Ackermann and Primitive-Recursive Bounds with Dickson's Lemma

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Outline

well quasi orderings generic tools for termination arguments this talk beyond termination: complexity upper bounds contents

Dickson's Lemma Length of Bad Sequences Subrecursive Hierarchies Applications Dickson's Lemma Definition (wqo)

A wqo is a quasi-order (S, \leq) s.t.

$$\forall \mathbf{x} = \mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, \dots \in S^{\omega}, \exists i_1 < i_2, \mathbf{x}_{i_1} \leqslant \mathbf{x}_{i_2}.$$

Lemma (Dickson's Lemma) If (A, \leq_A) and (B, \leq_B) are two wqo's, then $(A \times B, \leq_{\times})$ is a wqo, where \leq_{\times} is the product ordering:

 $\langle \mathfrak{a}, \mathfrak{b} \rangle \leqslant_{\times} \langle \mathfrak{a}', \mathfrak{b}' \rangle \stackrel{\text{\tiny def}}{\Leftrightarrow} \mathfrak{a} \leqslant_A \mathfrak{a}' \wedge \mathfrak{b} \leqslant_B \mathfrak{b}' \,.$

Dickson's Lemma

Definition (wqo)

A wqo is a quasi-order (S, \leq) s.t.

$$\forall \mathbf{x} = \mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, \dots \in S^{\omega}, \exists i_1 < i_2, \mathbf{x}_{i_1} \leqslant \mathbf{x}_{i_2}.$$

Lemma (Dickson's Lemma) In this talk: (\mathbb{N}^k, \leq) is a wqo.

Applications of Dickson's Lemma

Termination and decision of problems on

- well-structured transition systems (Finkel and Schnoebelen, 2001),
- Datalog with constraints (Revesz, 1993),
- ► Gröbner's bases (Gallo and Mishra, 1994),
- relevance logics (Urquhart, 1999),
- ► LTL with Presburger constraints (Demri, 2006),
- data logics (Demri and Lazić, 2009; Figueira and Segoufin, 2009),

▶ ...

An Example

SIMPLE (a, b)
c
$$\leftarrow 1$$

while $a > 0 \land b > 0$
 $\langle a, b, c \rangle \leftarrow \langle a - 1, b, 2c \rangle$
or
 $\langle a, b, c \rangle \leftarrow \langle 2c, b - 1, 1 \rangle$
end

- in any run $\langle a_0, b_0, c_0 \rangle, \dots, \langle a_n, b_n, c_n \rangle$, $\langle a_0, b_0 \rangle \not\leq \langle a_n, b_n \rangle$
- Dickson's Lemma: all the runs are finite
- ► How long can SIMPLE run?

$$\langle 3, 3, 2^{0} \rangle, \langle 2, 3, 2^{1} \rangle, \langle 1, 3, 2^{2} \rangle,$$

 $\langle 2^{3}, 2, 1 \rangle, \dots, \langle 1, 2, 2^{2^{3}-1} \rangle,$
 $\langle 2^{2^{3}}, 1, 1 \rangle, \dots, \langle 1, 1, 2^{2^{2^{3}-1}} \rangle,$
 $\langle 0, 1, 2^{2^{2^{3}}} \rangle$

- > 3 + 2³ + 2^{2³} + 1 steps: non elementary lower bound
- This talk: (matching) upper bound from the use of Dickson's Lemma

Complexity of SIMPLE

$$\langle 3, 3, 2^{0} \rangle, \langle 2, 3, 2^{1} \rangle, \langle 1, 3, 2^{2} \rangle,$$

 $\langle 2^{3}, 2, 1 \rangle, \dots, \langle 1, 2, 2^{2^{3}-1} \rangle,$
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Bad Sequences

- $\mathbf{x} = x_0, x_1, \dots$ in S^{∞} is a good sequence if $\exists i_1 < i_2, x_{i_1} \leqslant x_{i_2}$,
- ► a *bad sequence* otherwise,
- (S, \leq) wqo: every bad sequence is finite

