

Unification

Two terms  $s$  and  $t$  are **unifiable** iff there exists a substitution (called **unifier**) s.t.  $\theta(s) = \theta(t)$ .

## Example

- $f(x, g(x, a))$  and  $f(h(a), y)$  are unifiable with  $\theta = \{x/h(a), y/g(h(a), a)\}$

$$\begin{aligned} f(x, g(x, a)) &\doteq f(h(a), y) \\ f(h(a), g(h(a), a)) &= f(h(a), g(h(a), a)) \end{aligned}$$

- $f(x, g(x, a))$  and  $f(h(a), f(b, a))$  are not unifiable.

## Principal substitutions

Let  $\theta$  and  $\tau$  be two substitutions and  $\mathcal{S}$  be a set of substitutions.

- The **composition** of  $\theta$  and  $\tau$  is  $(\theta \circ \tau)(x) = \widehat{\theta}(\tau(x))$  for every variable  $x \in \mathcal{X}$ .
- $\theta$  is an **instance** of  $\tau$  (or  $\tau$  is **more general** than  $\theta$ ) iff there exists a substitution  $\rho$  s.t. for every variable  $x \in \mathcal{X}$ ,  $(\rho \circ \tau)(x) = \theta(x)$ .
- $\tau \in \mathcal{S}$  is **principal** (or **most general**) iff every substitution  $\theta \in \mathcal{S}$  is an instance of  $\tau$ .

### Example

Let  $\sigma_1 = \{y/b, z/h(c)\}$  and  $\sigma_2 = \{x/f(y), y/z\}$ .

$\sigma_1 \circ \sigma_2 = \{x/f(b), y/h(c), z/h(c)\}$ .

$\sigma_2$  is more general than  $\sigma_1 \circ \sigma_2$ .

### Theorem

Let  $S$  be a non-empty set of unifiers of  $s$  and  $t$ . Then, there exists a *principal unifier*  $\theta \in S$  s.t. for every  $\tau \in S$ ,  $\theta$  is more general than  $\tau$ . Moreover, this principal unifier is *unique* modulo renaming.

## Idempotent unifiers

A substitution  $\theta$  is **idempotent** iff  $\theta \circ \theta = \theta$ .

### Example

$\{y/b, z/h(c)\}$  is idempotent.

$\{x/f(y), y/z\}$  is not idempotent.

### Theorem

If  $s$  and  $t$  are unifiable, then there exists a **principal unifier** of  $s$  and  $t$  which is **idempotent**.

How we can construct this unifier?

## Equational systems

An ( $\Sigma$ )**equational system** is a set of ( $\Sigma$ )equations of the form  $s \doteq t$ .

An equational system  $E$  is **unifiable** iff there exists a unifier (called **solution**) for all the equations of  $E$ .

**Finite** equational systems are denoted  $\{s_1 \doteq t_1, \dots, s_n \doteq t_n\}$ .

## Solved forms

The equational system  $E = \{s_1 \doteq t_1, \dots, s_n \doteq t_n\}$  is in **solved form** iff

- All the  $s_i$  are **distinct variables**.
- No  $s_i$  appears in  $t_j$ .

### Example

$E_0 = \{x \doteq y, z \doteq f(a)\}$  is in solved form but  $E_1 = \{x \doteq y, x \doteq f(a)\}$ ,

$E_2 = \{x \doteq y, y \doteq f(a)\}$ ,

$E_3 = \{x \doteq z, y \doteq f(y)\}$  do not.

**Notation :** For the solved system  $E = \{x_1 \doteq t_1, \dots, x_n \doteq t_n\}$  we note  $\vec{E}$  the substitution  $\{x_1/t_1, \dots, x_n/t_n\}$ .

# The transformation rules

$$\frac{E \cup \{s \doteq s\}}{E} \quad (\text{erase}) \quad \frac{E \cup \{t \doteq x\} \quad t \notin \mathcal{X}}{E \cup \{x \doteq t\}} \quad (\text{orient})$$

$$\frac{E \cup \{f(s_1, \dots, s_n) \doteq f(t_1, \dots, t_n)\}}{E \cup \{s_1 \doteq t_1, \dots, s_n \doteq t_n\}} \quad (\text{decompose})$$

$$\frac{E \cup \{x \doteq s\} \quad x \in \text{Var}(E) \quad x \notin \text{Var}(s)}{E\{x \setminus s\} \cup \{x \doteq s\}} \quad (\text{substitute})$$



# The unification algorithm

- 1 Take an equational system  $E$
- 2 Compute a new system  $P$  by applying the **transformation rules** as far as possible.
- 3 If the system  $P$  is in **solved form**
  - then send the answer  $\vec{P}$
  - else fail

## Example

Unification of the system  $\{p(a, x, f(g(y))) \doteq p(z, f(z), f(u))\}$

$$\frac{\frac{\frac{p(a, x, f(g(y))) \doteq p(z, f(z), f(u))}{a \doteq z, x \doteq f(z), f(g(y)) \doteq f(u)}{z \doteq a, x \doteq f(z), f(g(y)) \doteq f(u)}{z \doteq a, x \doteq f(a), f(g(y)) \doteq f(u)}{z \doteq a, x \doteq f(a), g(y) \doteq u}}{z \doteq a, x \doteq f(a), u \doteq g(y)(solved\ form)}$$

yields the (idempotent) substitution  $\{z/a, x/f(a), u/g(y)\}$ .

## Soundness and completeness of the algorithm

### Theorem

*The algorithm terminates.*

### Theorem

**(Soundness)** *If the algorithm finds a substitution  $\vec{S}$  for the problem  $P$ , then  $P$  is unifiable and  $\vec{S}$  is a m.g.u. of  $P$ .*

*That is,*

*If  $P$  is not unifiable, then the algorithm fails.*

### Theorem

**(Completeness)** *If the system  $P$  is unifiable, then the algorithm computes the m.g.u. of  $P$ .*

*That is,*

*If the algorithm fails, then the system  $P$  is not unifiable.*