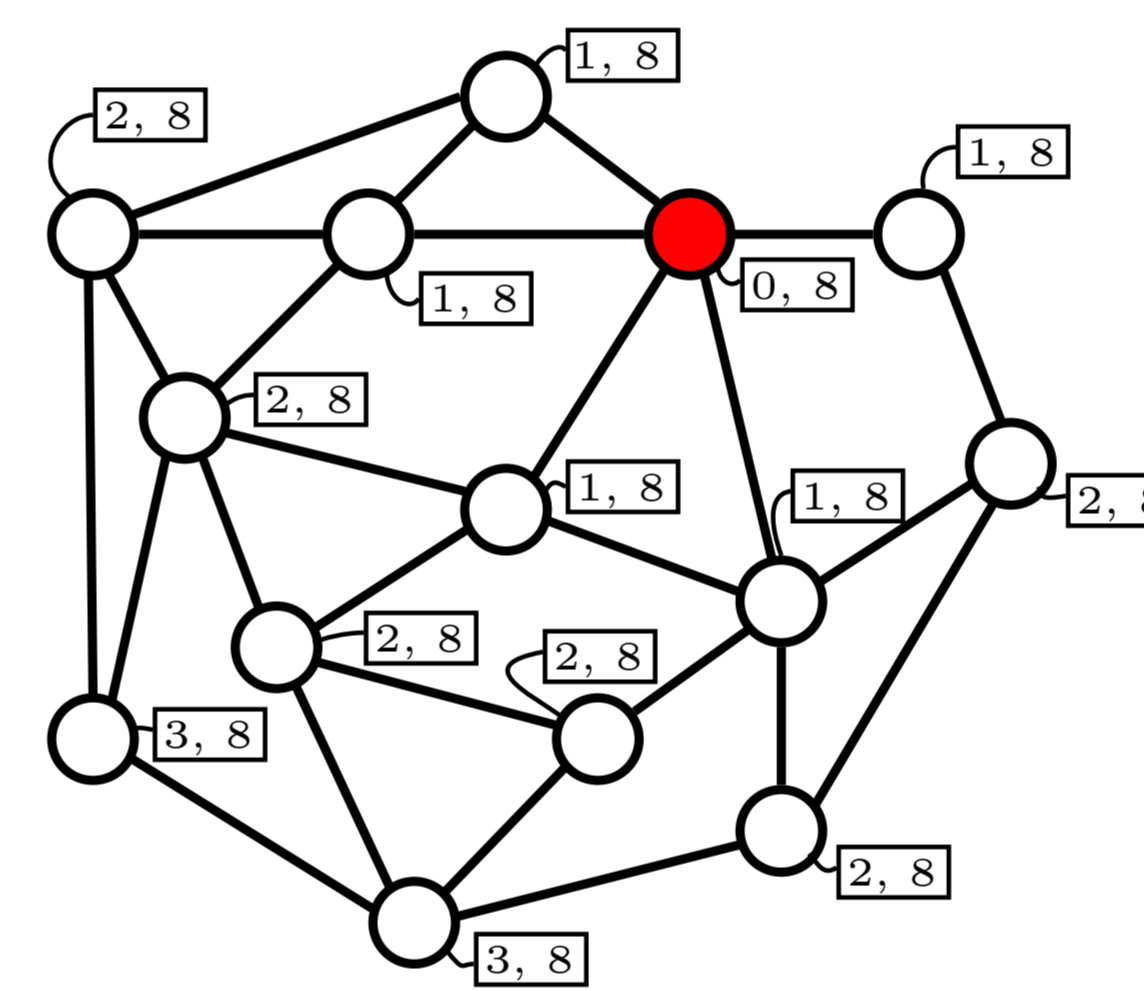
We define the classes Σ_p^L and Π_p^L . All the labels y have logarithmic size.

$\mathcal{L} \in \Sigma_p^L$ if and only if
 $\exists A \in \text{Cst-dist}$ such that for all G, x ,
 $(G, x) \in \mathcal{L} \Leftrightarrow \exists y_1, \forall y_2, \dots, Q_p y_p, A(G, x, y) = 1$

$\mathcal{L} \in \Pi_p^L$ if and only if
 $\exists A \in \text{Cst-dist}$ such that for all G, x ,
 $(G, x) \in \mathcal{L} \Leftrightarrow \forall y_1, \exists y_2, \dots, Q_p y_p, A(G, x, y) = 1$

EXAMPLE: LEADER

Language: graphs with exactly one leader (e.g. a node with a special flag). A locally checkable proof is shown below.