Controlled Sequences

- bound the length of bad sequences
- ▶ but: choose any N, and consider the bad sequence N, N − 1, ..., 0 over N
- similarly: $\langle 3,3 \rangle, \langle 3,2 \rangle, \langle 3,1 \rangle, \langle 3,0 \rangle, \langle 2,N \rangle, \langle 2,N-1 \rangle, \dots$

Controlled Sequences

- bound the length of *controlled* bad sequences
- fix a control function $f : \mathbb{N} \to \mathbb{N}$
- $\mathbf{x} = x_0, x_1, \dots$ over \mathbb{N}^k is (f, t)-controlled if

$$\forall i = 0, 1, \dots, \forall 1 \leqslant j \leqslant k, x_i[j] < f(i+t)$$

 for fixed k, f, t, there are *finitely* many (f, t)-controlled sequences over N^k: maximal length

$$L_{k,f}(t)$$

Example
$$k = 2, t = 3, f(x) = x + 1$$

Example (SIMPLE)

 $k = 2, t = 2 = \lceil log_2(max(a, b)) \rceil, f(x) = 2^x + 1$

Technical Overview

- 1. obtain inequalities for $L_{k,f}$ in terms of "simpler" wqo's
- 2. define a bounding function M with $L_{k,f}(t) \leqslant M_{k,f}(t)$
- 3. rank $M_{k,f}$ in a hierarchy of function classes $(\mathscr{F}_k)_k$

Easy Cases

$$\begin{split} L_{0,f}(t) &= 1\\ L_{1,f}(t) &= f(t) \end{split}$$

the latter sequence being

$$f(t) - 1, f(t) - 2, \ldots, 1, 0$$

A More General Problem

- disjoint sums $A_1 \oplus A_2$
- wqo for the sum ordering :

$$egin{aligned} & \mathbf{x} \leqslant \mathbf{x}' \stackrel{ ext{def}}{\Leftrightarrow} ig(\mathbf{x},\mathbf{x}' \in \mathsf{A}_1 \wedge \mathbf{x} \leqslant_1 \mathbf{x}'ig) \ & ee ig(\mathbf{x},\mathbf{x}' \in \mathsf{A}_2 \wedge \mathbf{x} \leqslant_2 \mathbf{x}'ig) \end{aligned}$$

- multiset notation: $\tau = \{k_1, k_2, \dots\}, \mathbb{N}^{\tau} = \bigoplus_i \mathbb{N}^{k_i}$
- shift to $L_{\tau,f}(t)$

A bad sequence $\mathbf{x} = x_0, x_1, \dots, x_l$ over \mathbb{N}^k :

- control: $x_0 \leq \langle f(t) 1, \dots, f(t) 1 \rangle$
- ▶ badness: $\forall i > 0$, $\exists j \leqslant k$, $x_i[j] < x_0[j] \leqslant f(t) 1$
- each x_i belongs to at least one *region* R_{j,s}
 depending on its value s = x_i[j] at coordinate j
- $\blacktriangleright R_{j,s} = \{ x \in \mathbb{N}^k \mid x[j] = s \}$
- there are $N_{k,f}(t) \stackrel{\text{\tiny def}}{=} k \cdot (f(t) 1)$ regions in total

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$$R_{j,s} = \{x \in \mathbb{N}^k \mid x[j] = s\}$$

• there are $N_{k,f}(t) \stackrel{\text{\tiny def}}{=} k \cdot (f(t) - 1)$ regions in total

