

# Automata with Parameterized Arrays and Parameterized Networks of Automata

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LIAFA

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  - for each  $a \in A$ ,  $s(a) = (D^a, (K_1^a, \dots, K_{n^a}^a))$  where  $D \in \mathcal{D}$  and  $\forall_{n^a i} : K_i^a = b_i^a \in \mathbb{N}^+ \cup P$  or  $K_i^a = (r_i^a, h_i^a) \in \mathbb{N}^+ \times (\mathbb{N}^+ \cup P)$

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 $\langle \text{guard on } P, A, \{x, \dots\} \rangle \rightarrow \langle \text{assignment on } P, A, \{x, \dots\} \rangle$

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 $t_p ::= \varepsilon \mid x \mid t_P.t_P \mid t_I$  and  $af_P ::= t_P \leq t_P \mid |t_P| \leq t_I \mid |t_P| \leq |t_P|$

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  - $C_0$  **is a finite set of initial configurations**  $(q, \iota)$

❖ the associated **modelling language constructs**:

- `type ::= tree [r,h] of type-id`
- `forall(b) : | exists(b) : | forall(r,h) : | exists(r,h) :`
- `tp ::= eps | x | tp.tp | ti`  
`afp ::= tp<=tp | #(tp)<=ti | #(tp)<=#(tp)`

`root(x) | leaf(r,h,x) | inner(r,h,x) | son(x,y)`



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  - a set of local variables  $L$ , a set of states  $Q$ , and local initial constraints
  - transitions  $(q_1, q_2, \tau)$  with guards and assignments over  $G, id, L, x, \dots$

- ❖ may be relatively easily **mapped** onto an automaton with arrays
- ❖ may be **extended** by:
  - global parameterized arrays
  - local parameterized arrays (yielding arrays whose structure is a “concatenation” of the process infrastructure and the local arrays)
- ❖ some **limitations/open problems**:
  - parameterized dimensions/arities
  - general graph architectures
  - dynamic instantiation