DEFINITION LD

We define the basic class of complexity, LD:

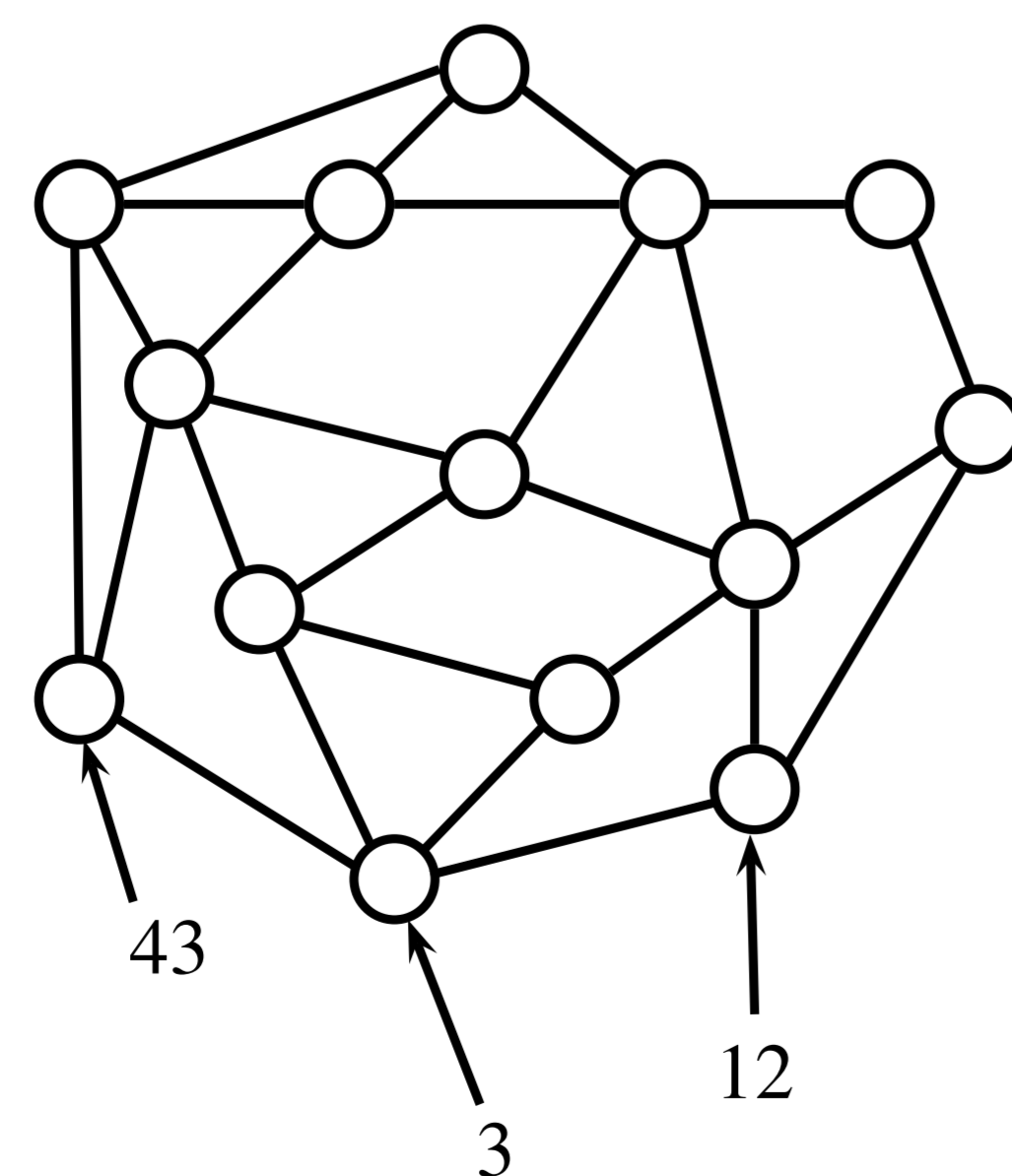
$\mathcal{L} \in LD$ if and only if
 $\exists A \in \text{Cst-dist}$ s.t. $\forall G, x, (G, x) \in \mathcal{L} \Leftrightarrow A(G, x) = 1$
where $A(G, x) = 1$ means $\forall v, A(G, x_v, v) = 1$

The analogue in the sequential setting is P :