Example

$$\mathbf{x} = \langle 2, 2 \rangle, \langle 1, 5 \rangle, \langle 4, 0 \rangle, \langle 1, 1 \rangle, \langle 0, 100 \rangle, \langle 0, 99 \rangle, \langle 3, 0 \rangle$$

$$\langle 2, 2 \rangle, \begin{bmatrix} \langle 0, 100 \rangle, \langle 0, 99 \rangle, & (R_{1,0} : x[1] = 0) \\ \langle 1, 5 \rangle, & \langle 1, 1 \rangle, & (R_{1,1} : x[1] = 1) \\ \langle 4, 0 \rangle, & \langle 3, 0 \rangle & (R_{2,0} : x[2] = 0) \\ & (R_{2,1} : x[2] = 1) \end{bmatrix}$$

References

Inequality for \mathbb{N}^k

Example

$$\mathbf{x} = \langle 2, 2 \rangle, \langle 1, 5 \rangle, \langle 4, 0 \rangle, \langle 1, 1 \rangle, \langle 0, 100 \rangle, \langle 0, 99 \rangle, \langle 3, 0 \rangle$$

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Inequality for \mathbb{N}^k Example

$$\mathbf{x} = \langle 2,2\rangle, \, \langle 1,5\rangle, \, \langle 4,0\rangle, \, \langle 1,1\rangle, \, \langle 0,100\rangle, \, \langle 0,99\rangle, \, \langle 3,0\rangle$$

$$\langle 2, 2 \rangle, \begin{bmatrix} \langle *, 5 \rangle, & \langle *, 1 \rangle, & (R_{1,0} : x[1] = 0) \\ \langle 4, * \rangle, & (R_{1,1} : x[1] = 1) \\ \langle 4, * \rangle, & \langle 3, * \rangle & (R_{2,0} : x[2] = 0) \\ (R_{2,1} : x[2] = 1) \end{bmatrix}$$

Suffix: a *bad* sequence over

 $\mathbb{N} \oplus \mathbb{N} \oplus \mathbb{N} \oplus \mathbb{N} = \mathbb{N}^{4 \times \{1\}} = \mathbb{N}^{N_{k,f}(t) \times \{k-1\}}$

Example

 $\mathbf{x}=\langle 2,2\rangle,\,\langle 1,5\rangle,\,\langle 4,0\rangle,\,\langle 1,1\rangle,\,\langle 0,100\rangle,\,\langle 0,99\rangle,\,\langle 3,0\rangle$

$$\langle 2, 2 \rangle, \begin{bmatrix} \langle 100 \rangle, \langle 99 \rangle, & (\mathsf{R}_{1,0} : \mathsf{x}[1] = 0) \\ \langle 5 \rangle, & \langle 1 \rangle, & (\mathsf{R}_{1,1} : \mathsf{x}[1] = 1) \\ \langle 4 \rangle, & \langle 3 \rangle & (\mathsf{R}_{2,0} : \mathsf{x}[2] = 0) \\ & (\mathsf{R}_{2,1} : \mathsf{x}[2] = 1) \end{bmatrix}$$

Suffix: an (f, t + 1)-controlled bad sequence:

$$L_{\{k\},f}(t)\leqslant 1+L_{N_{k,f}(t)\times\{k-1\},f}(t+1)$$

Inequality for $\bigoplus_i \mathbb{N}^{k_i}$

Example $\tau = \{1, 2, 2\}$:

 $\begin{bmatrix} \langle 5 \rangle, & \langle 3 \rangle \\ \langle 2, 2 \rangle, & \langle 1, 5 \rangle, \langle 4, 0 \rangle, & \langle 1, 1 \rangle, \\ & \langle 12, 1 \rangle, & \langle 3, 5 \rangle \end{bmatrix}$

| ⟨2,2⟩ | $\lceil \langle 5 \rangle, \langle 3 \rangle$ $\langle *, 5 \rangle, \langle 4, * \rangle, \langle 4, * \rangle, \langle 4, * \rangle$ | \rangle $\langle *,1 angle,$ | <*,100>,<*,99>, <3,*> |
|-------|---|--------------------------------|--------------------------|
| | | (12,1), (3,5) | > |

Inequality for $\bigoplus_i \mathbb{N}^{k_i}$

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Inequality for $\bigoplus_{i} \mathbb{N}^{k_i}$ Example

A Bounding Function

$$M_{\tau,f}(t) \stackrel{\text{\tiny def}}{=} \max_{k \in \tau} \{1 + M_{\tau_{\langle k,t,f \rangle},f}(t+1)\} \, .$$

Then for all τ and t

$$L_{\tau,f}(t) \leqslant M_{\tau,f}(t)$$

find the *functional complexity* of M

Fast Growing Hierarchy: $(F_{\alpha})_{\alpha}$

(Löb and Wainer, 1970)

Hierarchy of functions $(F_{\alpha})_{\alpha}$ indexed by ordinals; we only need the *finite* fragment.

$$\begin{split} \mathsf{F}_0(x) &\stackrel{\text{\tiny def}}{=} x+1\\ \mathsf{F}_{n+1}(x) &\stackrel{\text{\tiny def}}{=} \mathsf{F}_n^{x+1}(x) \end{split}$$

 $\begin{aligned} F_1(x) &= 2x + 1\\ F_2(x) &= (x + 1) \cdot 2^{x+1} - 1\\ F_3 \text{ is non elementary}\\ F_{\omega} \stackrel{\text{def}}{=} \lambda x. F_x(x) \text{ is non primitive-recursive} \end{aligned}$

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Fast Growing Hierarchy: $(\mathscr{F}_{\alpha})_{\alpha}$

(Löb and Wainer, 1970)

Elementary-recursive closure of the $(F_{\alpha})_{\alpha}$



Maximizing Strategy

Lemma For all $\tau \neq \emptyset$, $t \ge 0$, $M_{\tau,f}(t) = 1 + M_{\tau_{\langle \min \tau, t, f \rangle}, f}(t+1)$. Example t = 1, f(x + t) = x + t, $\tau = \{2, 1\}$: compare $\langle 0, 0 \rangle, \langle 1 \rangle, \langle 0 \rangle$ $\langle 0 \rangle, \langle 1, 1 \rangle, \langle 1, 0 \rangle, \langle 0, 3 \rangle, \langle 0, 2 \rangle, \langle 0, 1 \rangle, \langle 0, 0 \rangle$

A Variant of $(F_k)_k$

$$\begin{split} G_{1,f}(x) &\stackrel{\text{\tiny def}}{=} f(x) + x\\ G_{k+1,f}(x) &\stackrel{\text{\tiny def}}{=} G_{k,f}^{N_{k+1,f}(x)}(x+1) \end{split}$$

Lemma

For all $k \geqslant 1, r \geqslant 1, x \geqslant 0,$ $M_{r \times \{k\}, f}(x) = G_{k, f}^r(x) - x$

Lemma

Let $\gamma \ge 1$ and f be unary monotone in \mathscr{F}_{γ} with $f(x) \ge \max(1, x)$ for all x. Then for all $k \ge 1$, $G_{k,f}$ belongs to $\mathscr{F}_{\gamma+k-1}$.

Complexity Results

Proposition (Upper Bound)

Let k, r \geq 1 be natural numbers and $\gamma \geq$ 1. If f is a monotone unary function of \mathscr{F}_{γ} with $f(x) \geq \max(1, x)$ for all x, then $M_{r \times \{k\}, f}$ is in $\mathscr{F}_{\gamma+k-1}$.

Proposition (Lower Bound)

Let k, r \geq 1 be natural numbers and $\gamma \geq$ 0 with $\gamma + k \geq$ 3. Then $L_{r \times \{k\}, F_{\gamma}}$ is bounded below by a function which is **not** in $\mathscr{F}_{\gamma+k-2}$.