$\mathcal{L} \in P$ if and only if
 $\exists A \in \text{Polytime}$ such that $\forall x, x \in \mathcal{L} \Leftrightarrow A(x) = 1$

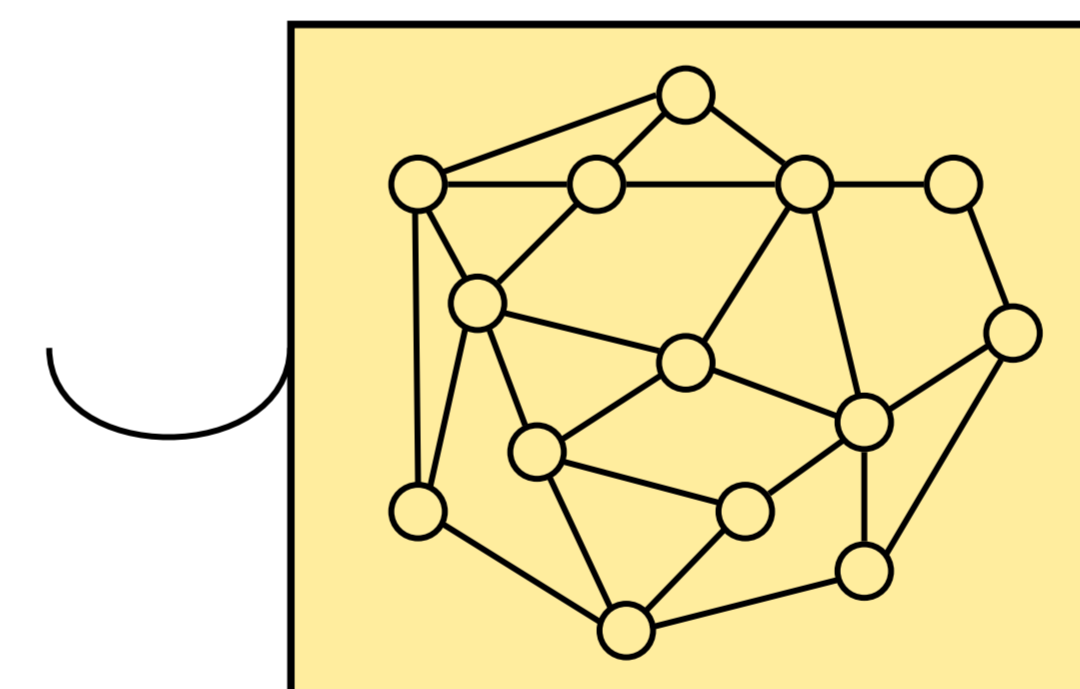
REMARKS

- The nodes have distinct IDs. They can use them during the computation. The language should not depend on the IDs of the graph.
- The degree is not bounded: constant size neighbourhoods can be big.
- Local model: no limit on bandwidth or local computation.



SIZE OF THE PROOFS

The labels can depend on IDs
 \hookrightarrow a $O(n^2)$ label encodes the graph
 \hookrightarrow any property can be decided.



Challenge: having small labels.

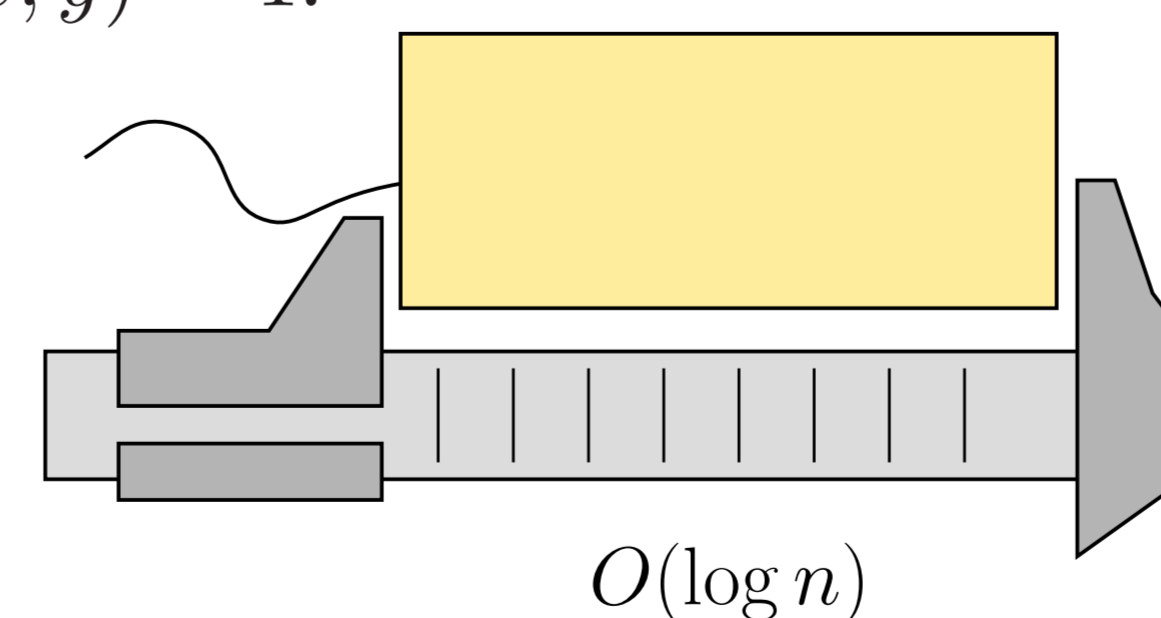
LOGLCP

We consider the class LogLCP, an analogue of NP:

$\mathcal{L} \in \text{LogLCP}$ if and only if
 $\exists A \in \text{Cst-dist}$ such that for all $G, x, (G, x) \in \mathcal{L} \Leftrightarrow \exists y$, with $|y| \in O(\log(n))$, $A(G, x, y) = 1$

$\mathcal{L} \in NP$ if and only if
 $\exists A \in \text{Polytime}$ such that for all $x, x \in \mathcal{L} \Leftrightarrow \exists y$, with $|y| \in O(\text{poly}(n))$, $A(x, y) = 1$.

LogLCP contains many languages: leader, acyclicity, colourability, and all the complement of languages in LD.



IF IT RINGS A BELL



You may know the paper *What can be computed locally?* by Naor and Stockmeyer (1995), where a very similar class, called LCL, is defined.

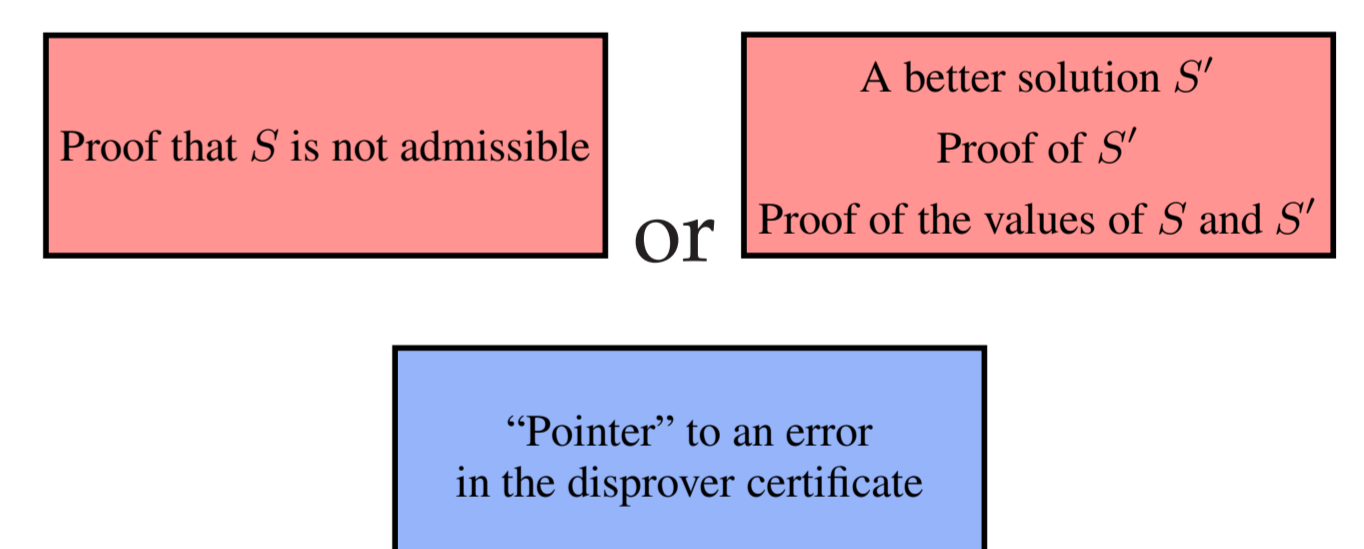
IF IT RINGS A BELL



Göös and Suomela defined locally checkable proofs in an eponymous paper. The basic concept is older, is called *proof labelling scheme* and has been studied by Korman, Kutten, Peleg and Masuzawa, among others.