References

Applications of our Bounds

Termination and decision of problems on

- well-structured transition systems (Finkel and Schnoebelen, 2001),
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Program Termination Proofs (Podelski and Rybalchenko, 2004)

Monolithic Termination Argument

- prove that the program's transition relation R is well-founded
- ▶ ranking function ρ from program configurations x = x₀, x₁,... into a wqo s.t. R ⊆ {(x_i, x_j) | ρ(x_i) ≰ ρ(x_j)}
- for simple: $\rho(a, b, c) = \omega^b + a$

Program Termination Proofs (Podelski and Rybalchenko, 2004)

Disjunctive Termination Argument

- find well-founded relations T₁,..., T_k on program configurations
- prove $R^+ \subseteq T_1 \cup \cdots \cup T_k$
- ► for simple:

$$\begin{split} T_1 &= \{ (\langle a, b, c \rangle, \langle a', b', c' \rangle) \mid a > 0 \land a' < a \} \\ T_2 &= \{ (\langle a, b, c \rangle, \langle a', b', c' \rangle) \mid b > 0 \land b' < b \} \end{split}$$

► at the heart of the TERMINATOR tool

Termination by Dickson's Lemma

- each T_j shown well-founded thanks to a ranking function ρ_j into a wqo (S_j, ≤_j)
- map any sequence of program configurations

$$\mathbf{x} = \mathbf{x}_0, \mathbf{x}_1, \dots$$

to a sequence of tuples $\mathbf{y} = \langle \rho_1(x_0), \dots, \rho_k(x_0) \rangle, \langle \rho_1(x_1), \dots, \rho_k(x_1) \rangle, \dots$ in $S_1 \times \dots \times S_k$ \mathbf{y} is bad: if $i_1 < i_2$, there exists j s.t. $(x_{i_1}, x_{i_2}) \in \mathbf{R}^+ \cap \mathbf{T}_j$ but

 $\rho_j(x_{i_1}) \nleq \rho_j(x_{i_2})$

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to a sequence of tuples

 $\boldsymbol{y} = \langle \rho_1(\boldsymbol{x}_0), \dots, \rho_k(\boldsymbol{x}_0) \rangle, \langle \rho_1(\boldsymbol{x}_1), \dots, \rho_k(\boldsymbol{x}_1) \rangle, \dots$

- in $S_1\times \cdots \times S_k$
- **y** is *bad*: if $i_1 < i_2$, there exists j s.t.

$$(x_{i_1}, x_{i_2}) \in \mathsf{R}^+ \cap \mathsf{T}_j$$

but

$$\rho_j(x_{i_1}) \nleq \rho_j(x_{i_2})$$

Bounds on Program Complexity

Make some assumptions:

- complexity bound g on atomic program operations
 - for instance polynomial
- complexity bound ρ on ranking functions into $\mathbb N$
 - for instance polynomial
- **y** controlled by $g^i \circ \rho$ in some \mathscr{F}_{γ}
 - in this case an exponential function in \mathscr{F}_2
- time complexity in $\mathscr{F}_{\gamma+k-1}$
 - in this case \mathscr{F}_{k+1}
- matches the lower bound (expand SIMPLE to dimension k instead of 2)

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Concluding Remarks

- practical applications of wqo's yield upper bounds!
- out-of-the-box upper bounds
- "essentially" matching lower bounds for decision problems on monotone counter systems (lossy counter systems, reset or transfer Petri nets)
- ▶ the future: Higman's Lemma

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References: Upper Bounds for WQO

Dickson's Lemma

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Lower Bound

Specific sequence, bad for $(\mathbb{N}^k, \leq_{lex})$, of length $\ell_{k,f}(t)$. Example

k = 2, t = 1, f(x) = x + 3:

$$\begin{array}{rl} 5 = & 1+4 & = 1+\ell_{1,f}(1) \\ 13 = & 5+8 & = 5+\ell_{1,f}(5) \\ 29 = & 16+13 = & 13+\ell_{1,f}(13) \end{array}$$