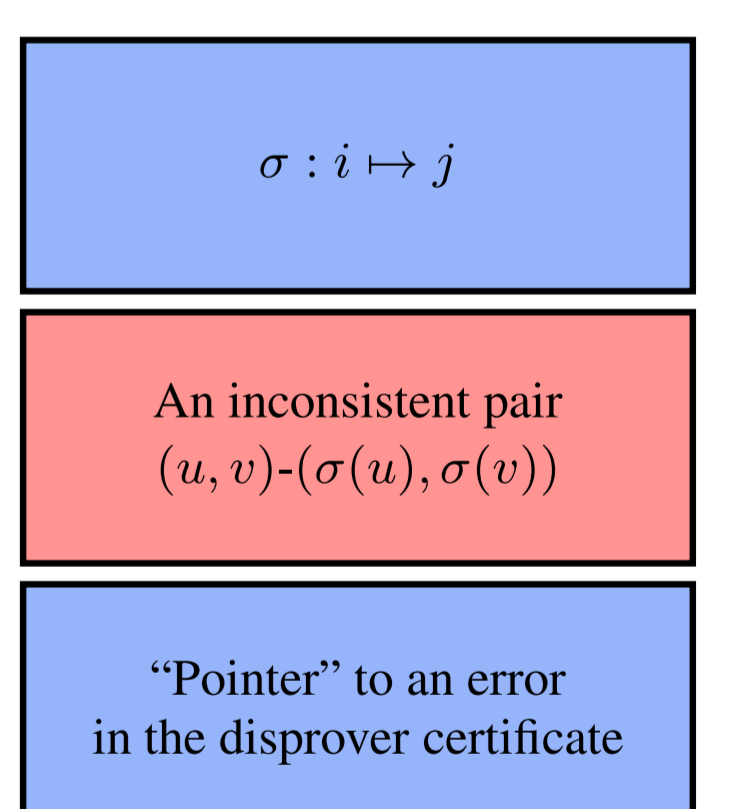
EXAMPLE: OPTIMAL SOLUTIONS

For many combinatorial problems, the set of optimal solutions is in Π_2^L . The protocol is on the right, with the disprover in red, and prover in blue.



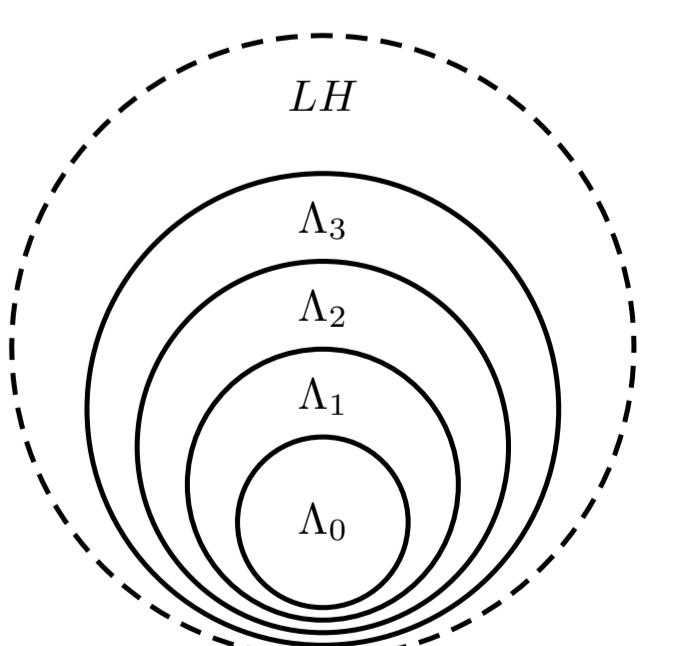
EXAMPLE: NON TRIVIAL AUTOMORPHISM

Language: the graphs that have a non-trivial automorphism. This language has a protocol in Σ_3^L , described on the right.



STRUCTURAL RESULTS

- Collapses: $\Sigma_{2i} = \Sigma_{2i-1}$ and $\Pi_{2i+1} = \Pi_{2i}$. We rename the classes as Λ_i .
- There are interesting co-classes.
- The levels 0, 1 and 2 are separated.
- There are languages outside the hierarchy.



OPEN PROBLEM

Are level 2 and 3 separated?

IF IT RINGS A BELL



Reiter proved a connexion between a similar hierarchy and MSO logic. The same hierarchy but with no labels in the certificate has a poster at **WoLA!**