Lower Bound Specific sequence, bad for $(\mathbb{N}^k, \leq_{lex})$, of length $\ell_{k,f}(t)$. In general, on the k + 1th coordinate:

 $\underbrace{ \substack{f(t) - 1 \ f(t) - 1 \ \cdots \ f(t) - 1 \\ \ell_{k,f}(t) \ times}}_{\ell_{k,f}(t) \ times} \underbrace{ \begin{array}{c} f(t) - 2, \ f(t) - 2, \ \cdots , \ f(t) - 2 \\ \ell_{k,f}(o_{k,f}(t)) \ times} \\ \end{array}}_{\ell_{k,f}\left(o_{k,f}^{f(t) - 1}(t)\right) \ times}$

$$\begin{split} & o_{k,f}(t) \stackrel{\text{\tiny def}}{=} t + \ell_{k,f}(t) \\ & \ell_{k+1,f}(t) = \sum_{j=1}^{f(t)} \ell_{k,f} \Big(o_{k,f}^{j-1}(t) \Big) \end{split}$$

Lower Bound

Specific sequence, bad for $(\mathbb{N}^k, \leq_{lex})$, of length $\ell_{k,f}(t)$. One can have $\ell_{k,f}(t) < L(\{k\}, t)$: let f(x) = 2x and t = 1,

$$\begin{array}{l} \langle 1,1\rangle, \langle 1,0\rangle, \langle 0,5\rangle, \langle 0,4\rangle, \langle 0,3\rangle, \langle 0,2\rangle, \langle 0,1\rangle, \langle 0,0\rangle \\ \langle 1,1\rangle, \langle 0,3\rangle, \langle 0,2\rangle, \langle 0,1\rangle, \langle 9,0\rangle, \langle 8,0\rangle, \langle 7,0\rangle, \langle 6,0\rangle, \langle 5,0\rangle, \dots, \langle 0,0\rangle \end{array}$$

$$\ell_{2,f}(1) = 8$$
 $L_{\{2\},f}(1) \ge 14$

Well-structured transition systems

transition systems (Q, →, q₀) with a wqo ≤ on Q compatible with transitions:

 $\forall p, q, p' \in Q, (p \xrightarrow{a} q \land p \leqslant p') \Rightarrow \exists q', (q \leqslant q' \land p' \xrightarrow{a} q')$

- a generic framework for decidability results: safety, termination, EF model checking, ...
- many classes of concrete systems are WSTS:
 - over (ℕ^k, ≤): vector addition systems, resets/transfer Petri nets, increasing counter systems,
 - over (Σ^*, \sqsubseteq) : lossy channel systems, ...
 - beyond: data nets, ...

Example: (Non) Termination

- given (Q, \rightarrow, q_0) , decide whether there exists an infinite run $q_0 \rightarrow q_1 \rightarrow \cdots$
- holds iff there exists $q_i \leqslant q_j$ with $q_0 \rightarrow^* q_i \rightarrow^+ q_j$
- thanks to wqo, termination is both r.e. and co-r.e.
- what is the complexity?

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Affine Counter Systems

- $\mathcal{C} = \langle Q, k, \delta, m_0 \rangle$
- ► transitions (q, g, q') where g(x) = Ax + B an affine function, $A \in \mathbb{N}^{k \times k}$, $B \in \mathbb{Z}^k$
- $\mathfrak{m}_0 \in \mathbb{N}^k$
- generalize reset/transfer Petri nets, broadcast protocols,...

Termination for ACS

Given $\langle \mathfrak{C} \rangle$ a k-ACS, does every run of \mathfrak{C} terminate?

- exponential control in \mathscr{F}_2
- $t < |\mathfrak{m}_0| < |\mathfrak{C}|$
- upper bound: \mathscr{F}_{k+1}
- ► lower bound: $\mathscr{F}_{k-O(1)}$ (Schnoebelen, 2010)
- if k is not fixed, non-primitive recursive, with an upper bound in *F*_ω